Product Catalog



SOFTWARE

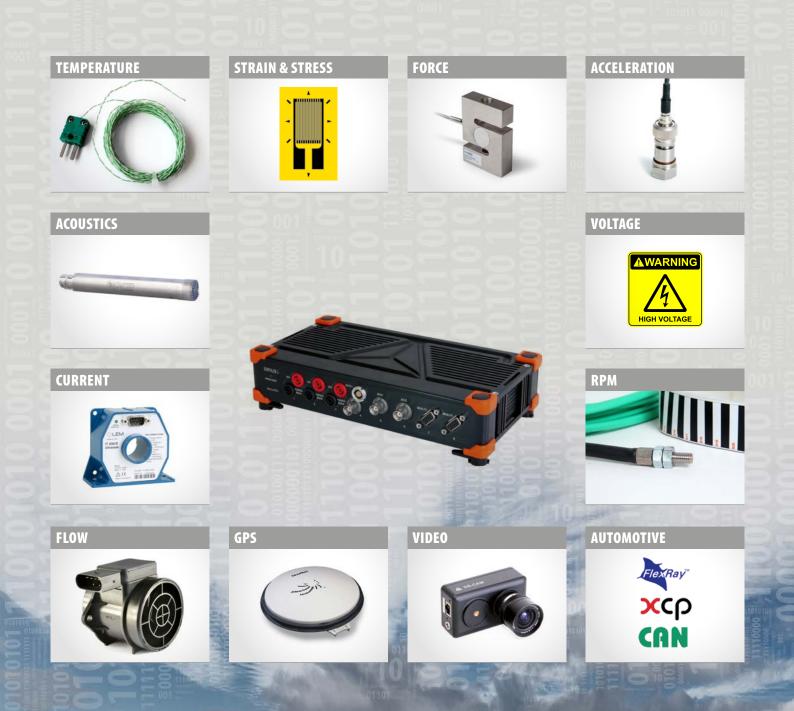
APPLICATIONS





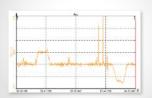






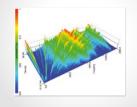
THE MISSION of the company is to provide the best possible test and measurement solution by working close together with our customers. THE SOLUTION consisting of a robust mechanical housing filled with great electronics provides the strong base for different applications.





SCOPE

ORDERTRACKING



POWER



BUS SYSTEMS

| The | 100 | 94_3 | | |
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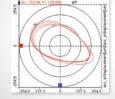




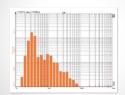


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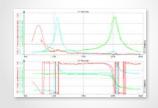
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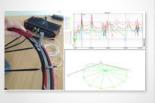
ACOUSTICS



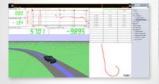
TORSIONAL VIBRATION



MODAL TEST



POLYGON





DEWESoft[®] handles complete instrument design, development and manufacturing ... ALL IN ONE HAND.



DEWESoft[®] was founded back in year 2000 and today DEWESoft[®] products are being used in many applications by global market leaders all around the world. DEWESoft[®] positioned itself in the global market with innovations in software and hardware products. We gained trust with our customers by keeping a close contact and tight support on all levels from sales down to technical support. The DEWESoft[®] hardware is the perfect match to the well established DEWESoft[®] software and offers the next generation in distributed data acquisition. The modular hardware concept with many new technologies like dual core ADC and digital high end isolation shows the clear next DAQ generation.



THE PROFESSIONAL TEAMS for software, electronics, hardware, machinery center, create the world-best instruments.



What sets DEWESoft® apart from most other DAQ-companies?

It is the complete development and manufacturing of the mechanics (enclosure), electronics (hardware), software, instruments know-how and customized solutions. This guarantees complete independence of suppliers.

The standard products are available with shortest delivery times. Special customized solution can be designed and manufactured on demand.

The high end test center form EMI, ISO - calibration and also for all environmental tests like temperature from -40 to 140° C, vibration and shock test are done in house !



Index

DEWESoft®

INSTRUMENTS

2

DEWESoft® measurement innovation



8

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| Company & Teams | 4 |
| DEWESoft [®] distributors | Back cover |

Handheld instruments from few channels up to high-end test systems with more than 1000 channels are available.

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Easy to use data acquisition and analysis software, even for sophisticated applications.

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Instrument generation

9

DAQ Instruments

R8/R8B



R2D/R2DB



MINITAURs



Compact portable all-in-one instrument with built-in display and hot-swappable batteries (R8DB)

R8D/R8DB

4 versions available:

- ▶ *R8 with integrated SBOXre computer*
- ► R8B R8 with hot-swappable 384 Wh batteries
- R8D with SBOXre computer and built-in display
- R8DB R8D with hot-swappable 384 Wh batteries
- ► Multi-touch 17" display

Compact portable instrument with integrated SBOXre computer

Configurable standalone rack with

- ► 1 to 8 easily exchangeable SIRIUS® slices, up to 64 (max. 128 channels
 - with up to 64 counter inputs
- ▶ up to 8 CAN ports
 ▶ EtherCAT[®] interface
- ► Built-in GPS (option)

Highest data throughput:

- ► 128 channels @ 200 kS/s, 24 bit (up to 64 ch @ 1 MS/s, 16 bit)
- Rack-mount option available

Mobile all-in-one instrument with integrated SBOXse computer, display and hot-swappable batteries

2 versions available:

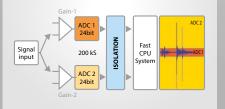
- R2D with built in display
- R2DB with built in display and hot-swappable batteries
- ► 1 to 2 easy exchangeable SIRIUS[®] modules up to 16 (max. 32) channels with up to 16 counter inputs
- Multi-touch high brightness 12" display
- ► 2 CAN ports
- ► EtherCAT[®] interface
- ▶ Built-in GPS (option)
- ▶ 192 Wh battery capacity

Compact instrument with integrated computer

- ► 8 universal sensor inputs (Strain, Voltage, Current, DSI® adapters)
- ▶ 8 Counter inputs
- ▶ 1 CAN port
- ► Integrated powerful PC Intel Core i3, 1.7 GHz 4 GB RAM (up to 16 GB) 250 GB/1 TB removable SSD 4x USB 3.0, 2x USB 2.0 DVI-D display interface 2x Ethernet LAN + WLAN EtherCAT[®]
- Built-in GPS (option)

HIGH DYNAMIC

This new technology solves the often faced problem that the signal is higher than expected and therefore clipped. DEWESoft[®] DUALCOREADC[®]technology always gives you the full possible measuring range, because the signal is measured with a high and a low gain at the same time!



CUSTOMIZABLE FRONT-END

Select your amplifier configuration! Example:

- ▶ 3 x High-Voltage inputs 1200 V
- ▶ 1 x IEPE/Voltage + Encoder/Tacho
- ▶ 2 x IEPE/Voltage
- 2 x MULTI (Strain gauge/Voltage, sensor excitation, Tacho, Analogue out)



IEPE SENSOR CHECK

The LED ring around the connector will light green/red to indicate if the sensor impedance is ok.



NARE

APPLICATIONS

SOFTWARE

SIRIUS® + SBOXe



SIRIUS®



Standalone instrument with SBOXe computer

4 versions available:

- ► Standard version SBOXe
- ► Fanless version SBOXfe
- Rack mount version SBOXre
- ► Waterresistant SBOXwe
- ► High performance industrial PC
- ▶ Core i7 CPU
- ⊾ 4 GB RAM
- ▶ 250 GB/1 TB removable SSD
- ► 4 x USB 3.0 ports, 2 x USB 2.0, EtherCAT®, 2xGLAN, WLAN, SYNC, DVI, GPS display / remote
- ▶ Built-in GPS (option)
- ▶ Built-in mSATA SSD (option)

Isolated 8 channel analyser

- Customisable 8 (16) analogue input channels
- ▶ Up to 1 MS/s
- ▶ Up to 8 Encoder/Tacho inputs
- ▶ USB interface
- ▶ 1 CAN port
- ▶ 8 analogue outputs (option)

Mobile 4 channel analyser

SIRIUS*m*

- ► 4 channel IEPE/Voltage
- ▶ 1 Encoder/Tacho input
- ▶ USB interface
- ▶ USB powered
- ► 1x Sync

DEWE-43

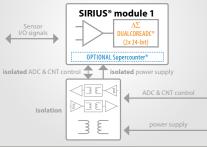


Very compact, award winning USB DAQ system

- ► 8 analogue channels (200 kHz/channel)
- 8 counter inputs or 24 digital inputs
- ▶ 3 digital outputs
- ▶ 2 CAN ports

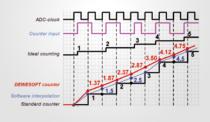
FULLY ISOLATED

The "worry-free" solution provides isolation on the sensor side (channel-to-GND, as well as channel-to-channel) and even isolated sensor excitation! Less noise, no ground loops, best signal quality!



Supercounter®

To achieve highest accuracy, DEWESoft® uses a special technique to determine the count and exact time of the input edge on a 102 MHz timebase. This allows the usage even for most demanding applications such as torsional vibration.



ANALOGUE OUT

Optional analogue output for control channels, shaker control, replay, or standalone digital signal conditioning



8 BNC connectors on rear side for analogue output.

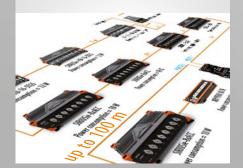
Extreme Line DAQ Instruments IP67 KRYPTONi LV KRYPTON STG KRYPTONi TH KRYPTON RTD Any thermocouple Low voltage **Distributed strain** PTx temperature, resistance and measurement measurement measurement Voltage measurement ▶ 8 or 16 isolated thermocouple ▶ 4 or 8 isolated analogue inputs ▶ 3 or 6 differential voltage or 8 differential universal PTx inputs strain inputs temperature, resistance and voltage ▶ ±100 V input range ▶ TC types: K, J, T, R, S, N, 24-bit sigma delta 24-bit sigma delta E, C, U, B ▶ Up to 20 kHz sampling rate 1-15 V programmable excitation ▶ Up to 100 Hz sampling rate ▶ Up to 100 Hz sampling rate ▶ 1000 V isolation channel/ground & channel/channel ▶ Up to 20 kHz sampling rate ▶ 1000 V isolation channel/ground \sim < 0.001 °C resolution & channel/channel

DISTRIBUTED SYSTEMS

▶ 1000 V isolation channel/ground

& channel/channel

Highly distributed systems, with up to 100 m between separate unit.



HIGH RUGGEDNESS

High shock & vibration rating of more than 100 g.



IP 67

Totally sealed product line, which can be submerged in the water.



APPLICATIONS

SIRIUSiwe 6xSTGM, 2xSTGM+



Rugged SIRIUS STGM

- ▶ Up to 200 kHz
- ► 8x analogue STGM inputs with 2x24 Bit vertical resolution up to 200 kHz
- ▶ 2 counter inputs
- ▶ -40°C .. 60°C operating temperature
- ▶ EtherCAT[®] / USB interface





Rugged SIRIUS STGS

- ▶ Up to 200 kHz
- ► 16x analogue STGS inputs with 24 Bit vertical resolution up to 200 kHz
- ▶ -40°C .. 50°C operating temperature
- ▶ EtherCAT[®] / USB interface

SBOXwe



Rugged SBOX computer

- ▶ Intel[®] Core[™] i7-4650U 2x 1.7 GHz
- ▲ 4 GB RAM, 250/500 GB mSATA SSD
- ► EtherCAT[®], 2x Ethernet, 5x USB, WLAN, GPS display / remote, Sync
- ▶ -40°C .. 50°C operating temperature
- ▶ Built-in GPS (option)

HIGH TEMP RANGE

High temperature range of -40 $^\circ C$ to 85 $^\circ C$



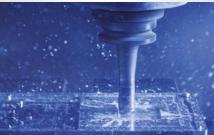
SYNCHRONISATION

Realise unlimited channel counts with the possibility of synchronizing all DEWESoft® products



EVERYTHING FROM A SINGLE SOURCE

All instruments are completely manufactured in-house, starting from the CNC-milled rugged aluminium housings over dedicated front-end electronics hardware, up to the intuitive, but powerful software combining all the features to the solution for your application.



SIRIUS® THE NEXT INSTRUMENT GENERATION



- ▶ Fast data recorder
- High dynamic range up to 160 dB
 20 times better than 24 bit systems
- Isolated input amplifiers for any sensor/signal
- Analogue output for control channels, shaker control, replay, or standalone digital signal conditioning
- ▶ Including DEWESoft[®] X next generation DAQ software
- ► Ether**CAT** → versions to build distributed DAQ systems, up to 100 m between two instruments, only one cable!

Whenever you need an instrument without cooling fan we offer the SIRIUS® fanless version. It fits perfectly for heavy industrial applications with dust, or for sound measurements. You may choose between the slice + note-book version or the slice and the SBOX fanless computer.

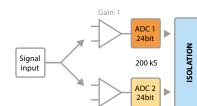
TECHNOLOGY OVERVIEW

Three different technologies are available:

00000

SIRIUS® Dual Core series: High Dynamic (up to 160 dB), 2x24 Bit ADC, 200kS/s

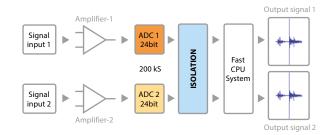
This new technology solves the often faced problem that the signal is higher than expected and therefore clipped. DEWESoft® DUALCOREADC® technology



SIRIUS®-HD-series: High density (16 channel per slice), 1x24 Bit ADC, 200kS/s



For highest channel count this solution offers 24Bit resolution with up to 200 kS/ sec sample rate per channel.



SIRIUS[®]-HS series: High speed and bandwidth, 1x16 Bit ADC, 1 MS/s



This series combines high bandwidth with alias free acquisition with 16 Bit of up to 1 MS/sec acquisition rate. The analogue anti-aliasing filter (100 kHz, 5th order, Bessel) is combined with a free programmable digital IIR filter block inside the FGPA. For bandwidth requirement of up to 500 kHz the complete filter chain is bypassed.

always gives you the full possible

measuring range, because the

signal is measured with a high and

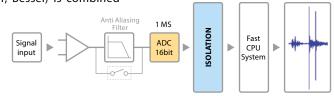
Fast

CPU

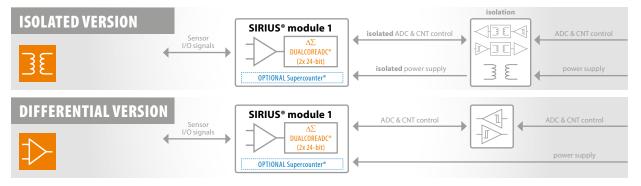
System

ADC 2

a low gain at the same time!



DUALCOREADC[®], high density and high speed SIRIUS[®] slices can be freely combined and synched together. Mixing of technologies inside one slice is not possible.



CUSTOMISED SIRIUS® SOLUTIONS

Choose your amplifier configuration:



In addition to the standard slice solution, the 8 amplifiers per chassis can also be configured freely (customised solution).

GENERAL SPECIFICATIONS

| MISC | |
|-----------------------|--|
| Power Supply | 636V _{DC} |
| Operating Temperature | -10 to 50°C (40°C for fanless series ¹⁾) |
| Storage Temperature | -40 to 85°C |
| Humidity | 5 to 95 % RH non condensing @ 60°C |
| Shock & Vibration | Sweep sinus (EN 60068-2-6:2008); Random (EN 60721-3-2: 1997 - Class 2M2); Shock (EN 60068-2-27:2009) |
| EMC | EN 61326-1, EN 61000-3-2, EN61000-3-3 |

| COUNTER/DIGITAL INPUTS | | | |
|------------------------|---|--|--|
| Modes | Counting, waveform timing, encoder, tacho, geartooth sensor | | |
| Compatibility | TTL/CMOS | | |
| Timebase | 102.4 MHz | | |
| Time base accuracy | Typical: 5 ppm, Max: 20 ppm | | |
| Max. Bandwidth | 10 MHz | | |
| Input Filter | 500 ns, 1μs, 2μs, 4μs, 5μs and 7.5μs | | |

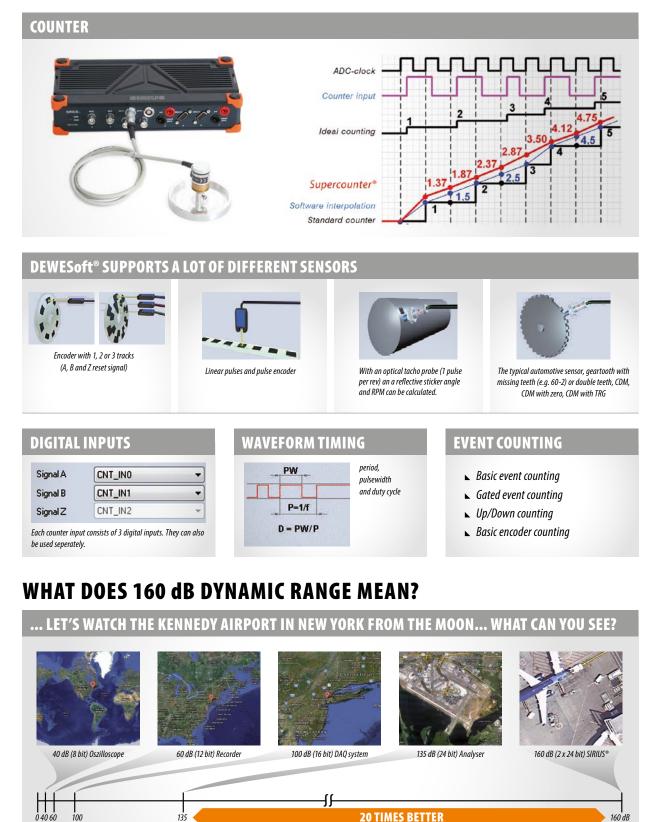
| SYNCHRONISATION | |
|------------------------|--|
| Delay between slices | 50 nsec |
| Max. Sync-cable length | 100 m (Master/Slave), 200 m (IRIG), 75 m EtherCAT® |

INSTRUMENTS

100

135

Counters are mainly used for measuring RPM and angle of rotating machines. DEWESoft® Supercounters® work on a 102.4 MHz internal time base, ALWAYS, independent of the current sample rate. In comparison to standard counters, which only output whole numbers like 1,1,2,2,3,4, ... one sample later, DEWESoft® is able to extract the accurate values like 1.37, 1.87, 2.37, ... fully time- and amplitude-synchronized! This is done by measuring the exact time of the rising edge of the signal with an additional counter.



20 TIMES BETTER Even in the biggest range you can see every detail! SOFTWARE

160 dB

OPTION: ANALOGUE OUT - 4 FUNCTIONS



8 BNC connectors on rear side for analogue output

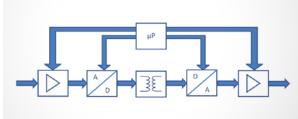
Applications

- Standalone Digital Signal Amplifier
- ▶ Control channel
- ⊾ Replay
- ► Function generator (Modal/shaker control)

Available for standard slices with 200 kS/s or HS-slice with 1 MS/s

This option is available on USB versions only!

FUNCTION 1: STANDALONE DIGITAL SIGNAL CONDITIONING



Principle of internal architecture

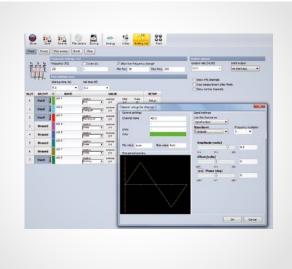
With the AO8 option the DEWESoft[®] instrument can be used as a pure, standalone signal conditioner. No DEWESoft[®] software is needed, no USB cable connected. Any physical input signal is converted to an output voltage of max. ± 10 V.

- ▶ Any analogue input
- ⊾ Signal conditioning
 ⊾ Scaling

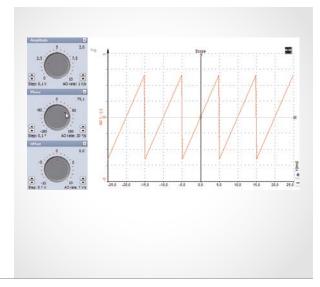
⊾ Offset ⊾ Gain

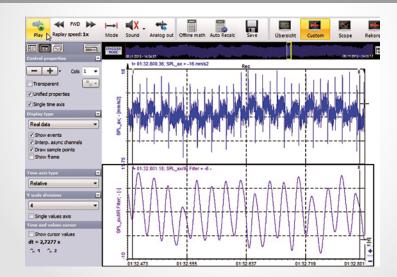
- Redundant DAQ system
 Simple mathematic functions
- Standalone operation possible
- FUNCTION 2: FUNCTION GENERATOR (MODAL/SHAKER CONTROL)

No need for additional analogue out hardware any more! The Function generator is able to output signals like sine, triangle, rectangle, saw or even an arbitrary table. This can



be done continuously or in Sweep / step sweep / burst / ... and many more. Fine-tuning can be done LIVE during measurement.

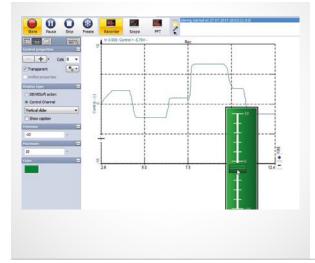




After the measurement is done, replay your data file and output the conditioned channels on the rear side BNC connectors for post-analysis. Use SIRIUS® to feed a test-bed and simulate e.g. the vibrations during a test drive.

FUNCTION 4: CHANNEL OUTPUT

You can output any DEWESoft channel (even math or CAN channels) to the analogue out BNC connectors. Also manual channel control is possible during LIVE measurement:

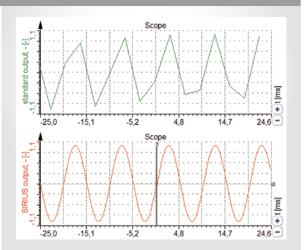


Choose from many different instruments like bar, turn knob, button or text box...



OUTPUT OVERSAMPLING

Similar to the Sigma-Delta converter on the input the analogue output uses a special oversampling technology, which enables correct output of higher frequencies. Although the maximum SIRIUS® sample rate is 200 kHz, the output looks as if it were sampled with 1 MHz!



THE SIRIUS® CHASSIS SOLUTIONS:



- ▶ 8 analogue input channels / slice
- ▶ Stackable with the DEWESoft® click mechanism
- Directly connected to PC or to the powerful SBOX
- ▶ USB and EtherCAT[®] version available

THE SIRIUS® – BOXED SOLUTION



- ▶ ONE BOX solution with or without embedded SBOX PC,
- ▶ Up to 4 slices / system
- ► Internal sync and power supply between the slices, less cables needed
- Smallest high channel count system .. 64 channels 216 * 266 * 139 mm

THE COMPACT DAQ SYSTEM: MINITAURs



Integrated high performance computer

- ▶ 8 universal sensor inputs (Strain, Voltage, Current, DSI[®] adapters)
- Internal Quarter- and Half-bridge completion
- Programmable sensor excitation
- ▲ 8 Supercounters[®]
- ▶ Removable 250 GB/1 TB SSD
- ▶ Expandable with SIRIUS® or EtherCAT® input
- ▶ Built-in GPS (option)



THE MOST PORTABLE: R2D / R2DB



- ▶ For up to 8 easily exchangeable SIRIUS® slices
- ▶ The full data transfer is guaranteed:
 - 8 SIRIUS HD 16 channel slice with 200 kS/s
 8 SIRIUS HS 8 channel slice with 1 MS/s
 - 8 SIRIUS HS 8 Charlier side with 1 MS/S
 - ► Or ANY combination of different slices HS, HD or standard high dynamic
- ▶ Up to 64 analogue outputs (option for R8)

R8D & R8DB:

▶ High brightness 17" FULL HD multi-touch screen

R8B & R8DB:

- ▶ Hot-swappable 384 Wh batteries
- ▲ Up to 2 SIRIUS® amplifier slices can be plugged into the instrument
- ► The full data transfer is guaranteed with the powerful i3 PC
 - ▶ 2 SIRIUS HD 16 channel slice with 200 kS/s
 - ▶ 2 SIRIUS HS 8 Channel slice with 1 MS/s
 - ► Or ANY combination of different slices HS, HD or DUALCOREADC[®]
- ▶ High brightness 12" display
- All connectors are on the front side of the instrument
- Available in 2 versions:
- ▶ R2D with built in display
- ▶ R2DB with built in display
- and hot-swappable 192 Wh batteries

THE 19" PC SOLUTION: R3



- ► Up to 3 SIRIUS*r* amplifiers slices can be plugged into the R3
- ▶ Full size PC with PCI / PCIe cards expandability
- ▶ 19″ rack option
- 2 removable SSDs

SOFTWARE

SIRIUS[®] – Modular solution



Typ. Configuration : 1 slice 8 or 16 analogue channels with standard notebook PC



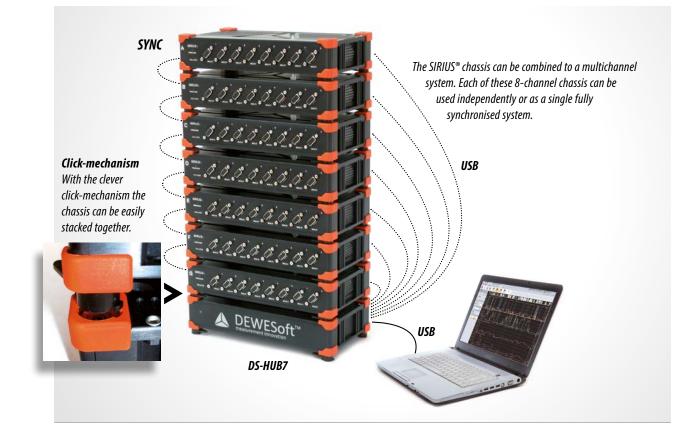


Typ. configuration : single or multiple slices(s) combined together with powerful SBOX and new 12" high brightness Display

SIRIUS® USB CHASSIS WITH AN EXTERNAL PC

Multiple chassis can be combined and synced together to get a multichannel system. If you go for the modular solution, due to the clever mounting-system (click-mechanism)

you can use the SIRIUS[®] devices separately or stacked together, whatever fits best to the actual measurement task.



SIRIUS[®] – Boxed solution

SIRIUS® BOXED system is the most compact solution. It is available with or without the SBOX computer and can be configured with up to 4 slices. Any slice: DUALCOREADC®, high speed

1 MS/s, high density 16 channel / slice or even the 1 ½ height SIRIUS-STG-DB can be combined to any configuration. The SIRIUS[®] BOXED solution offers the most compact system:



- ▶ PC only: 266x139x73 (incl. feet)
- ▶ 8 channels: 266x139x109
- ▶ 16 channels: 266x139x145
- ▲ 24 channels: 266x139x181
- ▶ 32 channels: 266x139x216

CONFIGURATION EXAMPLES

The DEWESoft® CLICK – mechanism allows any combination of MODULAR and BOXED configurations...



COMPACT DAQ SYSTEM

- ▶ Integrated high performance computer
- 8 universal sensor inputs (Strain, Voltage, Current, DSI® adapters)
- ▶ Internal Quarter- and Half-bridge completion
- ▶ Programmable sensor excitation
- ▶ 8 Supercounters®
- ▶ Removable 250 GB/1 TB SSD
- ▶ Expandable with SIRIUS® or EtherCAT® input
- ▶ Built-in GPS (option)



DEWESoft[®] introduces the MINITAURs, fully packed with the latest technology. Based on the SIRIUS[®] DUALCOREADC[®] technology with amazing dynamic, it offers eight universal analogue input channels and at the same time eight Supercounters[®] plus 1 CAN port for automotive applications.

In addition to the standard interfaces such as 2x GLAN and WLAN, DVI-D, the integrated computer provides 4 x USB 3.0 and 2 x USB 2.0 ports and removable SSD for fast data transfer.

Built of a solid aluminium block, rugged and compact, with 266 x 139 mm footprint and 109 mm height only, it is the dedicated instrument for mobile usage. MINITAURs is expandable with battery packs BPi2 and BPi4, and compatible with all other DEWESoft® frontends.

| Analogue Inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), potentiometer |
|---|--|
| ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec |
| DUALCOREADC [®] Ranges (Low Range) | $\pm 10V$ (500 mV), $\pm 1V$ (50 mV), $\pm 100mV$ (5 mV), $\pm 10mV$ (0.5 mV) |
| Bridge ranges @ 10 Vexc (Low Range) | 1000(50)mV/V, 100(5)mV/V, 10(0.5)mV/V, 1(0.05)mV/V |
| Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) |
| Input coupling | DC |
| Input impedance | 10 ΜΩ |
| Bridge modes | Full/Half/Quarter Br 120/350 Ω 3-wire; internal bridge completion |
| Internal shunt resistor | 100 k Ω , bipolar to Exc+ or Exc- (others on request) |
| TEDS | supported DSI® adapters only fit on 9pin DSUB |
| Excitation Voltage | 0 to 12 VDC software programmable (16 Bit DAC), max 44 mA |
| Overvoltage protection | In+ to In-: 50V continuous; 200 V peak (10msec) |
| Typical power consumption (max.) | 11 W (20 W) |
| Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| Input level compatibility | CMOS, LVTTL |
| Input protection | ±25 V continuous |
| Digital output | 8 ch open collector, max. 100mA/30 V |

| Integrated high performance computer | | | | |
|--------------------------------------|--|--|--|--|
| CPU | Intel Core i3, 1.7GHz, 3 MB cache | | | |
| RAM | 4GB (up to 16 GB upon request) | | | |
| Storage | 250 GB removable SSD option: 1 TB removable SSD option: 250 GB int. FLASH (for OS) | | | |
| Power supply | 9-36 VDC | | | |
| Power out | same output voltage level as power in | | | |
| GPS | 10 Hz option, 100 Hz option, 100 Hz option + RTK option | | | |
| Interfaces | 2x USB 2.0 4x USB 2.0 4x USB 3.0 DVI-D interface for external display 2x Ethernet LAN + WLAN GPS antenna GPS display/RTK modem (DB9) EtherCAT® connector 2x Sync connector | | | |
| Operating temperature | 0 to 50°C | | | |
| Dimensions | 266 x 139 x 109 mm | | | |





HIGH PERFORMANCE CPU IN SIRIUS® FORMAT

- ▶ For rugged standalone DAQ solution
- ▶ 6 USB interfaces (screwable connector)
- ▶ WLAN and 2x GLAN
- **EtherCAT**[®] interface with Synchronisation
- Removable 250 GB SATA SSD (1 TB option)
- ▶ Optional GPS with RTK
- ► Fanless version: SBOXfe

With the SBOX, SIRIUS® becomes a state-of-the-art compact standalone solution. Please find our waterresistant and ultra rugged version SBOXwe in the extreme line instruments section.

FAST SPEED

With typ. 180 MB/s write rate to the flash disk, there is enough capability for e.g. external high-speed cameras with high streaming rates. USB 3.0 ports for quick data transfer (nearly 10x faster than USB 2.0) and the Core i7 processor allow quick and fluent working even if your setup has thousands of channels with multiple interfaces.

REMOVABLE SSD

For safe, stable operation we recommend separating the operating system and measurement data. The SIRIUS® SBOX-FLASH250 option allows the operating system to be installed on an internal 250 GB flash storage. The measurement data is stored on the removable SSD. This allows easy transportation and archiving of your data.



| | SBOXe | SBOXfe | | |
|--------------------------|---|--|--|--|
| TECHNICAL SPECIFICATIONS | | | | |
| CPU | Intel® Core™ i7-3612QE 4x 2.1 GHz 8 threads | Intel® Core™ i7-3517UE 2x 1.7 GHz 4 threads | | |
| RAM | 4 GB | 4 GB | | |
| Disc | 250 GB removable SATA SSD Option: 1TB removable SATA SSD Option: 250 GB mSATA internal SS | 250 GB removable SATA SSD Option: 1TB removable SATA SSD Option: 250 GB mSATA internal SSD | | |
| Power supply voltage | 9-36 VDC | 9-36 VDC | | |
| Power consumption | Typ. 40 W (max. 55 W) | 30 W max. | | |
| Operating temperature | | -10 to 50°C | | |
| Storage temperature | | -20 to 80°C | | |
| INTERFACES AND OPTIONS | | | | |
| USB | Front: 4x USB 3.0 Rear: 2x USB 2.0 | | | |
| Ethernet | 2x GLAN, 1x WLAN | | | |
| EtherCAT® | 1x EtherCAT® 100Mbps Full Duplex, LEMO 8pin female | | | |
| Synchronisation | | 1x SIRIUS® SYNC on LOOB4f | | |
| Video | | 1x DVI (VGA and HDMI compatible) | | |
| GPS option | 10Hz, 100Hz, 100 Hz & RTK | | | |
| GPS display | External on DSUB9f connector with remote power on | | | |
| Power out | Switched supply on L1B2f (max. 8A) | | | |
| PHYSICAL SPECIFICATIONS | | | | |
| Dimensions | 265 x 150 x 75 mm | 265 x 150 x 80 mm | | |
| Humidity (@60°C) | | 5 to 95 % RH non-condensing | | |
| Shock & Vibration | VIBRATION SWEEP SINUS (EN 60068-2-6:2008) | VIBRATION RANDOM (EN 60721-3-2: 1997 - Class 2M2 / 2M3) SHOCK (EN 60068-2-27:2009) | | |



R8 / R8B / R8D / R8DB

THE MOST COMPACT HIGH CHANNEL PORTABLE

- ▲ 4 versions available:
 - *R8 with integrated SBOXre computer R8B - with hot-swappable 384 Wh batteries R8D - with 17" high brightness multi-touch screen R8DB - with touch screen and hot-swappable batteries*
- ▶ Up to 128 analogue channels with SIRIUS HD (200 kS/s each channel)
- ▶ Up to 64 analogue channels with SIRIUS HS (1 MS/s each channel)
- ▶ Up to 64 Supercounters®
- ▶ Up to 8 CAN ports
- ▶ Up to 64 analogue outputs
- ► 250 GB internal flash + 250 GB removable SSD (1 TB opt.)
- **•** Easily expandable to hundreds of channels



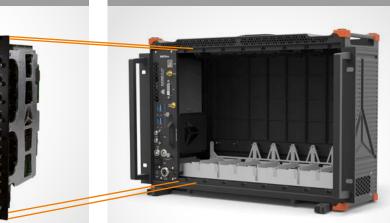


| | R8 | R8B | R8D | R8DB |
|--|--|--|---|---|
| TECHNICAL SPECIFICATIONS | | | | |
| Display | - | - | 17" high brightness multi-touch display full HD | 17" high brightness multi-touch display full HD |
| Hot-swappable batteries | - | 384 Wh Li-Ion | - | 384 Wh Li-Ion |
| CPU | | Intel® Core™ i7-3612Q | E; 4x 2.1 GHz; 8 threads | |
| RAM | | 4 | GB | |
| Storage | | 250 GB removable SATA SSD Option: 1TB removable SATA SSD Option: 250 GB mSATA internal SSD | | |
| Power supply voltage | 12-36 VDC | 18-24 VDC | 12-36 VDC | 18-24 VDC |
| Power consumption (without SIRIUS slices) | Typ. 25 W (max. 55 W) | Typ. 25 W (max. 55 W) | Typ. 35 W (max. 65 W) | Typ. 35 W (max. 65 W) |
| Charging power | - | 60 W | - | 60 W |
| Operating temperature | -10 to 50°C | 0 to 40°C | -10 to 50°C | 0 to 40°C |
| Storage temperature | -40 to 85°C | -20 to 60°C | -40 to 85°C | -20 to 60°C |
| INTERFACES AND OPTIONS | | | | |
| USB | Front: 4x USB 3.0 | Front: 4x USB 3.0 | Front: 3x USB 3.0, 1x USB 2.0 Rear: 4x USB 3.0 | Front: 3x USB 3.0, 1x USB 2.0 Rear: 4x USB 3.0 |
| Ethernet | | 1x GLAN, 1x WLAN, opt. | 2x GLAN instead of WLAN | |
| EtherCAT® | 1x Ether | CAT® 100Mbps Full Duplex, LEMO 8 pin fe | emale, max. 8 A (shared with power out c | onnector) |
| Power out | | Switched supply on L1B2f, max. 8 | A (shared with EtherCAT® connector) | |
| Video | Video 1x DVI-I (VGA and HDMI compatible) | | | |
| GPS option | GPS option 10 Hz or 100 Hz or 100 Hz + RTK | | | |
| GPS display | | External on DSUB9f conne | ector with remote power on | |
| Synchronization | | 2x SIRIUS® S | YNC on L00B4f | |
| Analogue out option | up to 64 channels | - | - | - |
| PHYSICAL SPECIFICATIONS | | | | |
| Dimensions | 447 x 313 x 150 mm | 447 x 313 x 205 mm | 447 x 313 x 165 mm | 447 x 313 x 205 mm |
| Weight excl. SIRIUS® slices | 5 kg | 9.6 kg incl. 4 batteries | 7.3 kg | 11.9 kg incl. 4 batteries |
| Humidity (@60°C) | | 5 to 95 % RH | non-condensing | |
| Shock & Vibration | VIBRATION SWEEP SINUS (EN 60068-2-6:2008) VIBRATION RANDOM (EN 60721-3-2: 1997 - Class 2M2) SHOCK (EN 60068-2-27:2009) MIL-STD-810D | | | |

Battery weight: 650 g SIRIUS® slice weight: ~800 g

Isolated / differential

- ► SIRIUSir 8xACC
- ► SIRIUSir 6xACC,2xACC+
- ▶ SIRIUSir 8xCHG
- ⊾ SIRIUSir 8xHV
- ► SIRIUSir 8xMULTI
- ⊾ SIRIUSir 8xSTG
- ► SIRIUSir 8xSTGM
- ▶ SIRIUSr-HD 16xSTGS
- ▶ SIRIUSr-HD 16xLV
- ► SIRIUSir-HS 8xACC
- ▶ SIRIUSir-HS 6xACC, 2xACC+
- **.** ...



R8

- ► Base enclosure for rack/standalone solution
- ▶ Including powerful Core i7 SBOXre computer
- ▶ Provides space for up to 8 SIRIUSr slices

Intel i7-PC

| | - | | | | | 0 | lata | | | | 0.000 |
|---------|--------|----|------|--------|----------|-------|------|------|------|------|-------|
| | Core 1 | AB | - | 010 | 11010 | 01010 | 1010 | | | ٦ | 1 |
| SBOX i7 | Core 2 | AB | 0' | 10110 | 10101 | 010 | | 7 | ٦ | | |
| SBC | Core 3 | AB | | | | 7 | ٦ | | | | |
| | Core 4 | AB | 0101 | 10100 | 1 | | | | | | |
| | | | | | 1 | 1 | - | 4 | 4 | 1 | 1 |
| | | | | Sirius | ns | ns | ns | ius | ns | SU | sn |
| | | | | Siri | Siri | Siri | Siri | Siri | Siri | Siri | Sir |

The fast SBOX computer is equipped with a quad core/8 thread i7 CPU. One native USB port for each of the 8 slots guarantees the fastest data throughput:

- ▶ 64 channels @ 1 MS/s, 16 bit high speed
- ▶ 64 channels @ 200 kS/s, 2x24 bit DUALCOREADC®
- 128 channels @ 200 kS/s, 24 bit high density
- ⊾ i7 CPU
- ▶ 1 TB SSD: up to 180 MB/s data streaming

CONFIGURATION EXAMPLE



Mixed analogue channels:

- 24 channels @ 1 MS/s, 16 bit high speed
- ▲ 16 channels @ 200 kS/s, 2x24 bit DUALCOREADC[®]
- ▶ 48 channels @ 200 kS/s, 24 bit high density
- ▶ 8 counters
- ⊾ 5 CAN BUS
- HIGH CHANNEL COUNT EXAMPLE

R8RT

HIGH END DEWESoft® DAQ SYSTEM AND DIGITAL REAL-TIME SIGNAL CONDITIONING VIA EtherCAT®

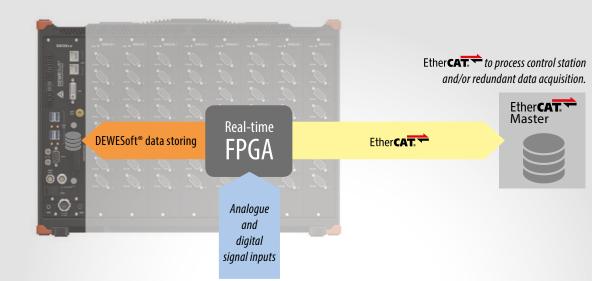
- ▶ DEWESoft® analogue and digital input signal conditioning:
 ▶ based on the SIRIUS® DAQ modules
- ▶ REDUNDANT data storing:
 ▶ internal SBOX and external EtherCAT[®] master
- ▶ Programmable 2 different data rates: USB and EtherCAT®
- **Real-time data output via EtherCAT**[®], data delay $< 100 \, \mu s$



| R8RT | | | | |
|-----------------------------|--|--|--|--|
| TECHNICAL SPECIFICATIONS | | | | |
| CPU | Intel® Core™ i7-3612QE; 4x 2.1 GHz; 8 threads | | | |
| RAM | 4 GB | | | |
| Disc | 250 GB removable SATA SSD Option: 1TB removable SATA SSD Option: 250 GB mSATA internal SSD | | | |
| Power supply voltage | 12-36 VDC | | | |
| Power consumption | Typ. 25 W (max. 55 W) | | | |
| Operating temperature | -10 to 50°C | | | |
| Storage temperature | -40 to 85°C | | | |
| INTERFACES AND OPTIONS | | | | |
| USB | Front: 4x USB 3.0 | | | |
| Ethernet | 1x GLAN, 1x WLAN, opt. 2x GLAN instead of WLAN | | | |
| EtherCAT® | 1x EtherCAT® 100Mbps Full Duplex, LEMO 8 pin female, max. 8 A (shared with power out connector) | | | |
| Power out | Switched supply on L1B2f, max. 8 A (shared with EtherCAT* connector) | | | |
| Video | 1x DVI-I (VGA and HDMI compatible) | | | |
| GPS | Optional 10 Hz or 100 Hz or 100 Hz + RTK | | | |
| GPS display | External on DSUB9f connector with remote power on | | | |
| Synchronization | 2x SIRIUS® SYNC on L00B4f | | | |
| Analogue out option | up to 64 channels | | | |
| REAL-TIME | | | | |
| EtherCAT® slave port | Minimum delay (analogue input to EtherCAT® bus): 70 µs Minimum EtherCAT® cycle time: 100 µs | | | |
| PHYSICAL SPECIFICATIONS | | | | |
| Dimensions | 447 x 313 x 150 mm | | | |
| Weight excl. SIRIUS® slices | 5 kg | | | |
| Humidity (@60°C) | 5 to 95 % RH non-condensing | | | |
| Shock & Vibration | VIBRATION SWEEP SINUS (EN 60068-2-6:2008) VIBRATION RANDOM (EN 60721-3-2: 1997 - Class 2M2) SHOCK (EN 60068-2-27:2009) MIL-STD-810D | | | |

SIRIUS® slice weight: ~800 g

DIGITAL SIGNAL CONDITIONING AS WELL AS REDUNDANT DATA ACQUISITION



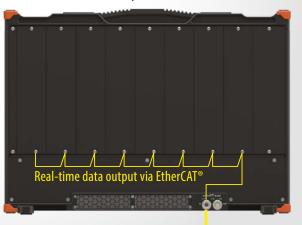
R8RT front view EtherCAT[®] master port for SIRIUSe / KRYPTON[®]



EtherCAT[®] master port:

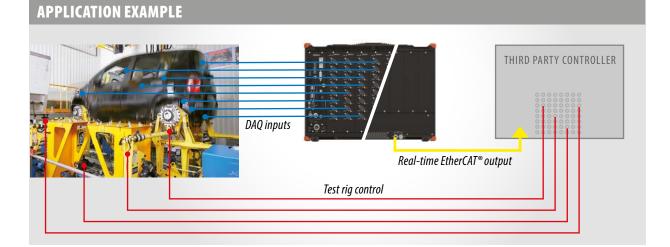
- ▶ Connect SIRIUSe / KRYPTON[®] with daisy chain cable
- ▶ For DAQ in DEWESoft X, not real-time
- ▶ Synchronized with USB devices
- ▶ Includes power output (R8RT supply voltage, max. 8 A)

R8RT rear view Internal EtherCAT[®] bus with output connector



EtherCAT[®] slave port:

- ► Connects to 3rd party EtherCAT[®] master
- ▶ Standard EtherCAT®
- ▶ Real-time data from SIRIUS[®] slices



INSTRUMENTS

R2D and R2DB

THE MOST COMPACT PORTABLE



- ▶ Powerful Intel[®] Core[™] i3-PC
- ▶ Up to 2 SIRIUS[®] slices (32 channels)
- 12.1" high brightness multi-touch WXGA display
 Hot-swappable batteries for maximum portability
- 192 Wh Li-Ion
- ► All connectors on one side of the instrument
- ► Integrated keyboard & touchpad
- ▶ 4xUSB 3.0, WLAN, 2x sync, EtherCAT[®], 2xGLAN,
- ▶ 4 GB RAM, 250/500 GB mSATA SSD
- ▶ Up to 2x CAN ports
- ▶ *GPS option: 10 Hz/100 Hz/100 Hz* + *RTK*
- 9-36 V_{DC} supply
- ▶ Operating temperature 0 to 50°C
- ▶ Including DEWESoft® X Prof

Available in 2 versions: R2D - with built in display R2DB - with built in display and hot-swappable batteries

The system is easy to carry because of the low weight of only 11 kg and the small dimensions (446x357x205 mm). The free combination of any SIRIUS® slice with DUAL-COREADC® 200 kS/s, high density or high speed (1 MS/s) makes it very easy to configure the system for any application!



The light weight aluminium chassis makes the R2D a very small rugged instrument



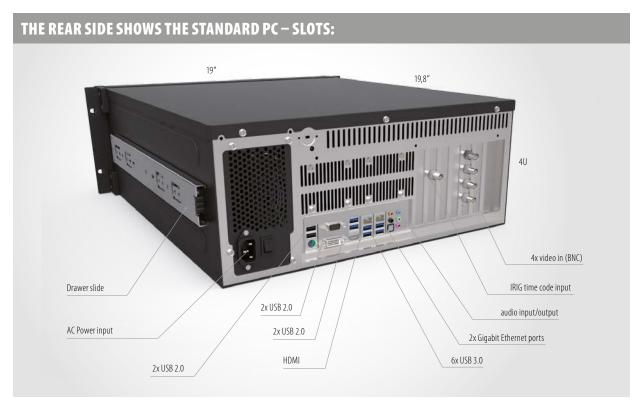
EtherCAT[®] expansion example: 64 thermocouples 100Hz sampling rate

- ▲ 4x KRYPTON 16xTH
- ▶ -40 to 85 °C ambient temperature
- ▶ high shock/vibration rating

R3 THE FLEXIBLE PC - BASED CHASSIS



Up to 3 slices (48 analogue input channels) or any combination of the SIRIUS® slices can be installed. The standard PC offers easy expendabilities with our PPCM cards to a full telemetry system. The 19" brackets are available for Rack installation.



SIRIUS®

| | HIGH DTNAMIC: DOALCOREADC WITH 2X24 Bit | | | | | | |
|--|---|---|-------------------------------------|--|---|--|--|
| SIRIUS* analogue input modules types | SIRIUS-ACC | SIRIUS-CHG | SIRIUS-HV | SIRIUS-LV | SIRIUS-MULTI | SIRIUS-STG | SIRIUS-STGM |
| version with additional counter / DIO | SIRIUS-ACC+ | SIRIUS-CHG+ | | SIRIUS-LV+ | SIRIUS-MULTI | SIRIUS-STG+ | SIRIUS-STGM+ SIRIUS-STGM-DB |
| Isolated version i | ✓ | \checkmark | ✓ | \checkmark | \checkmark | \checkmark | \checkmark |
| Differential version | ✓ | \checkmark | - | ✓ | ✓ | \checkmark | \checkmark |
| EtherCAT [®] version | Image: A start of the start of | Image: A start of the start of | ✓ | ✓ | ✓ | Image: A second s | |
| Rack version r ¹⁾ | _ | · · | | · · · · · · · · · · · · · · · · · · · | | · · · · · · · · · · · · · · · · · · · | · · · · · · · · · · · · · · · · · · · |
| Fanless version f | | - | | 5) | _ | _ | · · · · · · · · · · · · · · · · · · · |
| Analogue inputs ²⁾ | • | _ | • | V 3/ | - | - | • |
| Analog inputs per module | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Data Rate / USB | 200 k | 200 k | 200 k | 200 k | 200 k | 200 k | 200 k |
| Channel [Hz] EtherCAT® | 200 k | 200 k | 200 k | 200 k | 200 k | 200 k | 200 k |
| Vertical Resolution | 2 * 24 Bit | 2 * 24 Bit | 2 * 24 Bit | 2 * 24 Bit | 2 * 24 Bit | 2 * 24 Bit | 2 * 24 Bit |
| Bandwidth | 70 kHz | 70 kHz | 70 kHz | 70 kHz | 70 kHz | 70 kHz | 70 kHz |
| Voltage | ± 10 V, ± 500 mV | ± 10 V, ± 500 mV | ±1200 V, ±50 V | ±200 V to ±100 mV | ± 10 V to ± 50 mV | ±50 V to ±100 mV | ± 10 V to ± 10 mV |
| Input coupling | DC, AC 0.1 Hz, 1 Hz, (3,10 Hz SW) | DC, AC 0.1 Hz, 1 Hz, 10 Hz or 100 Hz | DC | DC, AC 1 Hz (3,10 Hz SW) | DC | DC, AC 1 Hz (3,10 Hz SW) | DC |
| Sensor Excitation | - | - | - | 230 V bipolar 024 V unipol. max. 0.2 A/2 W | 0 12 V, max. 44 mA 12 V, 5 V | 0 20 V, max. 0.8 W 0 60 mA, max 0.5 W | 0 15 V, max. 44 mA |
| Bridge connection (internal completion) | - | - | - | Full | Full, Half, ¼ 120/350 Ω 3-wire | Full, Half, ¼ 120/350 Ω 3 or 4-wire | Full, Half, ¼ 120/350 Ω 3-wire |
| Programmable Shunt (default Values) | - | | - | - | 59.88 kΩ | 59.88 kΩ, 175 kΩ bipolar | 100 kΩ, bipolar |
| IEPE/ICP Sensors | 2 to 20 mA (prog.) | 4, 8 or 12 mA | - | DSI® | DSI® | DSI® | DSI® |
| Resistance | - | - | - | DSI® | DSI® | ✓ | DSI® |
| Temp. (PT100 to PT2000) | - | - | - | DSI® | DSI® | ✓ | DSI® |
| Temp. (Thermocouple) | - | - | - | DSI® | DSI® | DSI® | DSI® |
| Potentiometer | - | - | - | - | ✓ | ✓ | ✓ |
| LVDT | - | - | - | DSI® | DSI® | DSI® | DSI® |
| Charge | - | 100,000 pC, 10,000 pC | - | DSI® | DSI® | DSI® | DSI® |
| Current | ext. Shunt | ext. Shunt | - | ext. Shunt | ext. Shunt | ext. Shunt | ext. Shunt |
| TEDS interface Advanced functions | Sens. error detection, high dynamic range | Sensor error detection in IEPE and charge mode (injection) | – High Voltage High Isolation | High sensor power and multi range | Analogue and digital inputs, analogue out | Supports all strain types and high input range | Low power, Sensor and Amplifier balance, Bipolar shunt |
| Analogue input connectors | | | | | | | |
| Connector type (Default) | BNC | BNC, TNC | Banana | DB9, BNC, Banana | DB15, L2B16f | DB9, L2B7f, L2B10f | DB9, L2B8f, L2B16f |
| Digital types (version with a | addtional counter/digi | tal input) | | | | | |
| Counter (connector) | 1 ch(L1B7f) | 1 ch(L1B7f) | - | 1 ch(L1B7f) | 1 ch(DB15) 1 ch(L2B16f) | 1 ch(L1B7f) 1ch(L2B10f) ⁶⁾ | 1 ch(L1B7f) |
| Digital Input (connector) | 3 ch(L1B7f) | 3 ch(L1B7f) | - | 3 ch(L1B7f) | 3 ch(DB15) 3 ch(L2B16f) | 3 ch(L1B7f) 1ch(L2B10f) ⁶⁾ | 3 ch(L1B7f) |
| Digital Output (connector) | 1 ch(L1B7f) | 1 ch(L1B7f) | | 1 ch(L1B7f) | - | 1 ch(L1B7f) 1ch(L2B10f) ⁶⁾ | 1 ch(L1B7f) |
| Additional information | 1000 V | 1000 1/ | CAT 1000\/ | 10001/ | 1000.1/ | 1000.1 | 1000 V |
| Isolation voltage 3) Power consumption | 1000 V | 1000 V | CAT II 1000V | 1000V | 1000 V | 1000 V | 1000 V |
| (max.) ⁴⁾ | 8 W (15 W) | 10 W (18 W) | 8 W | 10 W (25 W) | 15 W (25 W) | 15 W (25 W) | 11 W (20 W) |

HIGH DYNAMIC: DUALCOREADC® with 2x24 Bit

32

| Site Site <th< th=""><th colspan="3">HIGH DENSITY: 24 Bit, 16 channels per slice</th><th colspan="6">HIGH SPEED: 16 Bit with high bandwidth</th></th<> | HIGH DENSITY: 24 Bit, 16 channels per slice | | | HIGH SPEED: 16 Bit with high bandwidth | | | | | |
|--|--|---------------------------------|---------------------------|--|---|--------------------------|--------------------------|---|--|
| Image of the set of | ۲ | ° | o o | SIRIUS-HS-ACC | SIRIUS-HS-CHG | SIRIUS-HS-HV | sirius-HS-LV | sirius-HS-STG | |
| Image: state of the state of | | | | SIRIUS-HS-ACC+ | SIRIUS-HS-CHG+ | | SIRIUS-HS-LV+ | SIRIUS-HS-STG+ | |
| Image: state of the state of | ✓ | ✓ | ✓ | \checkmark | \checkmark | ✓ | ✓ | \checkmark | |
| \checkmark \checkmark \checkmark \cdot | | ✓ | ✓ | | | - | ✓ | ✓ | |
| Image: state | | | | | | | | | |
| · | · · · · · · · · · · · · · · · · · · · | | | | | | | | |
| Note Note Note Note Note Note Note 2 2 1 1 1 1 1 1 1 200 k 200 k 200 k 1M | | | | | | | | | |
| 200k200k200k11M <th< td=""><td>-</td><td></td><td>-</td><td></td><td></td><td>•</td><td>V 5)</td><td></td></th<> | - | | - | | | • | V 5) | | |
| 200 k200 k200 k1 M1 M | 2 | 2 | 2 | 1 | 1 | 1 | 1 | 1 | |
| 10 k 10 k 10 k . <th< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th<> | | | | | | | | | |
| 70 kHz70 Hz70 Hz500 Hz500 Hz20 Hz2 Hz1 HHz $\pm 100 V to \pm 100 W$ $\pm 100 V to \pm 20 W$ | | | | | | | | | |
| ±101 Vb ±200 mV ±100 Vb ±100 mV ±101 Vb ±100 mV ±101 Vb ±200 mV ±100 Vb ± | 24 Bit | 24 Bit | 24 Bit | 16 Bit | 16 Bit | 16 Bit | 16 Bit | 16 Bit | |
| DC, Cd, Cd, L1, L1, L1, (B, 10 Hz, SW)DCDC, CdDC, Cd, Cd, L1, L1, (B, 10 Hz, SW)DCDC, Cd, Cd, L1, L1, (B, 10 Hz, SW)DCDC, Cd, Cd, L1, L1, | 70 kHz | 70 kHz | 70 kHz | 500 kHz | 500 kHz (200 kHz chg) | 2 MHz | 1 MHz | 1 MHz | |
| (3, 10 hz SW) UL (3, 10 hz SW) 10 Hz or 100 Hz UL (3, 10 Hz SW) | $\pm 10V$ to $\pm 200mV$ | $\pm 100~V$ to $~\pm 100~mV$ | ± 10 V to ± 10 mV | $\pm 10V$ to $\pm 200mV$ | ± 10 V to $\ \pm 100$ mV | $\pm 1600V$ to $\pm 20V$ | $\pm 100V$ to $\pm 50mV$ | $\pm50V$ to $\pm20mV$ | |
| 0.24V unipol.max. 0.2 A/2 W $0.24V unipol.max. 0.2 A/2 W 0.24V unipol.max. 0.2 A/2 W 0.24V unipol.max. 0.2 A/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W 0.26V a/2 W $ | | DC | DC | | | DC | | | |
| \cdot | - | 024 V unipol. | | | - | - | 024 V unipol. | max. 0.1 A/0.8 W, | |
| $4,8 or 12 mÅ$ DS1*DS1* $4 or 8 mÅ$ $4,8 or 12 mÅ$ $-$ DS1*DS1* $DS1*$ \cdot DS1*DS1* \cdot | - | Full | | - | - | - | Full | Full, Half, ¼ 120/350 Ω 3 or 4-wire | |
| \cdot DS1*DS1* \cdot \cdot \cdot DS1*DS1* \cdot \cdot DS1* \cdot \cdot \cdot DS1* \cdot \cdot DS1* \cdot \cdot \cdot DS1* \cdot | - | - | 100 kΩ | - | - | - | - | 59.88 kΩ, 175 kΩ, bipol | |
| \cdot DS1*DS1* \cdot \cdot \cdot DS1* \checkmark \cdot DS1*DS1* \cdot \cdot \cdot \cdot DS1*DS1* \cdot DS1*DS1* \cdot \cdot \cdot \cdot DS1*DS1* \cdot \cdot \cdot DS1*DS1* \cdot \cdot \cdot \cdot DS1*< | 4, 8 or 12 mA | DSI® | DSI® | 4 or 8 mA | 4, 8 or 12 mA | - | DSI® | | |
| \cdot DSI*DSI* \cdot \cdot \cdot \cdot DSI*DSI* \cdot DSI*DSI* \cdot \cdot \cdot \cdot DSI*DSI* \cdot <td< td=""><td>-</td><td>DSI®</td><td>DSI®</td><td>-</td><td>-</td><td>-</td><td>DSI®</td><td>✓</td></td<> | - | DSI® | DSI® | - | - | - | DSI® | ✓ | |
| ··· <td>-</td> <td>DSI®</td> <td>DSI®</td> <td>-</td> <td>-</td> <td>-</td> <td>DSI®</td> <td>\checkmark</td> | - | DSI® | DSI® | - | - | - | DSI® | \checkmark | |
| \cdot DS1*DS1*DS1* \cdot \cdot \cdot \cdot DS1* </td <td>-</td> <td>DSI®</td> <td>DSI®</td> <td>-</td> <td>-</td> <td>-</td> <td>DSI®</td> <td>DSI®</td> | - | DSI® | DSI® | - | - | - | DSI® | DSI® | |
| ·DSI*DSI*100,000 pC to 1,000 pC·DSI*DSI*DSI*ext. Shuntext. Shuntext. Shuntext. Shuntext. Shuntext. Shuntext. Shuntext. Shunt✓✓✓✓✓✓✓✓✓Sensor error detection in high input range, high sensor supplylow power, Sensor and Amplifier balanceHigh speed, Sensor error detection in IEPE and charge mode (injection)High Sensor power and Sensor error detection in IEPE and charge mode (injection)High Sensor power and Sensor error detection in IEPE and charge mode (injection)High Sensor power and Sensor error detection in IEPE and charge mode (injection)High Sensor power and Sensor error detection in IEPE and charge mode (injection)High Sensor power and Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error detection in IEPE and charge mode (injection)High Sensor Sensor error | - | - | \checkmark | - | - | - | - | \checkmark | |
| ext. Shuntext. Shuntext. Shuntext. Shuntext. Shuntext. Shuntext. ShuntImage: Constraint of the state of the stat | - | DSI® | DSI® | - | - | - | DSI® | DSI® | |
| Image: Constraint of the sensor error detection in high input range, high input range, high input range, high sensor supply Image: Constraint of the sensor error detection in LEPE and charge mode (injection) High Voltage High sensor power and high sensor power and high sensor supply High sensor and high speed, sensor error detection in LEPE and charge mode (injection) High sensor power and high sensor and high speed, sensor error detection in LEPE and charge mode (injection) High sensor power and high sensor supply High speed, sensor error detection in LEPE and charge mode (injection) High sensor power and high sensor supply High speed, sensor error detection in lePE and charge mode (injection) High sensor power and high speed, sensor error detection in lePE and charge mode (injection) High sensor power and high sensor supply High sensor power and high speed, sensor error detection in lePE and charge mode (injection) High sensor power and high sensor supply High sensor power and high sensor power and high sensor power and high sensor supply High sensor power and high sensor powe | - | DSI® | DSI® | - | 100,000 pC to 1,000 pC | - | DSI® | DSI® | |
| Sensor error detection high input range, high sensor supply Low power, Amplifier balance Low power, Sensor and Amplifier balance High speed, Sensor error detection IEPE and charge mode (injection) High Voltage High Bandwidth High speed, Suppo strain types and F input range BNC DB9, DBC DB9, L1B10f BNC BNC Banana DB9, BNC, Banana DB9 - <td>ext. Shunt</td> <td>ext. Shunt</td> <td>ext. Shunt</td> <td>ext. Shunt</td> <td>ext. Shunt</td> <td>-</td> <td>ext. Shunt</td> <td>ext. Shunt</td> | ext. Shunt | ext. Shunt | ext. Shunt | ext. Shunt | ext. Shunt | - | ext. Shunt | ext. Shunt | |
| · | | Low power, high input range, | Low power, Sensor and | High speed, | Sensor error detection in IEPE and charge mode | | High sensor power and | High speed, Support all strain types and high | |
| · | | | | | | | | | |
| And the second | BNC | DB9, BNC | DB9, L1B10f | BNC | BNC | Banana | DB9, BNC, Banana | DB9 | |
| · | | | | | | | | | |
| · | - | - | - | 1 ch(L1B7f) | 1 ch(L1B7f) | - | 1 ch(L1B7f) | 1 ch(L1B7f) | |
| 500 V 500 V 500 V 1000 V 1000 V CAT II 1000 V 1000 V 1000 V | - | - | - | 3 ch(L1B7f) | 3 ch(L1B7f) | - | 3 ch(L1B7f) | 3 ch(L1B7f) | |
| | - | - | | 1 ch(L1B7f) | 1 ch(L1B7f) | - | 1 ch(L1B7f) | 1 ch(L1B7f) | |
| | 500 V | 500 V | 500 V | 1000 V | 1000 V | CAT II 1000 V | 1000 V | 1000 V | |
| 11 W (22 W) 11 W (22 W) 11 W (22 W) 15 W (22 W) 10 W (18 W) 8 W 10 W (25 W) 15 W (25 W) | | | | | | | | | |

Rack version modules not available with extended height (eg. STGM-DB).
 Analogue input types: Pinout of input connector may limit functionality. Please refer to detailed specification below. DSI®-Option requires DB9 connector on the module or adapter connector or cable.

3) Applies only for isolated SIRIUS® version 4) One complete slice with same modules 5) Fanless operation only for BNC or Banana version (without excitation) 6) One digital I/O per amplifier with Lemo 2B10f connector

| | | DUALCOREADC® | (200 kS/s, 2x24 bit) | and High Density | (200 kS/s, 24 bit) | High Speed (1 | l MS/s, 16 bit) |
|-------------------------------|--------------------------|--|-----------------------|-------------------|------------------------|-------------------------------|--------------------|
| | | | | Far | nless | | |
| SIRIUS® type | Connectors | Isolated | Differential | Isolated | Differential | Isolated | Differenti |
| Modular version | | SIRIUS i | SIRIUS® | SIRIUS if | SIRIUS f | SIRIUS <mark>i</mark> -HS | SIRIUS-H |
| Rack version | | SIRIUS ir | SIRIUS | - | - | SIRIUS ir -HS | SIRIUS r -H |
| EtherCAT [®] modula | ar version ¹⁾ | SIRIUS ie | SIRIUS <mark>e</mark> | SIRIUS <i>ife</i> | SIRIUS fe | | |
| EtherCAT [®] rack ve | rsion ¹⁾ | SIRIUS <i>ire</i> | SIRIUS re | - | - | - | - |
| IEPE | | • | | | | | |
| 4xACC | BNC | - | - | - | ● | - | - |
| 3xACC, 1xACC+ | BNC + Lemo | - | - | - | ●~~ <u></u> | - | - |
| 8xACC | BNC | EtherCAT + | EtherCAT + | EtherCAT + | EtherCAT + | • | • |
| 6xACC, 2xACC+ | BNC + Lemo | EtherCAT. + | EtherCAT + | EtherCAT + | EtherCAT. | • | •~~ <u>•</u> |
| HD 16xACC | BNC | EtherCAT + | EtherCAT: + | | EtherCAT + | - | - |
| CHARGE | DNC | | | | | | |
| 8xCHG | BNC | EtherCAT. | EtherCAT. | - | - | • | • |
| 6xCHG, 2xCHG+ VOLTAGE | BNC + Lemo | EtherCAT. + + ++++++++++++++++++++++++++++++++ | EtherCAT + | - | - | ● | • |
| 8xHV | Banana | EtherCAT | _ | Ether CAT | - | • | - |
| 4xHV, 4xLV | Banana+DSUB/Banana | Ether CAT | _ | _ | _ | • | - |
| 4xHV, 4xLV+ | Banana+DSUB+Lemo | Ether CAT | _ | _ | _ | • | - |
| 8xLV | DSUB/BNC/Banana | EtherCAT + | Ether CAT | | | • | •~ |
| 8xLV+ | DSUB/BNC/Lemo | Ether CAT | Ether CAT, 23 + C+ | • 4) | ← (4) | • | • |
| HD 16xLV | DSUB/BNC | EtherCAT + | EtherCAT + | • (BNC only) | • (BNC only) | - | - |
| MULTI | | | | | | | |
| 8xMULTI | DSUB | • | • | - | - | - | - |
| 4xACC+,4xSTGM | DSUB+BNC+Lemo | EtherCAT + | EtherCAT + | • | - | - | - |
| STRAIN GAUGE | DCUD // | | | | | 4 | |
| 8xSTG | DSUB/Lemo | EtherCAT. | EtherCAT. | - | - | ● ~ | •~ |
| 6xSTG, 2xSTG+ | DSUB+Lemo | EtherCAT. | Ether CAT | - | - | | - |
| 8xSTG+ | DSUB/Lemo+Lemo | Ether CAT | EtherCAT. | - | - | ● | • |
| 8xSTGM | DSUB | EtherCAT • | EtherCAT. | • | • | - | - |
| 8xSTGM+ | DSUB+Lemo | Ether CAT. | EtherCAT. | • | ● ~ ~ ~ ~ ~ | - | - |
| 8xSTGM-DB | DSUB | EtherCAT. | EtherCAT. | - | - | - | - |
| HD 16xSTGS | DSUB/Lemo | EtherCAT. + | EtherCAT. + | - | - | - | - |
| CUSTOMISED Custom | DSUB/BNC/Banana/Lemo | EtherCAT + | EtherCAT + | | | €~~ | •4 |
| ANALOGUE OUT | | | | - | - | | |
| A08 option ⁵⁾ | BNC | •< | •< | - | - | ● | •4 |
| CAN-BUS | | | | | | | |
| 4xCAN | DSUB | - | - | •~ | - | - | - |
| 8xCAN | DSUB | • | _ | • | _ | _ | |

1) For all EtherCAT® versions, CAN interface is not available

2) Not available for Rack version

3) Via Ethercat bus max. 4 counter channels are supported

4) Fanless operation only for BNC or Banana version (without excitation)

5) Signal conditioning mode is not supported with SIRIUS® High Densitiy

For all CAN types and EtherCAT[®] versions, A08 option not available

6) For Rack: SIRIUSir-9xCAN instead of 8xCAN

USB interface • Control EtherCAT® interface

<u>SIRIUS</u>®

SIRIUS® HIGH DYNAMIC DUALCOREADC® – 2x 24 Bit, 200 kS/s

This new technology solves the often faced problem that the signal is higher than expected and therefore clipped. DEWESoft®DUALCOREADC®technology always gives you the full possible measuring range, because the signal is measured with a high and a low gain at the same time!

- Sound and vibration
- No over-range errors (no signal clipping)
 Best for high dynamic sensors:
- Microphones, Accelerometers, Strain gauges

SIRIUS<mark>m</mark> 4xACC

| Analogue inputs | 4 ch voltage, IEPE, current (with ext. Shunt) |
|--------------------------------------|--|
| ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec |
| DUALCOREADC [®] (Low range) | ± 10 V (500 mV), ± 500 mV (not available) |
| Dynamic Range@10kS (DUALCOREADC® | 140 dB (160 dB) |
| Input coupling | DC, AC 0.1 Hz, 1 Hz (3, 10 Hz SW) |
| Input impedance | 1 MΩ in parallel with 0.4nF |
| IEPE mode | Exc.: 2, 4, 8, 12, 16 or 20 mA; Sensor detection (Short: <4 V; Open: > 19 V) |
| TEDS | supported in IEPE mode |
| Overvoltage protection | 50 V continuous; 200 V peak (10msec) |
| Typical power consumption (max.) | 4 W, USB powered (2 USB cables) |
| | |

SIRIUSm 3xACC, 1xACC+

| Analogue inputs | 4 ch voltage, IEPE, current (with ext. Shunt) |
|----------------------------------|---|
| | same as SIRIUSm 4xACC, but with additional counters |
| Digital Inputs | 1 counter/3 digital inputs, fully synchronized with analogue data |
| Input level compatibility | CMOS, LVTTL |
| Input protection | ±25 V continuous |
| Digital output | 1 ch open collector, max. 100 mA/30 V |
| Typical power consumption (max.) | 4 W, USB powered (2 USB cables) |
| | Digital Inputs Input level compatibility Input protection |

SIRIUS<mark>i</mark> 8xACC

| SIRI | USie | EtherCAT. |
|------|-------|------------------|
| PINI | U SIC | Ether CAT |

| 4 | <u>k</u> ., | 1 | 2 | 16 | | | |
|---|-------------|---|---|---------|----------|---|---|
| | Ô | ٢ | ģ | <u></u> | <u>ģ</u> | ģ | ġ |
| - | | | | | | | - |

| Analogue inputs | 8 ch voltage, IEPE, current (with ext. Shunt) |
|-----------------------------------|--|
| ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec • 🚓 version; 20 kS/sec Ethercat version |
| DUALCOREADC® Ranges (Low range) | ±10 V (500 mV), ±500 mV (not available) |
| Dynamic Range@10kS (DUALCOREADC*) | 140 dB (160 dB) |
| Input coupling | DC, AC 0.1 Hz, 1 Hz (3, 10 Hz SW) |
| Input impedance | 1 M Ω in parallel with 0.4nF |
| IEPE mode | Exc.: 2, 4, 8, 12, 16 or 20 mA; Sensor detection (Short: <4 V; Open: > 19 V) |
| TEDS | supported in IEPE mode |
| Overvoltage protection | 50 V continuous; 200 V peak (10msec) |
| Typical power consumption (max.) | 8 W (15 W) |

| SIRIUS <mark>i</mark> 6xACC, 2xACC+ | SIRIUS <mark>ie</mark> | Ether CAT |
|-------------------------------------|------------------------|------------------|
|-------------------------------------|------------------------|------------------|

Isolated version i

| Analogue inputs | 8 ch voltage, IEPE, current (with ext. Shunt) |
|----------------------------------|---|
| | same as SIRIUSi 8xACC, but with additional counters |
| Digital inputs | 2 counter/6 digital inputs, fully synchronized with analogue data |
| Input level compatibility | CMOS, LVTTL |
| Input protection | ±25 V continuous |
| Digital output | 2 ch open collector, max. 100mA/30 V |
| Typical power consumption (max.) | 8 W (15 W) |
| | |

Differential version

Rack version r

(X

Fanless version **f**

SIRIUS®

ther CAT EtherCAT® version e

SIRIUS[®] HIGH DYNAMIC DUALCOREADC[®] - 2x 24 Bit, 200 kS/s

| IRIUS <mark>i</mark> 8xCHG | SIRIUSie EtherCAT. | |
|------------------------------------|---|---|
| | Analogue Inputs | 8 ch voltage, IEPE, charge, current (with ext. Shunt) |
| | ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| | Sampling rate | Simultaneous 200 kS/sec ← version; 20 kS/sec Ethercat version |
| | Charge mode ranges (low range) | ±100,000 pC (5,000 pC), ±10,000 pC (500 pC) |
| | DUALCOREADC® Ranges (Low range) | ±10 V (500 mV), ±500 mV (not available) |
| | Dynamic Range@10kS (DUALCOREADC®) | 140 dB (160 dB) |
| | Input coupling | DC, AC (0.1 Hz, 1 Hz, 10 Hz or 100 Hz) |
| | Input impedance | $1\text{M}\Omega$ in parallel with 0.4nF |
| | IEPE mode | 4 or 8 or 12 mA excitation; Sensor detection (Short: <4 V; Open: > 19 V) |
| | TEDS | supported in IEPE mode |
| | Overvoltage protection | 50 V continuous; 200 V peak (10 msec) |
| | Typical power consumption (max.) | 10 W (18 W) |
| IRIUS i 6xCHG, 2xCHG+ | SIRIUSie Ethercat | |
| IRIUS <mark>i</mark> 6xCHG, 2xCHG+ | SIRIUS <mark>ie</mark> Ether CAT | |
| RIUS i 6xCHG, 2xCHG+ | | 8 ch voltage, IEPE, charge, current (with ext. Shunt) |
| | SIRIUSie EtherCAT | |
| RIUS 6xCHG, 2xCHG+ | SIRIUSie EtherCAT | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSi 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data |
| | SIRIUSIe EtherCAT. Analogue inputs Digital Inputs | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSI 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL |
| | SIRIUSIE EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSI 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL |
| | SIRIUSIE EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSi 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 2 ch open collector, max. 100 mA / 30 V |
| - | SIRIUSie EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection Digital output | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSi 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 2 ch open collector, max. 100 mA / 30 V |
| | SIRIUSie EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection Digital output Typical power consumption (max.) | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSI 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 2 ch open collector, max. 100 mA / 30 V 10 W (18 W) |
| | SIRIUSie EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection Digital output Typical power consumption (max.) SIRIUSie EtherCATT Analogue inputs | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSI 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 2 ch open collector, max. 100 mA / 30 V 10 W (18 W) |
| | SIRIUSie EtherCATT Analogue inputs Digital Inputs Input level compatibility Input protection Digital output Typical power consumption (max.) SIRIUSie EtherCATT Analogue inputs ADC type | 8 ch voltage, IEPE, charge, current (with ext. Shunt) same as SIRIUSI 8xCHG, but with additional counters 2 counter/6 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 2 ch open collector, max. 100 mA / 30 V 10 W (18 W) 8 ch voltage, current (with ext. Shunt) |



SIRIUS<mark>i</mark> 8xLV

SIRIUSie Ethercat.

Dynamic Range@10kS (DUALCOREADC®) 142 dB (158 dB)

Typical power consumption (max.) 8 W

Input coupling DC

Input impedance 10 MΩ in parallel 2pF

Overvoltage protection In+ to In-: 1.8 kV RMS, Inx to GND: 1.4 kV RMS



| Analogue inputs | 8 ch voltage, full bridge strain, current (with ext. Shunt) | |
|---|--|--|
| ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter | |
| Sampling rate | Simultaneous 200 kS/sec ↔ version; 20 kS/sec Ether cat → version | |
| DUALCOREADC [®] Ranges (Low range) | ± 200 V (10 V), ± 10 V (500 mV), ± 1 V (50 mV), ± 100 mV (5 mV) | |
| Br ranges @ 10Vexc (Low Range) | 1000(50) mV/V, 100(5) mV/V, 10(0.5) mV/V | |
| Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) | |
| Input coupling | DC, AC 1 Hz (3 Hz, 10 Hz per SW) | |
| Input impedance (100 V range) | 10 (1) $M\Omega$ between IN+ or In- and GND | |
| Bridge modes | full bridge | |
| TEDS | Standard + DSI® adapters, only on DSUB 9 version | |
| Sensor Excitation | 2 to 30 V bipolar / 0 to 24 V unipolar, sw programmable (16 bit DAC), max 0.2 A / 2 W | |
| Overvoltage protection | 200 V and 20 V range: 300 V; all other ranges: 100 V (250 V peak for 10 msec | |
| Typical power consumption (max.) | 10 W (25 W) | |

SIRIUS[®] HIGH DYNAMIC DUALCOREADC[®] - 2x 24 Bit, 200 kS/s

| SIRIUS <mark>i</mark> 4xHV, 4xLV | SIRIUSie EtherCAT | |
|---------------------------------------|------------------------------------|--|
| | ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| | Sampling rate | Simultaneous 200 kS/sec ← version; 20 kS/sec Etherca → version |
| | Typical power consumption (max.) | 10 W (18 W) |
| | High voltage analogue inputs | 4 ch voltage |
| | DUALCOREADC® Ranges (Low range) | ±1200 V (50 V), ±50 V (not available) |
| · · · · · · · · · · · · · · · · · · · | Dynamic Range@10kS (DUALCOREADC®) | 142 dB (158 dB) |
| | Input coupling | DC |
| | Input impedance | 10 M Ω in parallel 2pF |
| | Overvoltage protection | In+ to In-: 1.8 kV RMS, Inx to GND: 1.4 kV RMS |
| | Low voltage analogue inputs | 4 ch voltage, full bridge strain, current (with ext. Shunt) |
| | DUALCOREADC® Ranges (Low range) | ± 200 V (10 V), ± 10 V (500 mV), ± 1 V (50 mV), ± 100 mV (5 mV) |
| | Bridge ranges @ 10Vexc (Low Range) | 2mV/V1000mV/V free programmable with Dual Core |
| | Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) |
| | Input coupling | DC, AC 1 Hz (3 Hz, 10 Hz per SW) |
| | Input impedance (100 V range) | 10 (1) $M\Omega$ between IN+ or In- and GND |
| | Bridge modes | Full bridge |
| | TEDS | Standard + DSI® adapters, only on DSUB 9 version |
| | Sensor Excitation | 2 to 30 V bipolar / 0 to 24 V unipolar, sw programmable (16 bit DAC), max 0.2 A / 2 W |
| | Overvoltage protection | 200 V and 20 V range: 300 V; all other ranges: 100 V (250 V peak for 10 msec) |

SIRIUS<mark>i</mark> 8xLV+

SIRIUSie Ethercat

| - | Analogue inputs | 8 ch voltage, full bridge strain, current (with ext. Shunt) |
|---------------------|--|--|
| | | same as SIRIUSi 8xLV, but with additional counters |
| | Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | Input level compatibility | CMOS, LVTTL |
| | Input protection | ±25 V continuous |
| | Digital output | 8 ch open collector, max. 100m A/30 V |
|]E ↓ IIII DSI 🔤 🐼 * | Typical power consumption (max.) | 10 W (25 W) |
| | * Fanless operation only for BNC or Banana version (with | out excitation) |

SIRIUS<mark>i</mark> 8xMULTI

Analogue in, Analogue out and Counter at the same tim

Fanless version f

| | Analogue Inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), potentiometer |
|---------------|---|---|
| | ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| | Sampling rate | Simultaneous 200 kS/sec |
| | DUALCOREADC [®] Ranges (Low Range) | \pm 10V (500 mV), \pm 1V (50 mV), \pm 100mV (5 mV), \pm 50mV (2.5 mV) |
| | Br ranges @ 10 Vexc (Low Range) | 1000(50)mV/V, 100(5)mV/V, 10(0.5)mV/V, 5(0.25)mV/V |
| | Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) |
| | Input coupling | DC |
| | Input impedance | 10 ΜΩ |
| | Bridge modes | Full/Half/Quarter Br 120/350 Ω 3-wire; internal bridge completion |
| - | Internal shunt resistor | 59.88 k Ω , bipolar to Exc+ or Exc- (others on request) |
| | TEDS | supported |
| | Excitation Voltage | 0 to 12 VDC software programmable (16 Bit DAC), max 44 mA |
| | Overvoltage protection | In+ to In-: 50V continuous; 200 V peak (10msec) |
| | Typical power consumption (max.) | 15 W (25 W) |
| | Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | Analogue outputs | 8 ch 24 bit sigma delta 200 kHz, ± 10 V |
| € Ĵ≻ IIII DSI | Typical power consumption (max.) | 15 W (25 W) |



EtherCAT® version e







SIRIUS® HIGH DYNAMIC DUALCOREADC® – 2x 24 Bit, 200 kS/s

| SIRIUS <mark>i</mark> 8xSTG | SIRIUSie EtherCATT | |
|-----------------------------|-----------------------------------|---|
| | Analogue Inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer |
| | ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| | Sampling rate | Simultaneous 200 kS/sec •< version; 20 kS/sec EtherCATT version |
| | DUALCOREADC® Ranges (Low Range) | ±50 V (2.5 V), ±10 V (500 mV), $\pm1V$ (50 mV), ±100 mV (5 mV) |
| | Br ranges @ 10 Vexc (Low Range) | 1000(50) mV/V, 100(5) mV/V, 10(0.5) mV/V |
| | Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) |
| P | Input coupling | DC, AC 1 Hz (3 Hz, 10 Hz per SW) |
| | Input impedance | 1 M Ω between IN+ and In- for 50 V Range ; all other Ranges $>$ 1 G Ω |
| | Bridge modes | Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completion |
| \$ | Internal shunt resistor | 59.88 k Ω and 175 k Ω , bipolar to Exc+ or Exc- (others on request) |
| | TEDS | supported on all except SIRIUSi 8xSTG-L2B7f DSI® adapters only fit on 9pin DSUB |
| | Excitation Voltage | 0 to 20 VDC software programmable (16 Bit DAC), max 0.1 A / 0.8 W |
| | Excitation Current | 0 to 60 mA software programmable (16 Bit DAC), max. 500 mW |
| | Overvoltage protection | In+ to In-: 50 V Range: 300 V; all other Ranges: 50 V (200 V peak for 10 mse |
| | Digital inputs | SIRIUSi 8xSTG: none SIRIUSi 8xSTG-L2B10f: on 10pin LEMO connector one pin is used for digital I/0 -> total 8 dig I/0 (open collector) |
| | Typical power consumption (max.) | 15 W (25 W) |

| SIRIUS <mark>i</mark> 8xSTG+ | SIRIUSie EtherCAT | |
|----------------------------------|---------------------------|--|
| P | Analogue inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer |
| FINITE & D & A D & A D & A D & A | | same as SIRIUSi 8xSTG, but with additional counters |
| | Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| - | Input level compatibility | CMOS, LVTTL |
| | Input protection | ±25 V continuous |
| ∃€ 🕁 IIII DSI Etter cat.→ | Digital output | 8 ch open collector, max. 100 mA/30 V |

| SIRIUS <mark>i</mark> 6xSTG, 2xSTG+ | SIRIUSie EtherCAT. | |
|-------------------------------------|---------------------------|--|
| | Analogue inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer |
| P | | same as SIRIUSi 8xSTG, but with 2 additional counters |
| Frank the treater the treater the | Digital Inputs | 2 counter/6 digital inputs, fully synchronized with analogue data |
| | Input level compatibility | CMOS, LVTTL |
| - | Input protection | ±25 V continuous |
| | Digital output | 2 ch open collector, max. 100 mA/30 V |

INSTRUMENTS

SIRIUS[®] HIGH DYNAMIC DUALCOREADC[®] - 2x 24 Bit, 200 kS/s

| SIRIUS <mark>i</mark> 8xSTGM | SIRIUSie EtherCATT | |
|------------------------------|---|---|
| | Analogue Inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), potentiometer |
| | ADC type | 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter |
| | Sampling rate | Simultaneous 200 kS/sec • 🚓 version; 20 kS/sec Ether CATT 🕈 version |
| | DUALCOREADC [®] Ranges (Low Range) | $\pm 10V (500 \text{ mV}), \pm 1V (50 \text{ mV}), \pm 100 \text{mV} (5 \text{ mV}), \pm 10 \text{mV} (0.5 \text{ mV})$ |
| | Br ranges @ 10 Vexc (Low Range) | 1000(50)mV/V, 100(5)mV/V, 10(0.5)mV/V, 1(0.05)mV/V |
| | Dynamic Range@10kS (DUALCOREADC®) | 137 dB (152 dB) |
| | Input coupling | DC |
| > | Input impedance | 10 ΜΩ |
| | Bridge modes | Full/Half/Quarter Br 120/350 Ω 3-wire; internal bridge completion |
| | Internal shunt resistor | 100 k Ω , bipolar to Exc+ or Exc- (others on request) |
| | TEDS | supported DSI® adapters only fit on 9pin DSUB |
| | Excitation Voltage | 0 to 15 VDC software programmable (16 Bit DAC), max 44 mA |
| | Overvoltage protection | In+ to In-: 50V continuous; 200 V peak (10msec) |
|] [] - DSI 👯 🛧 | Typical power consumption (max.) | 11 W (20 W) |

| SIRIUS <mark>i</mark> 8xSTGM+ | SIRIUSie EtherCATT | |
|-------------------------------|----------------------------------|--|
| | | |
| | Analogue inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), potentiometer |
| | | same as SIRIUSi 8xSTGM, but with additional counters |
| | Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | Input level compatibility | CMOS, LVTTL |
| | Input protection | ±25 V continuous |
| | Digital output | 8 ch open collector, max. 100mA/30 V |
| | Typical power consumption (max.) | 11 W (20 W) |
| | | |

| SIRIUS <mark>i</mark> 8xSTGM-DB | | |
|---------------------------------|----------------------------------|--|
| | | |
| | Analogue inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), potentiometer |
| | | same as STGM, but with additional digital I/O |
| | Digital Inputs | 8 counter/24 digital inputs on DSUB 37pin connectors, fully synchronize with analogue data |
| | Digital outputs | 8 ch on DSUB 25pin connector, high side switch to supply voltage, max. 150mA per ch to directly connect relais, short circuit protected |
| | Typical power consumption (max.) | 12 W (26 W) |



<u>SIRIUS</u>®





SIRIUS[®] HIGH SPEED – 1 MS/s, alias free, 16 Bit

This series combines high bandwidth and alias free acquisition with 16 Bit of up to 1 MS/sec acquisition rate. The analogue anti-aliasing filter (100 kHz, 5th order, Bessel) is combined with a free programmable digital IIR filter block inside the FGPA. For bandwidth requirement of up to 500 kHz the complete filter chain is bypassed.

Combustion analyser

- Transient recorder
- ▶ 1 MS/s sampling rate
- ► Power applications

SIRIUS<mark>i</mark>-HS 8xACC

| | Analogue inputs | 8 ch voltage, IEPE, current (with ext. Shunt) |
|---|--|---|
| | ADC type | 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz) |
| | | Simultaneous 1 MS/s |
| * | Ranges | ±10 V, ±5 V, ±1 V, ±0.2 V |
| | Typ. SNR @ 100 kHz | 89 dB |
| <u>େ</u> ତ ତ ତ ତ ତ ତ ତ | Input coupling | |
| - | Input impedance | 1 ΜΩ |
| | IEPE mode | 4 or 8 mA excitation; Sensor detection (Short: <4 V; Open: > 19 V) |
| | TEDS | Supported in IEPE mode |
| | Overvoltage protection | 50 V continuous; 200 V peak (10 msec) |
| 3€ ⊅ ∭ | Typical power consumption (max.) | 15 W (22 W) |
| SIRIUS <mark>i</mark> -HS 6xACC, 2xACC+ | | |
| | Analogue inputs | 8 ch voltage, IEPE, current (with ext. Shunt) |
| | | same as SIRIUSI-HS 8xACC, but with additional counters |
| | Digital Inputs | |
| | Input level compatibility | |
| - | Input protection | |
| | input protection | ±25 V continuous |
| | | \pm 25 V continuous 2 ch open collector, max. 100 mA / 30 V |
| 38 ⊅ 📖 | | 2 ch open collector, max. 100 mA / 30 V |
| BE D | Digital output | 2 ch open collector, max. 100 mA / 30 V |
| BE D | Digital output | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) |
| IRIUSI-HS 8xCHG | Digital output Typical power consumption (max.) Analogue inputs | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) |
| IRIUSI-HS 8xCHG | Digital output Typical power consumption (max.) Analogue inputs ADC type | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) |
| IRIUSI-HS 8xCHG | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz |
| | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V |
| SIRIUSI-HS 8xCHG | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate Ranges | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V 89 dB |
| | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate Ranges Typ. SNR @ 100 kHz | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V 89 dB DC or AC (1 Hz) |
| | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate Ranges Typ. SNR @ 100 kHz Input coupling | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V 89 dB DC or AC (1 Hz) 1 MΩ |
| | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate Ranges Typ. SNR @ 100 kHz Input coupling Input impedance IEPE mode | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V 89 dB DC or AC (1 Hz) 1 MΩ |
| SIRIUSI-HS 8xCHG | Digital output Typical power consumption (max.) Analogue inputs ADC type Sampling rate Ranges Typ. SNR @ 100 kHz Input coupling Input impedance EEPE mode TEDS | 2 ch open collector, max. 100 mA / 30 V 15 W (22 W) 8 ch voltage, IEPE, charge, current (with ext. Shunt) 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (500 kHz Simultaneous 1 MS/s ±10, ±5, ±2, ±1, ±0.5, ±0.2, ±0.1 V 89 dB DC or AC (1 Hz) 1 MΩ 4 or 8 or 12 mA excitation; Sensor detection (Short: <4 V; Open: > 19 V) |

SIRIUSi-HS 6xCHG, 2xCHG+

| | Analogue inputs | 8 ch voltage, IEPE, charge, current (with ext. Shunt) |
|-----------------------|----------------------------------|---|
| | | same as SIRIUSi-HS 8xCHG, but with additional counters |
| | Digital Inputs | 2 counter/6 digital inputs, fully synchronized with analogue data |
| - <u> </u> | Input level compatibility | CMOS, LVTTL |
| | Input protection | ±25 V continuous |
| and the second second | Digital output | 2 ch open collector, max. 100 mA/30 V |
| 3€ ⊅ | Typical power consumption (max.) | 10 W (18 W) |
| | | |

SIRIUS[®] HIGH SPEED – 1 MS/s, alias free, 16 Bit

| SIRIUS <mark>i</mark> -HS 8xHV | | |
|---------------------------------|---|--|
| | | |
| | Analogue inputs | 8 ch voltage |
| | | 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (2 MHz) |
| | | Simultaneous 1 MS/s |
| | | ± 1600 V, ± 800 V, ± 400 V, ± 200 V, ± 100 V, ± 50 V, ± 20 V |
| | Typ. SNR @ 100 kHz | |
| > | Input coupling | |
| | | 10 M Ω in parallel 2pF |
| 38 🛄 🛞 | Typical power consumption (max.) | In+ to In-: 1.8 kV RMS, Inx to GND: 1.4 kV RMS 8 W |
| | | |
| SIRIUS <mark>i</mark> -HS 8xLV | | |
| | | 8 ch voltage, full bridge strain, current (with ext. Shunt) |
| | | 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass |
| | Sampling rate | Simultaneous 1 MS/s |
| | Ranges | $\pm 100 \text{ V}, \pm 50 \text{ V}, \pm 20 \text{ V}, \pm 10 \text{ V}, \pm 5 \text{ V}, \pm 2 \text{ V}, \pm 1 \text{ V}, \pm 0.5 \text{ V}, \pm 0.2 \text{ V}, \pm 0.1 \text{ V}, \pm 0.05 \text{ V}$ |
| | Bridge ranges @ 10 Veve | 1000 mV/V, 100 mV/V, 10 mV/V |
| -000000000 | Input counting | DC, AC 1 Hz (3 Hz, 10 Hz per SW) |
| | | 10 (1) M Ω between IN+ or In- and GND |
| | Bridge modes | |
| | | Standard + DSI [®] adapters, only on DSUB 9 version |
| | | 2 to 30 V bipolar / 0 to 24 V unipolar, sw programmable (16 bit DAC), max 0.2 A / 2 W |
| | Overvoltage protection | 100 V Range: 300 V; All other Ranges: 100V (200 V peak for 10 msec) |
|]€ ↓ III DSI 🛞 * | Typical power consumption (max.) | 10 W (25 W) |
| | * Fanless operation only for BNC or Banana version (wit | hout excitation) |
| SIRIUS <mark>i</mark> -HS 8xLV+ | | |
| - | Analogue inputs | 8 ch voltage, full bridge strain, current (with ext. Shunt) |
| | | same as SIRIUSi-HS 8xLV, but with additional counters |
| | | · · · · · · · · · · · · · · · · · · · |
| | Digital Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | Input level compatibility | 8 counter/24 digital inputs, fully synchronized with analogue data |
| | Input level compatibility Input protection | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous |
| | Input level compatibility Input protection Digital output | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V |
| E → DSI 80080020 | Input level compatibility Input protection | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) |
| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.4 V, ±0.2 V, |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexcc Dynamic Range@10kS | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (wit Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges 87 dB |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (wit Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 v, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 S00 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN-Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completio |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN- Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completio 59.88 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GQ / Range >=10 V: 1 MΩ between IN+ and IN-Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completion 59.88 KQ and 175 kQ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS Excitation voltage | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 500 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN-Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completio 59.88 KΩ and 175 KΩ, bipolar to Exc+ or Exc- (others on request) Supported; DSI® adapters only fit on 9pin DSUB 0, 1, 2.5, 5, 10, 15 and 20 VDC software programmable (16 Bit DAC) |
| | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt) resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MI Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, 50 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: > 1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN- Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge com, 59.88 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) |
| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS Excitation voltage | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.6 S00 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN- Full/Half/Quarter Br 120/350 Ω -wire or 4-wire; internal bridge completities 59.8 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB 0, 1, 2.5, 5, 10, 15 and 20 VDC software programmable [16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) 0.1, 2.5, 50 V (200 Vpeak for 10 msec) / Range >=10 V: 300 V cont. |
| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS Excitation voltage Excitation current Overvoltage protection Typical power consumption (max.) | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.0 500 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN- Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completion 59.88 KΩ and 175 kQ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB 0, 1, 2.5, 5, 10, 15 and 20 VDC software programmable (16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) 0.1, 1, 2, 50 V (200 Vpeak for 10 msec) / Range >=10 V: 300 V cont. 15 W (25 W) |
| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Bar ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS Excitation voltage Excitation current Overvoltage protection | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s 50 v, ±20 v, ±10 v, ±5 v, ±2 v, ±1 v, ±0.4 v, ±0.2 v, ±0.1 v, ±0.04 v, ±0.02 500 mV/v to 2 mV/v in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN-Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completio 59.88 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB 0, 1, 2.5, 5, 10, 15 and 20 VDC software programmable (16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) Range <10 V: 50 V (200 Vpeak for 10 msec) / Range >=10 V: 300 V cont. 15 W (25 W) |
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| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with Analogue Inputs ADC type Sampling rate Bar ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor Excitation voltage Excitation current Overvoltage protection Typical power consumption (max.) | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 S00 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GΩ / Range >=10 V: 1 MΩ between IN+ and IN- Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completio 59.8 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB 0, 1, 2, 5, 10, 15 and 20 VDC software programmable (16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) Range <10 V: 50 V (200 Vpeak for 10 msec) / Range >=10 V: 300 V cont. 15 W (25 W) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer same as SIRIUSi-HS 8xSTG, but with additional counters 8 counter/24 digital inputs, fully synchronized with analogue data |
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| SIRIUSI-HS 8xSTG | Input level compatibility Input protection Digital output Typical power consumption (max.) * Fanless operation only for BNC or Banana version (with ADC type Sampling rate Ranges Br ranges @ 10 Vexc Dynamic Range@10kS Input coupling Input impedance Bridge modes Internal shunt resistor TEDS Excitation voltage Excitation voltage Excitation current Overvoltage protection Typical power consumption (max.) | 8 counter/24 digital inputs, fully synchronized with analogue data CMOS, LVTTL ±25 V continuous 8 ch open collector, max. 100 mA/30 V 10 W (25 W) hout excitation) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer 16 bit SAR with 100 kHz 5th order analogue AAF filter or bypass (1 MHz) Simultaneous 1 MS/s ±50 V, ±20 V, ±10 V, ±5 V, ±2 V, ±1 V, ±0.4 V, ±0.2 V, ±0.1 V, ±0.04 V, ±0.02 S00 mV/V to 2 mV/V in 8 ranges 87 dB DC, AC 1 Hz (3 Hz, 10 Hz per SW) Range <10 V: >1 GQ / Range >=10 V: 1 MΩ between IN+ and IN-Full/Half/Quarter Br 120/350 Ω 3-wire or 4-wire; internal bridge completion 59.88 kΩ and 175 kΩ, bipolar to Exc+ or Exc- (others on request) Supported; DSI* adapters only fit on 9pin DSUB 0, 1, 2, 5, 10, 15 and 20 VDC software programmable (16 Bit DAC) 0.1, 1, 2, 5, 10, 20 and 60 mA software programmable 16 Bit DAC) Range <10 V: 50 V (200 Vpeak for 10 msec) / Range >=10 V: 300 V cont. 15 W (25 W) 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt), resistance, temperature, potentiometer same as SIRIUSi-HS 8xSTG, but with additional counters 8 counter/24 digital inputs, fully synchronized with analogue data |

Rack version r

 (\mathscr{A})

Fanless version **f**

Eth<u>er</u>

EtherCAT® version e

Isolated version i

 \supset

Differential version

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SIRIUS[®] HIGH DENSITY – 16 CHANNELS / SLICE

SIRIUS<mark>i</mark>-HD 16xACC



| SIRIUSie-HD EtherCAT | |
|----------------------------------|--|
| Analogue inputs | 16 ch voltage, IEPE, current (with ext. Shunt) |
| ADC type | 24 bit delta-sigma with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec |
| Ranges | ± 10 V, ± 5 V, ± 1 V, ± 200 mV |
| Dynamic Range@10kS | 135 dB |
| Input coupling | DC, AC 0.1 Hz, 1 Hz (3 Hz, 10 Hz per SW) |
| Input impedance | 1 MΩ in parallel with 0.4nF |
| IEPE mode | 4, 8 or 12 mA excitation; Sensor detection (Short: <4 V; Open: > 19 V) |
| TEDS | supported in IEPE mode |
| Overvoltage protection | 50 V continuous; 200 V peak (10 msec) |
| Typical power consumption (max.) | 11 W (22 W) |

SIRIUSI-HD 16xLV

SIRIUSie-HD EtherCAT



| Analogue inputs | 16 ch voltage, full bridge strain, current (with ext. Shunt) |
|----------------------------------|--|
| ADC type | 24 bit delta-sigma with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec •< version; 10 kS/sec EtherCATT version |
| Ranges | ± 100 V, ± 10 V, ± 1 V, ± 100 mV |
| Bridge ranges @ 10 Vexc | 1000 mV/V, 100 mV/V, 10 mV/V |
| Dynamic Range@10kS | 137 dB |
| Input coupling | DC |
| Input impedance | $1M\Omega$ for 100 V range, all other ranges 10 $M\Omega$ |
| Bridge mode | Full bridge |
| Excitation level unipolar | 0 to 24 VDC software programmable (16 Bit DAC), max 0.2 A / 2 W |
| Excitation level bipolar | 2 to 30 V software programmable (16 Bit DAC), max 0.2 A / 2 W |
| TEDS | Standard + DSI® adapters, only on DSUB 9 version |
| Overvoltage protection | 100 V Range: 300 V; All other Ranges: 100 V (250 V peak for 10 msec) |
| Typical power consumption (max.) | 11 W (22 W) |
| Available front connectors | DB9, BNC (others on request) |

SIRIUSI-HD 16xSTGS

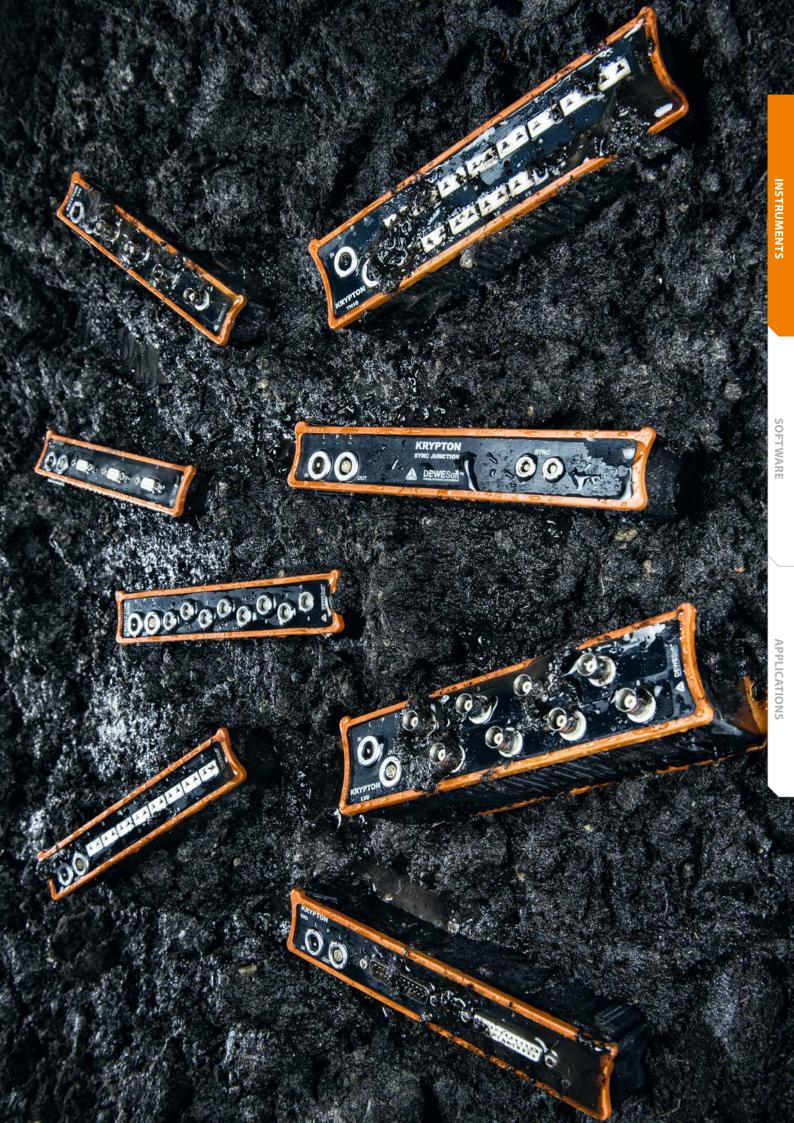
SIRIUSie-HD EtherCAT



| Analogue inputs | 16 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt) |
|----------------------------------|--|
| ADC type | 24 bit delta-sigma with anti-aliasing filter |
| Sampling rate | Simultaneous 200 kS/sec •< version; 10 kS/sec EtherCAT-+ version |
| Ranges | ±10 V, ±1 V, ±100 mV, ±10 mV |
| Bridge ranges @ 10 Vexc | 1000 mV/V, 100 mV/V, 10 mV/V, 1 mV/V |
| Dynamic Range@10kS | 137 dB |
| Input coupling | DC |
| Input impedance | 10 ΜΩ |
| Bridge modes | Full/Half/Quarter Bridge 120/350 Ω 3-wire; internal bridge completion |
| Internal shunt resistor | 100 kΩ, bipolar to Exc+ or Exc- (others on request) |
| Excitation voltage | 0 to 12 V_{DC} software programmable (16 bit DAC), max 44 mA |
| TEDS | Supported, DSI® adapters only fit on 9pin DSUB |
| Overvoltage protection | IN+ to IN-: 50 V continuous; 200 V peak (10 msec) |
| Typical power consumption (max.) | 11 W (22 W) |
| Available front connectors | DB9, L1B10f (others on request) |

APPLICATIONS

INSTRUMENTS



EXTREME LINE

SIRIUS®

USB or EtherCAT[®] connection for flexible system configuration

200 kS/sec

-40°C .. 60°C operating temperature

00

100 g shock rating



SIRIUSiwe 6xSTGM, 2xSTGM+

SIRIUSwe-HD 16xSTGS

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000

| Analogue inputs | 8 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt) | 16 ch voltage, full/half/quarter bridge strain, current (with ext. Shunt) | |
|--------------------------|---|--|--|
| ADC type | 2x 24 bit delta-sigma DUALCOREADC® with anti-aliasing filter | 24 bit delta-sigma with anti-aliasing filter | |
| Sampling rate on USB | Simultaneous 200 kS/sec | Simultaneous 200 kS/sec | |
| mpling rate on EtherCAT® | Simultaneous 20 kS/sec | Simultaneous 10 kS/sec | |
| Ranges | ±10 V, ±1 V, ±100 mV, ±10 mV | ±10 V, ±1 V, ±100 mV, ±10 mV | |
| Bridge ranges | 2mV/V 1000mV/V, free programmable | 2mV/V 1000mV/V, free programmable | |
| Dynamic Range@10kS | 152 dB | 137 dB | |
| Input coupling | DC | DC | |
| Input impedance | 10 ΜΩ | 10 ΜΩ | |
| Bridge modes | Full/Half/Quarter Br 120/350 Ω 3-wire; internal bridge completion | | |
| Internal shunt resistor | 100 k $\Omega,$ bipolar to Exc+ or Exc- (others on request) | | |
| Excitation voltage | 0 to 15 VDC software programmable (16 bit DAC), max 44 mA | 0 to 12 VDC software programmable (16 bit DAC), max 44 mA | |
| TEDS | Supported, DSI® adapters | Supported, DSI® adapters | |
| Overvoltage protection | IN+ to IN-: 50 V continuous; 200 V peak (10 msec) | IN+ to IN-: 50 V continuous; 200 V peak (10 msec) | |
| Counter | 2 x Supercounter® (6 Digital In , 2 Dgital out) | None | |
| Input configuration | 1000 V channel-channel (analogue_x and counter_x channel are not isolated to each other) 1000 V channel-ground | Differential | |
| Power supply | 9 36 V | 9 36 V | |
| ower consumption (max.) | 11 W (20 W) | 14 W (24 W) | |
| Input connectors | Al: DSUB 9, CNT: LEMO 7pin female | DSUB 9 | |
| Operating Temperature | -40°C 60°C | -40°C 50°C | |

282 x 135 x 85 mm

SBOXwe rugged computer

| CPU | Intel Core i3, 1.7GHz, 3 MB cache |
|------------------------------|---|
| RAM | 4GB |
| Storage | 250 GB mSATA SSD |
| USB | 5x USB 2.0 (Snap-In) |
| Ethernet | 2x GLAN (Snap-In), 1x WLAN |
| EtherCAT® | 100Mbps Full Duplex, L1T8f (Lemo) |
| Video | DVI-D |
| Synchronisation | 1x SIRIUS® SYNC on LOOB4f |
| GPS | Optional 10Hz or 100Hz or 100Hz + RTK |
| GPS display | External on DSUB 9 connector with remote power on |
| Power out | Switched supply on L1K2f (Lemo) |
| Power supply | 936V |
| Typical power consumption | 12 W |
| Operating Temperature | -40°C 50°C |
| Dimension (W x D x H) | 282 x 135 x 70 mm |

SOFTWARE

S Samplin

Typ. power of

INSTRUMENTS

Common Environmental Specifications

Dimensions (W x D x H) 282 x 135 x 70 mm

Protection IP67 Shock 60g @ 6ms 50x, half sine, all axes PASS 100g @ 4ms 50x, half sine, all axes PASS Vibration Random 11 g RMS, all axes, 18 h total 24 Hz - 0.03 g^2/Hz 60 Hz - 0.4 g^2/Hz 100 Hz - 0.4 g^2/Hz

240 Hz - 0.08 g^2/Hz 2 kHz - 0.08 g^2/Hz

INSTRUMENTS KRYPTON®

the EtherCAT[®] modules for harshest environments

-40°C .. 85°C operating temperature



| | KRYPTONi 8x TH, 16x TH | KRYPTON 8xRTD | KRYPTON 3xSTG, 6xSTG | KRYPTONi 4x LV, 8x LV |
|----------------------------------|--|--|---|---|
| | | | | |
| ANALOGUE INPUTS | | | | |
| Input channels | 8 (16) isolated universal thermocouple and voltage | 8 differential universal PTx temperature, resistance and voltage | 3 (6) differential voltage or strain | 4 or 8 isolated voltage |
| Input signals | TC types: K, J, T, R, S, N, E, C, U, B / Voltage: 1 V and 100 mV | PT-types: PT100, PT200, PT500, PT1000, PT200, PT2000 Resistance: 500 Ω and 10 $k\Omega$ Voltage: 1 V and 100 mV | Voltage: 10 V; 1 V, 100 mV or 10 mV; Strain: 2 1000 mV/V programmable; 1/1; 1/2 and 1/4 Bridge; Excitation: 1 15V programmable, max. 0.4 W/channel | +/- 100 V |
| Input connector | mini Thermocouple connector (cu) | LEMO OB 6-pin | DSUB 9pin | BNC |
| Sampling rate | Maximum 100 Hz per channel (software selectable) | Maximum 100 Hz per channel (software selectable) | Maximum 20 kHz per channel (software selectable) | 10 kHz per channel (software selectable) |
| ADC type | 24 bit sigma delta | 24 bit sigma delta | 24 bit sigma delta | 24 bit sigma delta |
| Input impedance | >100 MΩ | >10 MΩ | 10 MΩ | 1 ΜΩ |
| lsolation voltage peak | 1000 V channel/ground & channel/channel | 1000 V channel/ground & channel/channel | - | 1000 V channel/ground & channel/channel |
| Resolution | <0.001 deg. C | <0.001 deg. C | - | 0.01 mV |
| Accuracy | TC: $\pm 0.02\%$ of reading ± 0.5 °C $\pm 10 \mu$ V Voltage: $\pm 0.02\%$ of reading 10 μ V | Temperature: ±0.05°C Voltage: ±0.02% of reading ±10 μV | ±0.03% of reading ±0.02% of range ±0.1mV | ±0.03% ±5mV |
| Gain drift over temperature | typ. 3ppm/K (max. 10 ppm/K) | typ. 3ppm/K (max. 10 ppm/K) | typ. 10ppm/K (max. 40 ppm/K) | typ. 10ppm/K (max. 20 ppm) |
| Offset drift over temperature | 0.03 µV/K | 0.03 µV/K | typical 0.3 μ V/K + 5 ppm of range/K | 10 µV/K |
| GENERAL SPECS | | | | |
| Noise | 0.25 µVrms (=0.007°Crms@Type K)@10 S/s 0.7µVrms (=0.02°Crms@Type K)@100 S/s | 0.25 μVrms @ 10 S/s 0.7 μVrms @ 100 S/s | up to 100 dB | 0.7 mVrms |
| Interface | LEMO 1B Ethercat cable (single cable connection power + sync + data) | LEMO 1B Ethercat cable (single cable connection power + sync + data) | LEMO 1B Ethercat cable (single cable connection power + sync + data) | LEMO 1B Ethercat cable (single cable connection powe + sync + data) |
| Data rate | 100 Mbit bus speed | 100 Mbit bus speed | 100 Mbit bus speed | 100 Mbit bus speed |
| Power supply voltage | 6 to 50 V DC | 6 to 50 V DC | 6 to 50 V DC | 6 to 50 V DC |
| Power consumption | 3 W (8xTH), 4 Watt (16xTH) | 3 W | 3.5 W (3xSTG), 5 Watt (6xSTG) | 2.5 W (4xLV), 3 W (8xLV) |
| Dimensions | 200x50x30 mm (8xTH) / 200x50x45 mm (16xTH) | 200x50x30 mm | 200x50x30 mm (3xSTG) 200x50x45 mm (6xSTG) | 200x50x30 mm (4xLV) / 200x50x45 mm (8xLV) |
| Weight | Typically 650 g (8xTH) / Typically 900 g (16xTH) | Typically 900 g | Typically 650 g (8xTH) Typically 900 g (16xTH) | Typically 650 g (4xLV) / Typically 900 g (8xLV) |
| Environmental rating | IP67 | IP67 | IP67 | IP67 |
| Shock & Vibration Rating | > 100 g | > 100 g | > 100 g | > 100 g |
| | | | | |

INSTRUMENTS

| Input channels (isolated)168-CompatibilityCMOS Configuration-Input low levelUIN < 0.8 V-Input high levelUIN > 2.4 V-Input high current @ 5 V UIN<1.8 mJ-Propagation delay<1 µsec-Sampling rateMaximum 20 kHz per channel (software selectable)-Overvoltage protection40 V continuous (65 V peak)-Isolation voltage peak250 V channel/youruk & channel/ychannel-DidfAL OUTPUTSCompatibility-0pen collector with 10 kR pull-up to +5 VMaximum sink current-0 Open collector with 10 kR pull-up to +5 VMaximum sink current-0 Open collector with 10 kR pull-up to +5 VIsolation voltage peak-0 Open collector with 10 kR pull-up to +5 VMaximum switching voltage-0 Open collector with 10 kR pull-up to +5 VMaximum switching voltage-0 Open collector with 10 kR pull-up to +5 VInterfaceLEM0 18 Ether Source | | KRYPTONi 16xDI | KRYPTONi 8xDI 8xDO | KRYPTONi 16xDO |
|---|------------------------------|-------------------------|---|------------------------------|
| Input channels (isolated)168-CompatibilityCMOS Configuration-Input low levelUIN < 0.8 V-Input high levelUIN > 2.4 V-Input high current @ 5 V UIN<1.8 mJ-Propagation delay<1 µsec-Sampling rateMaximum 20 kHz per channel (software selectable)-Overvoltage protection40 V continuous (65 V peak)-Isolation voltage peak250 V channel/youruk & channel/ychannel-DidfAL OUTPUTSCompatibility-0pen collector with 10 kR pull-up to +5 VMaximum sink current-0 Open collector with 10 kR pull-up to +5 VMaximum sink current-0 Open collector with 10 kR pull-up to +5 VIsolation voltage peak-0 Open collector with 10 kR pull-up to +5 VMaximum switching voltage-0 Open collector with 10 kR pull-up to +5 VMaximum switching voltage-0 Open collector with 10 kR pull-up to +5 VInterfaceLEM0 18 Ether Source | | ····· | <u>.</u> | |
| CompatibilityCMOS Configuration-Input low levelUIN <0.8 V-Input low levelUIN > 2.4 V-Input high levelUIN > 2.4 V-Input high current @ 5 V UIN<1.8 mA-Propagation delay<1 µsec-Sampling rateMaximum 20 kHz per channel (software selectable)-Overvoltage protection40 V continuous (65 V pak)-Station voltage peak250 V channel/ground & channel/channel-DIGITAL OUTPUTS-816Compatibility-0pen collector with 10 k pull-up to +5 VMaximum sink current-150 mA (not protected)Maximum sink current-50 VIsolation voltage peak-50 VSolation voltage peak-50 VMaximum switching voltage-50 VPropagation delay-20 µsecInstrumt sink current-250 V channel to ground, no channel isolationGENERAL SPECS100 Mbit bus speed-Prover supply voltage6 to 50 V DCProver consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | DIGITAL INPUTS | | | |
| Input low level UIN < 0.8 V | Input channels (isolated) | 16 | 8 | - |
| Input high level UIN > 2.4 V - Input high current @ 5 V UIN <1.8 mA - Propagation delay <1 µsc - Sampling rate Maximum 20 kHz per channel (software selectable) - Overvoltage protection 40 V continuous (65 V peak) - Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS - - Input channels (isolated) - 8 16 Compatibility - 0pen collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum sink current - Propagation delay - Maximum sink current - 0pen collector with 10 kR pull-up to +5 V Maximum sink current - 00 Propagation delay - Maximum update rate - 200 y c- Isolation voltage peak - 250 V channel to ground, no channel to channel isolation GENERAL SPECS - - Power onsumption 2Watt (all types) Dianensions 200x50x30 mm Weight Typically 600 g | Compatibility | CMOS Confi | iguration | - |
| Input high current @ 5 V UIN <1.8 mA - Propagation delay <1 µsc - Sampling rate Maximum 20 kHz per channel (software selectable) - Some support outside peak 250 V channel/ground & channel/channel - Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS Input channels (isolated) - Maximum sink current - Maximum switching voltage - Propagation delay - Propagation delay - Sol V Maximum update rate - Isolation voltage peak - Sol V Maximum update rate - Isolation voltage peak - Sol V Maximum update rate - Sol V Maximum update rate - Sol V Maximum update rate - Sol V Maximum update rate - Sol V Maximum solt bus speed Fower supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight - Weight - Sol V Sol | Input low level | UIN < | 0.8 V | - |
| Propagation delay < 1 μsec - Sampling rate Maximum 20 kHz per channel (software selectable) - Overvoltage protection 40 V continuous (65 V peak) - Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS - - Input channels (isolated) - 8 16 Compatibility - Open collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - 220 μsec Maximum update rate - Depending on EtherCAT master Isolation voltage peak - 250 V channel to ground, no channel isolation GENERAL SPECS LEM0 18 EtherCAT cable (single cable connection power + sync + data) Data rate 100 Mbit bus speed Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Input high level | UIN > 2 | 2.4 V | - |
| Sampling rate Maximum 20 kHz per channel (software selectable) - Overvoltage protection 40 V continuous (65 V peak) - Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS - - Input channels (isolated) - 8 16 Compatibility - 0pen collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - 220 µsec Maximum update rate - 250 V channel to ground, no channel isolation GENERAL SPECS 100 Mbit bus speed 100 Mbit bus speed Power supply voltage 6 to 50 V DC 20 wer consumption Query ti (all types) 200x50x30 mm 200x50x30 mm Weight Typically 600 g 100 kg deg 100 kg deg | Input high current @ 5 V UIN | < 1.8 | - | |
| Overvoltage protection 40 V continuous (65 V peak) - Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS - 8 16 Compatibility - 0pen collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - 20 y sec Maximum update rate - 250 V channel to ground, no channel isolation GENERAL SPECS IEEM0 1B EtherCAT cable (single cable connection power + sync + data) Data rate 100 Mbit bus speed Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Propagation delay | <1µ | - | |
| Isolation voltage peak 250 V channel/ground & channel/channel - DIGITAL OUTPUTS Input channels (isolated) - 8 16 Compatibility - Open collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - 20 µsec Maximum update rate - Depending on EtherCAT master Isolation voltage peak - 250 V channel to ground, no channel to channel isolation GENERAL SPECS Interface LEMO 1B EtherCAT cable (single cable connection power + sync + data) Data rate 100 Mbit bus speed Power supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Sampling rate | Maximum 20 kHz per chan | - | |
| DIGITAL OUTPUTS Input channels (isolated) - 8 16 Compatibility - Open collector with 10 kR pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - <20 µsec Maximum update rate - Depending on EtherCAT master Isolation voltage peak - 250 V channel to ground, no channel isolation GENERAL SPECS Power supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Overvoltage protection | 40 V continuou | - | |
| Input channels (isolated) - 8 16 Compatibility - Open collector with 10 k pull-up to +5 V Maximum sink current - 150 mA (not protected) Maximum switching voltage - 50 V Propagation delay - <20 μsc Maximum update rate - 250 V channel to ground, no channel isolation Isolation voltage peak - 250 V channel to ground, no channel isolation GENERAL SPECS LEM0 1B Ether CAT cable (single cable connection power + syn + data) Data rate 100 Mbit bus speed Power supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Isolation voltage peak | 250 V channel/ground | - | |
| Compatibility-Open collector with 10 kR pull-up to +5 VMaximum sink current-150 mA (not protected)Maximum switching voltage-50 VPropagation delay-<20 µsecMaximum update rate-Depending on EtherCAT masterIsolation voltage peak-250 V channel to ground, no channel isolationGENERAL SPECSInterfaceLEM0 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | DIGITAL OUTPUTS | | | |
| Maximum sink current-150 mA (not protected)Maximum switching voltage-50 VPropagation delay-<20 µsecMaximum update rate-Depending on EtherCAT masterIsolation voltage peak-250 V channel to ground, no channel isolationGENERAL SPECSInterfaceLEM0 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Input channels (isolated) | - | 8 | 16 |
| Maximum switching voltage-50 VPropagation delay-50 VMaximum update rate-Depending on EtherCAT masterIsolation voltage peak-250 V channel to ground, no channel isolationGENERAL SPECSEEMO 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Compatibility | - | 0 kR pull-up to +5 V | |
| Propagation delay-Maximum update rate-Depending on EtherCAT masterIsolation voltage peak-250 V channel to ground, no channel isolationGENERAL SPECSInterfaceLEM0 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Maximum sink current | - | t protected) | |
| Maximum update rate-Depending on EtherCAT masterIsolation voltage peak-250 V channel to ground, no channel isolationGENERAL SPECSInterfaceLEM0 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Maximum switching voltage | - | 50 | V |
| Isolation voltage peak - 250 V channel to ground, no channel isolation GENERAL SPECS Itterface LEM0 1B EtherCAT cable (single cable connection power + sync + data) Data rate 100 Mbit bus speed Power supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Propagation delay | - | < 20 | µsec |
| GENERAL SPECS Interface LEM0 1B EtherCAT cable (single cable connection power + sync + data) Data rate 100 Mbit bus speed Power supply voltage 6 to 50 V DC Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Maximum update rate | - | Depending on E | therCAT master |
| InterfaceLEM0 1B EtherCAT cable (single cable connection power + sync + data)Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Isolation voltage peak | - | 250 V channel to ground, no | channel to channel isolation |
| Data rate100 Mbit bus speedPower supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | GENERAL SPECS | | | |
| Power supply voltage6 to 50 V DCPower consumption2 Watt (all types)Dimensions200x50x30 mmWeightTypically 600 g | Interface | LEMO 1B Ethe | rCAT cable (single cable connection power + : | sync + data) |
| Power consumption 2 Watt (all types) Dimensions 200x50x30 mm Weight Typically 600 g | Data rate | | 100 Mbit bus speed | |
| Dimensions 200x50x30 mm Weight Typically 600 g | Power supply voltage | | 6 to 50 V DC | |
| Weight Typically 600 g | Power consumption | | 2 Watt (all types) | |
| | Dimensions | | 200x50x30 mm | |
| Environmental rating IP67 | Weight | | Typically 600 g | |
| | Environmental rating | IP67 | | |
| Shock & Vibration Rating > 100 g | Shock & Vibration Rating | | > 100 g | |
| Temperature range -40 85 deg. C | Temperature range | | | |

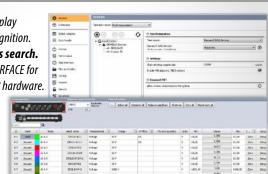
EtherCAT[®] ADVANTAGES:

- ► Fully compatible with ETHERNET hardware
- ► Power supply, data lines and Hardware A/D - synchronization in ONE cable



DEWESoft[®] USER ADVANTAGE:

- ► Easy plug and play hardware recognition.
- ▶ NO IP address search.
 - ► ONE USER INTERFACE for all DEWESoft[®] hardware.



ACCESSORIES TO CONNECT YOUR EtherCat® SYSTEMS

| 3 5 3 | ECAT SYNC-JUNCTION | C ^{IN4} C |
|----------------------|-----------------------|--------------------|
| <mark>/</mark> .@ @_ | DEWESoft* | 99 |

Synchronisation between DEWESoft® EtherCat® devices and USB devices or IRIG-B-DC or GPS

| Connection interface | 2x sync, 1x LEMO 1B EtherCAT® daisy (single cable connection power + sync + data) |
|---|--|
| Input signals | DEWESoft® USB devices: IRIG B DC |
| External synchronisation source: IRIG B DC | Simultaneous 200 kS/sec |
| Input IRIG B DC signal | TTL Level |
| Accuracy of synchronisation | Below 1 µsec when using same type of ADC (SIRIUS® EtherCAT® and SIRIUS® USB) and below 1 sample when using different ADC (KRYPTON® and SIRIUS®) |
| Data rate | 100 MBit bus speed |
| Power supply voltage | 6 to 50 V DC |
| Power consumption | 2 W |
| Dimensions | 200 x 50 x 30 mm |
| Weight | 650 g |
| Environmental rating | IP50 |
| Shock & Vibration Rating | > 100 g |
| Operating temperature | -40 to 85°C |
| | |

ECAT-POWER-JUNCTION

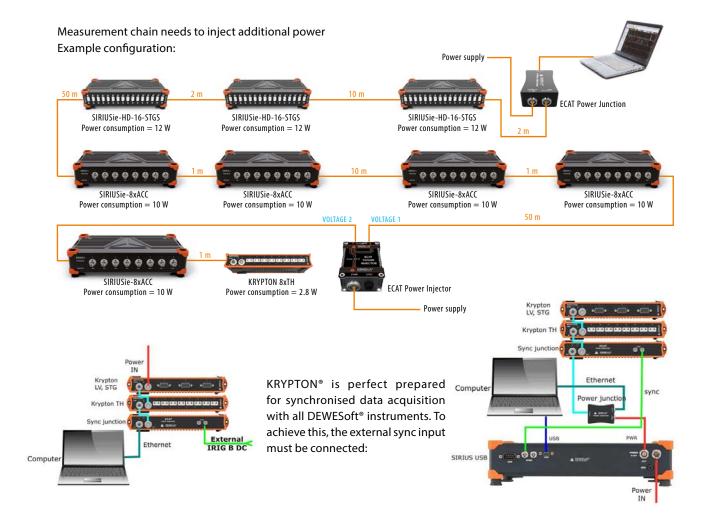


POWER-junction box. for connecting KRYPTON® or SIRIUS® EtherCAT® series to power supply over L1B2m (eg. PS-120-L1B2f) and Ethernet over RJ45.

ECAT-POWER-INJECTOR

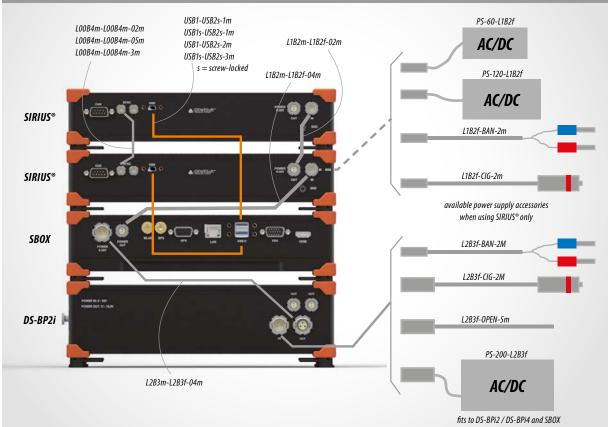


Power injector that acts as an additional power source in the chain of EtherCAT[®] instruments, connecting the EtherCAT[®] chain with power supply. EtherCAT[®] signal is passed through the instrument. Power lines are not passed through. IP67 rated.



ACCESSORIES – SUITABLE FOR ALL DEWESoft[®] INSTRUMENTS

SIRIUS® CABLE LABELING



BATTERY PACKS FOR MOBILE SOLUTIONS



- ► For SBOX and up to 4 SIRIUS[®] slices
- ▶ Supports 2 Li-lon batteries each 96 Wh (total capacity: 192 Wh)
- ► Hot-swap functionality
- Status display and USB interface to read out the status
- ▶ Maximum output power: 160 W
- ▶ Input voltage range: 10-36 VDC
- ▶ Output voltage: 21 V (powered), 11-16 V (battery)
- Wrong polarity protection

Calculation example for system:

DS-BP4i (384 Wh) and 1x SBOX (60 W) and 4x SIRIUSi - 8x ACC (4x 15 W) = 3 hours operation

DS-BP4i



- ► For SBOX and up to 8 SIRIUS[®] slices
- ▶ Supports 4 Li-Ion batteries each 96 Wh (total capacity: 384Wh) ► Hot-swap functionality
- Status display and USB interface to read out the status
- ► Maximum output power: 250 W
- ▶ Input voltage range: 12-36 VDC
- ▶ Output voltage: 24 V (powered), 11-16 V (battery)
- Wrong polarity protection

DS-BAT-96W

► Spare Battery Li-Ion 14,6V/6.6Ah = 96 Wh Weight 0.65 kg, 22 x 170 x 110 mm



DS-HUB7

For more than 4 SIRIUS® on one system, DEWESoft® offers a ruggedized USB hub.

- ▶ 7 USB ports with USB 2.0
- Lockable connectors

Total data throughput 4 MS/s DUALCOREADC® (160 dB) 8 MS/s SINGLE CORE (120 dB)





150

NAVIGATIONAL INSTRUMENTS

| | | 0 0 0 0 | S | 220 | S |
|---|--|--|---|--|--------------------------|
| | DS-GPS-CLOCK | DS-VGPS-HS/HSC | DS-IMU1 | DS-IMU2 | DS-GYRO |
| | Synchronisation box | Multi-purpose GNSS sensor | Basic vehicle dynamics sensor | Advanced vehicle dynamics sensor | GYRO sensor |
| Standalone (horizontal positioning) | 2.5 m | 1.2 m | 2.0 m | 1.2 m | - |
| Standalone (vertical positioning) | 3 m | 1.8 m | 3 m | 2.0 m | - |
| SBAS (horizontal positioning) | 1 m | 0.8 m (WAAS, EGNOS 0.3 m) | 0.6 m | 0.5 m | - |
| SBAS (vertical positioning) | 3 m | 1.2 m (WAAS, EGNOS 0.5 m) | 1 m | 1 m | - |
| Omnistar (horizontal positioning) | - | - | - | 0.1 m | - |
| Omnistar (vertical positioning) | - | • | - | 0.2 m | - |
| RTK (horizontal positioning) | - | 0.02 m | - | 0.01 m (0,3 m as standard option) | - |
| RTK (vertical positioning) | - | 0.02 m | - | 0.02 m (0,3 m as standard option) | - |
| Velocity accuracy | 0.05 m/s | 0.02 m/s | 0.05 m/s | 0.01 m/s | - |
| Roll & Pitch accuracy (dynamic) | - | - | 0.2 ° | 0.15 ° | 0.6 ° |
| Heading accuracy (dynamic with GNSS) | - | - | 0.2 ° | 0.1 ° | 1.0 ° |
| Slip angle accuracy | - | - | 0.5 ° | 0.1 ° | - |
| Range | Unlimited | Unlimited | Unlimited | Unlimited | Unlimited |
| Hot start time | < 3 s | < 10 s | 1s | 3 s | 0,5 s |
| Output data rate | 10 Hz | 20/100 Hz | Up to 100 Hz | Up to 500 Hz | up to 500 Hz |
| GNSS Supported navigation systems | GPS L1, GLONASS L1 | GPS L1, L2*GLONASS L1, L2* | GPS L1, GLONASS L1, Galileo E1, compass L1 | GPS L1, L2*, L5* GLONASS L1, L2*, BeiDou B1, B2 | |
| Supported SBAS systems | SBAS L1 | WAAS, EGNOS, MSAS, GAGAN, QZSS | WAAS, EGNOS, MSAS, GAGAN, QZSS | WAAS, EGNOS, MSAS, GAGAN, QZSS | - |
| HARDWARE | | | | | |
| Interface | USB | RS232 / USB, CAN, Analogue, Digital | USB & RS232 | USB & RS232 | USB |
| Operating voltage | 5 V USB powered | 9 to 36 V | 5 to 36 V USB powered | 9 to 36 V | 4 to 36 V USB powered |
| Power consumption | 400 mA @ 5 V | 250 mA @ 12 V | 100 mA @ 5 V | 220 mA @ 12 V/td> | 65 mA @ 5 V |
| Operating temperatures | -5 °C to 75 °C | 0 °C to 60 °C | -40 °C to 85 °C | -40 °C to 85 °C | -40 °C to 85 °C |
| Environmental protection | not IP rated | not IP rated | IP 67 | IP 67 | IP 68 |
| Input protection | Polarity & short overvoltage protection | Polarity & short overvoltage protection | ±40 V | -40 to 100 V | ±40 V |
| Shock limit | MIL-STD 810 F | MIL-STD 810 F | 2000 g - MIL-STD 810G | 2000 g - MIL-STD 810G | 2000 g - MIL-STD 810G |
| Dimensions | 115 x 93 x 35 mm | 115 x 93 x 35 mm | 30 x 40,6 x 24 mm | 90 x 127 x 31 mm | 30 x 40,6 x 24 mm |
| Weight | 330 g | 740 g | 37 g | 285 g | 25 g |
| INERTIAL SENSORS | | | | | |
| Accelerometer | _ | - | <u>√</u> | ✓ | <u>√</u> |
| Gyroscope | - | - | <u>√</u> | ✓ | <u>√</u> |
| Magnetometer | - | - | <u> </u> | ✓ | ✓ |
| Pressure sensor | - | - | ✓ | ✓ | - |
| Synchronisation and timing with DEWESoft DAQ | ✓ | ✓ | ✓ | ✓ | ✓ |
| Simple positioning | ✓ | ✓ | ✓ | ✓ | _ |
| Brake/Acceleration test | - | ✓ | ✓ | ✓ | - |
| Vehicle dynamics | - | _ | Simple | ✓ | - |
| Lane change | - | ✓ | Simple | ✓ | - |
| Circle drive | - | ✓ | ✓ | ✓ | - |
| Chassis development | _ | - | _ | ✓ | _ |
| Advanced driver assistance systems testing (Blind-spot detection, Forward collision warning,) | _ | ✓ | Simple | ~ | _ |
| Comfort testing | _ | - | Simple | \checkmark | - |
| Pass by Noise | - | ✓ | Simple | \checkmark | - |
| Functional safety | - | \checkmark | Simple | \checkmark | - |
| Orientation of different objects | - | - | ✓ | ✓ | ✓ |

CAN INSTRUMENTS

2 CHANNEL CAN: DS-CAN2



- ▶ 2 high speed CAN interfaces (isolated)
- Synchronization with all DEWESoft[®] products
- ▶ Up to 8 CAN interfaces per system
- ▶ Incl. DEWESoft® X-Prof.
- ▶ -20°... +60°C operating temperature (fanless)
- ▶ No external power supply needed if CAN operation only

4 CHANNEL CAN: SIRIUS*im* 4xCAN



- ▶ 4 high speed CAN interfaces (isolated)
- Sync with all DEWESoft® instruments
- ▶ 5V / 500mA sensor supply on each connector
- ▶ USB powered only (2x USB cable)

8 CHANNEL CAN: SIRIUS if-8xCAN



- 8 high speed CAN interfaces on front side (isolated)
- ► +1 high speed CAN interface on rear side (isolated)
- ► Sync with all DEWESoft[®] instruments
- ► 5V / 500mA sensor supply on every front connector
- ► 12V / 200mA sensor supply on the rear connector

DEWESoft[®] Smart Interfaces

The versatile DSI[®] adapters convert any DEWESoft[®] instruments DSUB9 analogue input into whatever is needed. E.g. Add ICP inputs to your DEWE-43 by connecting th DSI-ACC. The adapter is automatically recognized by TEDS and all the settings are done in DEWESoft[®]

X Software accordingly. The DSI® adapters contain the electronics for the sensor input, calibration data, identification and the input sensor connector. Sensor TEDS information will also be recognized of course.

DSI-ACC



IEPE ("Integrated Electronics Piezo Electric) adapter Excitation current 4 mA@21 V, highpass filter 1.5 Hz, BNC connector DUAL TEDS: Automatic adapter AND sensor identification.

DSI-V-200



± 200 V input adapter Differential input configuration, BNC connector Automatic adapter identification

DSI-RTD



Pt100, Pt200, Pt500, Pt1000 and Pt2000 adapter 2, 3 and 4 wire connection methods, 5-pin Binder 710 series connector Automatic adapter identification

DSI-CH-x



Charge input interface Range up to 50000 pC, AC coupled with 0.07 Hz, BNC signal connection Max. 100 kHz bandwidth (depending on the max. bandwidth of the amplifier) Automatic adapter identification

DSI-TH-x



Thermocouple type K / J / T adapter High accuracy cold junction reference measurement 1 m thermo cable with Mini TC connector Automatic adapter identification

DSI-20mA AND DSI-5A



DSI-20 mA: 20mA current input adapter with internal shunt 50 Ohm, 0.05%, use for sensors with 4...20 mA output **DSI-5 A:** 5 A current input adapter with internal shunt 0.1 Ohm, 0.05% both with screw terminals in housing for cable fixing both with Automatic adapter identification



Generates 4 or 10 kHz excitation to be able to connect to LVDT sensors, phase adjustment with potentiometer, output 1 V = 1000 mV/VAutomatic adapter identification

DEWESoft® CAMERAS

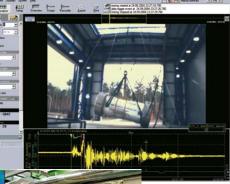
SYNCHRONIZED TO A/D CONVERTER

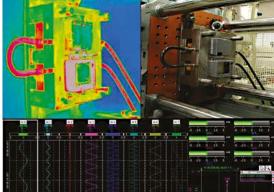
For applications requiring video which is truly synchronized to the dynamic sample rate, there is support for DS-Cameras. A high quality image with automatic shutter speed (selectable) is controlled directly by the A/D card, which generates a pulse to drive the camera. The result is a stunning correlation between each frame and the data.

Thermo cameras are supported from FLIR, NEC and MICRON, and high speed cameras from Photron which can acquire more than 100000 frames per second.



Video Input Synchronized video acquisition from web-, thermo- and high speed cameras





DS-CAM-88c: 640x480 @ 88 FPS, 320x240 @ 167 FPS, 160x120 @ 289 FPS

DS-CAM-88 + DS-CAM-120



- ▶ 88 / 120 fps @ VGA (640x480)
- ⊾ Auto-Shutter
- ⊾ Auto-Gain
- ► Auto-White-Balance
- ⊾ Color
- ▶ Power-over-Ethernet option

DS-CAM-600m/c: 1920x1080 (HD) @ 300 FPS, 640x480 (VGA) @ 600 FPS

DS-CAM-600



- ▶ 600 fps @ VGA
- ▶ Full HD resolution (1920x1080)
- ▶ Real-time onboard JPEG compression
- ▶ Power-over-Ethernet
- ▶ Best performance with SBOX
- ▶ Color and monochrome
- IP67 version available



1920×1080



- ▶ Machine diagnostics
- ▶ Product quality check
- ▶ Non destructive testing
- Research and development
- Automotive crash testing
- ▶ Impact tests
- ▶ Logistics & transportation
- Preventive maintenance
- ▶ Manufacturing

All DS-CAM cameras were designed to be high-shock and vibration resistant.

The DS-CAM cameras can run in triggered (sync) and free-run mode. The video is captured by real-time data streaming, even at full resolution! Therefore a Gigabit-Ethernet port is required.

SYSTEM REQUIREMENTS FOR GigE CAMERAS:

- ▶ Gigabit Ethernet LAN port
- ▶ DEWESoft® 7.1 or X
- (Clock possibility)
- ⊾ Core2Duo CPU

| | G | | | Free |
|---------------------------|--|-------------------------|--|-----------------------------|
| | DS-CAM-88 | DS-CAM-120 | DS-CAM-600 | Webcam |
| GENERAL | | | | |
| Color option | DS-CAM-88c | DS-CAM-120c | DS-CAM-600c | Yes |
| Monochrome option | - | - | DS-CAM-600m | Yes |
| OPTICAL SPECIFICATION | | | | |
| Image sensor | Sony ICX414 | Sony ICX618 | CMOSIS CMV2000 2E5M1PP | various |
| Sensor type | C | CD | CMOS | CCD/CMOS |
| Resolution | VGA resolut | ion 640x480 | Full HD resolution 1920x1080 | 1280x720 |
| FPS | 88 FPS @ 640x480 167 FPS @ 320x240 289 FPS @ 160x120 | 120 FPS @ 640x480 | 600 FPS @ 640x480 300 FPS @ 1920x1080 1460 FPS @ 320x240 | 30 FPS |
| Optical size | 1/2″ | 1/4" | Diagonal 12.7 mm (2/3") | various |
| Pixel size (in µm) | 9.9 x 9.9 | 5.6 x 5.6 | 5.5 x 5.5 | various |
| Dynamic range | 35 dB autogain function | 32 dB autogain function | 60 dB | various |
| Shutter | Full frame | | Electronic Global Shutter | - |
| Shutter time | 26 ns - 60 s58 μs - 60 s(autoshutter function)(autoshutter function) | | 210 ns - 90 s | - |
| Color correction | auto whi | te-balance | DS-CAM-600c: yes DS-CAM-600m: no | Yes |
| MECHANICAL SPECIFICATIONS | | | | |
| Operating temperature | +5+45°C | | 0+50°C | 0+45°C |
| Operating humidity | 25% - 80% (no condensation) | | 25% - 80% (no condensation) IP67 protected version available: DS-CAM-600cw | 25% - 80% (no condensation) |
| Dimensions | 86.4 x 44 x 29 mm (3.40 x 1.73 x 1.14 in) | | 54 x 40 x 92 mm (2.13 x 1.57 x 3.63 in) | various |
| Lens mount | C-mount | | C-mount (1" 32G thread) | - |
| Connectors | Screw mount GigE RJ45; EIAJ (Hirose) 12 pin | | Gigabit Ethernet: RJ45 | USB |
| Conformity | CE, FCC, RoHS, GigE Vision, GenICam (PoE IEEE 802.3at) | | CE, EN55022, class A; EN61000-4-2; EN61000-4-3; EN61000-4-4; EN61000-4-6; FCC Part 15, class A RoHS, GigE Vision 1.2 | Direct X |
| ELECTRICAL SPECIFICATIONS | | | | |
| Supply voltage | +8 to +30 VDC | | Power-over-Ethernet (42-57 V) | USB (5 V) |
| Power-over-Ethernet | optional | | yes | - |
| Power consumption | 3.6 W | | 6 W | 2 W |

CAM-BOX1

Adapter box for connecting up to 4 DS-CAM-88/120 to the DEWESoft® instrument. Combines Sync and Power to the camera connector. External GigE switch required.



CAM-BOX2

Distribution box for connecting up to 4 x DS-CAM-88/120 to the DEWESoft[®] instrument. Wide range supply input (9-36V DC), integrated GigE switch



CAM-BOX3

Distribution box for connecting up to 4 x DS-CAM-600 to the DEWESoft® instrument. Wide range supply input (9-36 V DC), integrated GigE switch with 4 x PoE; SIRIUS® chassis with 1.5 U height



DEWE-43A

MUST HAVE FOR EVERY ENGINEER

8 ANALOGUE INPUTS

► Multi-sensor input for Voltage, Bridge, IEPE, Temperature, Charge

0000

- ▶ Simultaneous sampling
- ▶ 200 kHz/channel
- ▶ 24 bit, alias-free
- ► 10 V, 1 V, 100 mV, 10 mV ranges (200 V with DSI[®] adapter)
- \blacktriangleright ± 5 V, 12 V sensor supply
- ▶ Isolated power supply as standard

8 COUNTER INPUTS 24 DIGITAL INPUTS

Ø

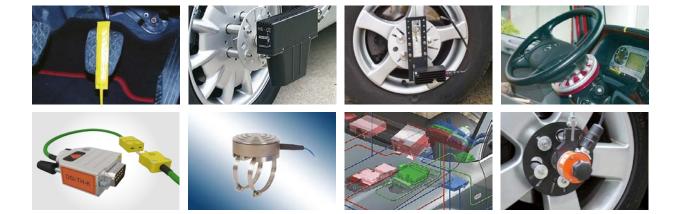
- ► Counting, Waveform timing, Encoder, Tacho and Geartooth sensors
- ▶ Digital inputs
- ► Fully synchronized with analogue data

2 CAN BUS PORTS

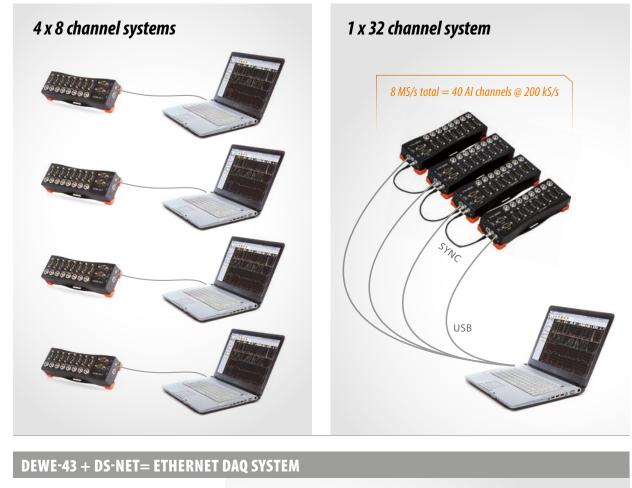
- ▶ optical isolation
- ▶ Vehicle CAN, OBDII, J1939
- ► CAN sensors support
- ► CAN 2.0b up to 1 MBit/sec

DEWESoft®

- ► DEWESoft® X included
- ► Synchronous data acquisition of different sources
- ► Full support of DEWE-43A, GPS and video camera



ANY combination up to 32 analogue, 32 counter and 8 CAN bus channels.

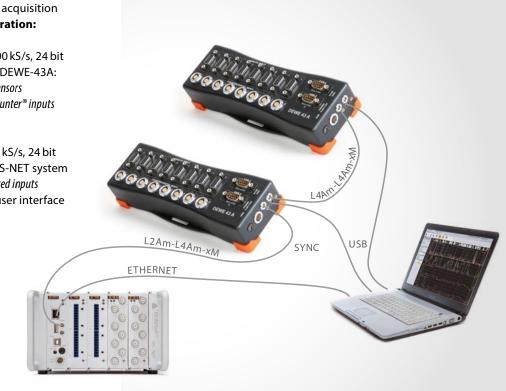


Mixed signal data acquisition **Example configuration:**

16 channel fast 200 kS/s, 24 bit each channel, 2 x DEWE-43A:

- ► For ACC vibration sensors
- ▶ 16 channel Supercounter[®] inputs
- ▶ 4 CAN bus

32 channel slow 2 kS/s, 24 bit each channel, 1 DS-NET system ► *Mixed signals isolated inputs* With DEWESoft® user interface



DEWE-43A - TECHNICAL SPECIFICATIONS

| ANALOGUE INPUT | |
|--------------------|--|
| Number of channels | 8 (simultaneously sampled) |
| Measured values | Voltage, full bridge (IEPE, charge, thermocouple and RTD with DSI® adapters) |
| Resolution | 24-bit |
| Type of ADC | Sigma-Delta with anti-aliasing filter |
| Sampling rate | 200 kS/s |
| -3 dB bandwith | 76 kHz @ 200 kS/s |

| AMPLIFIER CHARACTER | | |
|------------------------------|--|---|
| Input ranges | Voltage | ± 10 V; ± 1 V; ± 100 mV; ± 10 mV |
| | Voltage via DSI-V200 | up to ± 200 V |
| | Full bridge @ 10 Vexc | ± 10 mV/V, ± 100 mV/V, ± 1000 mV/V |
| | Half or quarter bridge | With external bridge completion |
| | IEPE via DSI-ACC | ± 0.1 V, ± 1 V, ± 10 V |
| | Thermocouple via DSI-THx | Full range of thermocouple type (isolated thermocouple only) |
| | Pt100, Pt200, Pt500, Pt1000, Pt2000 and resistance via DSI-RTD | -200°C to 1000°C and 0 to 6.5 kOhm |
| DC accuracy | 10 V range: 0.1 % of value, +1 mV 1 V range: 0.1 % of value, +0.5 mV 100 mV range: 0.1 % of value, +0.1 mV 10 mV range: 0.1 % of value, +0.1 mV | |
| Input impedance | 10 MΩ 33 pF (common mode), 20 MΩ 47 pF (differential mode) | |
| CMRR | >80 dB | |
| Sensor supply voltage | ±5 V 0.1 % @ 100 mA, 12 V @ 400 mA per channel | |
| Voltage mode coupling | DC | |
| Input overvoltage protection | ±70 V | |

| DYNAMIC CHARACTERISTICS | |
|------------------------------|-----------|
| Signal to noise @ fs<1000 Hz | < -100 dB |
| Crosstalk | < -100 dB |

| COUNTER/DIGITAL INPUTS | |
|--------------------------|---|
| Number of channels | 8 counters or 24 digital inputs (per software each counter can be selected to be 3x digital input) |
| Counter modes | Event counting, encoder input, period, pulsewidth, duty cycle, frequency measurement |
| Resolution | 32-bit |
| Time base | 102.4 MHz |
| Signal levels | TTL/CMOS |
| Input voltage protection | 30 V |

INSTRUMENTS

CAN PORTS

| Number of channels 2 | 2 (optically isolated) |
|----------------------|------------------------|
| Specification (| CAN 2.0b up to 1MBit/s |
| Physical layer | High speed |

ENVIRONMENTAL

| Operating temperature | -20 to 50°C |
|-----------------------|---------------------------------|
| Storage temperature | -20 to 70°C |
| Relative humidity | 10 to 90 % |
| Vibration | MIL-STD 810F 514.5, procedure I |
| Shock | MIL-STD 810F 516.5, procedure I |

PHYSICAL

| THISICAL | |
|------------------------|--|
| Dimensions (L x W x H) | 223 x 78 x 45 mm (7.78 x 3.08 x 1.77 inch) |
| Weight | 0.72 kg (1.58 pounds) |
| | |

POWER REQUIREMENTS Supply voltage 6 to 36 $V_{\rm DC}$ 80 V Supply overvoltage protection Negative input voltage protection -30 V 5 W

| SYSTEM REQUIREMENTS | |
|---------------------|--|
| Operating system | Microsoft WindowsXP® Microsoft Windows Vista® Microsoft Windows 7® |
| System | PC with DEWESoft [®] software |
| Interface | USB 2.0 |

6 W

IN THE PACKAGE

Typical power consumption

Maximum sensor consumption

| $DEWESoft^{\otimes}X$ - Professional Edition (DSA upgrade available) incl. CAN option | |
|---|--|
| MINI USB cable (equipped with special lock-in screws for secure connection) | |

Carrying bag

Device ground cable

| DEWE-43A INPUTS | |
|--------------------------|--------------|
| No. of analogue channels | 8 |
| Samplerate / channel | 200 kHz |
| Vertical resolution | 24 bit |
| Input type | differential |

| IND | PUT TYPES | |
|--------------|--|---|
| INF | Voltage | 8 ch |
| U | Max. Range | ± 10V ± 200 V DSI® option |
| | Input coupling | DC |
| ÷ | IEPE/ICP Sensors | 8 ch DSI® option 4 mA, max 21V |
| | Sensor supply per system | ± 5V 100 mA 12V 400 mA |
| | Bridge connection type | 8 ch 4 wire |
| | Bridge completion with DSI® adapter | full bridge, half bridge 1 kOhm quarter bridge 120 and 350 Ohm |
| .nnn .nnn | Supercounter® | 8 ch |
| | TEDS supprt without DSI® adapters | yes |
| ÷ | Charge input with DSI® adapter | up to 50000 pC |
| Ł | Potentiometer | with DSI® adapter |
| £ | Pt100 Pt2000 | with DSI® adapter |
| < | Thermocouple | with DSI® adapter |
| | CAN bus ports | 2 ch (isolated) |

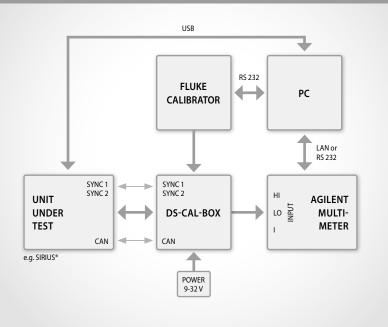
| CONNECTORS | |
|------------------------|--------------------------|
| DSUB 9 | 8 + 2 |
| LEMO 7pin | 8 |
| BNC, Binder and others | DSI [®] adapter |

SOFTWARE



The ISO standardization process requires a periodic check of the measurement equipment. You can either annually send back your DEWESoft® instrument to the factory for inspection, or – if you own a large number of measurement channels – build up a new or extend your existing calibration lab.

CALIBRATION SETUP



Required hardware:

- ► Fluke calibrator 5500, 5520, 5700, 5720 or 5502 series
- ► Agilent Multimeter 34410A (LAN) or 34401A (RS232)
- ▶ DS-CAL-BOX

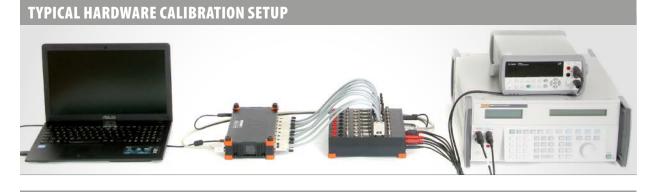
The calibrator generates reference signals, which are measured by the DEWESoft® instrument, while the multimeter checks the outputs, e.g. analogue out or excitation voltages. The DS-CAL-BOX ensures the correct routing and additional functionality check such as bridge completion, shunt, sync check etc...

DS-CAL-BOX



The ds-cal-BOX is a special device for automated calibration and additional functionality check of DEWESoft[®] instruments (e.g. SIRIUS[®], DEWE-43). It's standard routines contain the check of:

- ► Analogue ranges
- ▶ Excitations
- ▲ Counters
- ▶ power supplies
- ▶ bridge completion
- ⊾ shunts
- ▶ analogue output
- ⊾ sync
- ⊾ CAN



DEWESoft® CAL – SOFTWARE

| e <u>D</u> atab | | | | | | |
|-----------------|---------------|---------------------|--------------|----------------|---------------------------|--------------------|
| evice 1 | ▼ of 1 | Refresh | | | | |
| | SIRIUS L ACC. | *** | | | 10 10 | <u> </u> |
| | ···· 🎢 | ' 🖧 () | $\sum O $ | r 0° | ဳိုိ | |
| | 80.410 | | •~ • | ••• | | |
| | | | | | _ | |
| _ | - | | | | | - |
| SI | RIUSI | erial number: D0060 | | | olation: ISO ptions: / | Temperature: 34 °C |
| | 5 | ystem SN: DOOBFFBF | 32 PW Versio | n: 4.6.12.16 O | ptons: / | Cal date: 1.1.1900 |
| Idx | Туре | SN | Cal. date | HW Ver | FW Ver | |
| Ch 1 | SIRIUS-ACC+ | D007380B31 | 7.3.2013 | 1.4.0.0 | 1.13 | |
| Ch 2 | SIRIUS-ACC+ | D0073AFF94 | 7.3.2013 | 1.4.0.0 | 1.13 | |
| Ch 3 | SIRIUS-MUL | D008684295 | 7.3.2013 | 2.5.0.0 | 1.17 | |
| Ch 4 | SIRIUS-MUL | D00868429D | 7.3.2013 | 2.5.0.0 | 1.17 | |
| Ch 5 | SIRIUS-STG | D00904CEB1 | 7.3.2013 | 1.5.0.0 | 1.15 | |
| Ch 6 | SIRIUS-STG | D00904CEB2 | 7.3.2013 | 1.5.0.0 | 1.15 | |
| | SIRIUS-HV | D007D38A6C | 7.3.2013 | 1.3.0.0 | 1.1 | |
| Ch 7 | SIRIUS-HV | D007D38A55 | 7.3.2013 | 1.3.0.0 | 1.1 | |
| Ch 7 Ch 8 | 1 | 1 | 1 | 1 | 1 | |
| | | | 1999 | | | |
| Ch 8 | | Adjustment | Calibration | | just and Check | |

Theease of use "DS Calibrator" software checks and adjusts the DEWESoft® instrument's amplifiers. If all channels pass, it will update the calibration date in the device and create a professional report in PDF format.

Then you just print the Calibration Certificate ...

ORDERING INFORMATION

1. DS-CAL-BOX

Calibration Set including DS-CAL-BOX with all cabling, adapters and accessories, DEWESoft® calibration software, supports FLUKE calibrator 5500, 5520, 5700, 5720 or 5502 series, supports Agilent Multimeter 34410A Supports SIRIUS®, DEWE-43

2. DS-CAL-BOX-PLUS

The PLUS package adds certified METCAL routines to the DS-CAL-BOX



DEWESoft® WORLDWIDE ON SITE CALIBRATION SERVICE AVAILABLE IN

- ▶ DEWESoft® Slovenia
- ► DEWESoft® Austria
- ► DEWESoft[®] France
- ▶ DEWESoft® USA
- ▶ DEWESoft® CHINA

FACTORY CALIBRATION:

Standard: factory calibration with ISO traceable certificate **OPTION:** worldwide accepted ANSI/NIST traceable certificate: (CAL-SIRIUS-ISO) INSTRUMENTS

SOFTWARE

DS-NET ETHERNET SOLUTION

DS-NET is a measurement and control system designed for many demanding applications, especially in the fields of

- ▶ Engine Testing

The DS-NET system is rugged and scalable from e.g. a two channel control unit to a large synchronized measurement grid with thousands of channels. It is as flexible as being a stand alone data logger, a channel expansion of DEWESoft® instruments, an Ethernet based distributed measurement system or a full-featured independent data acquisition instrument.

The completely modular architecture ensures always a perfect fit of the system configuration for the application at hand. A wide range of DS-NET modules is available to support almost any type of input and output signals. These multi-function modules can be combined in countless ways and provide top-notch data recording and process control. The system is designed for practical industrial appliance and thus is comprised of all metal housings and robust electronics offering galvanic isolation. Popular connector options enable convenient sensor connection and in combination with the easy-to-use software this ensures a time saving system setup.

Considering all these facts, DS-NET will serve you many years and is a safe investment.

- APPLICATIONS

- **Component Testing**

BENNN. NUMBER.

▶ Distributed data acquisition,

▶ Stand alone data logging

Ethernet based

in configuration

▶ REAL-TIME performance

▶ Redundant data storage

software

▶ Medium speed data acquisition up to 10 kS/s/ch

▶ Complete instrument running local DEWESoft®

▶ Channel expansion for DEWESoft[®] instruments

Scalable from two to several thousand channels

▶ Completely modular and thus very flexible

▲ Customised LabVIEW[™] based solution

▶ Portable and 19" rack-mount lines

▶ Operating temperature -20° C to +60° C

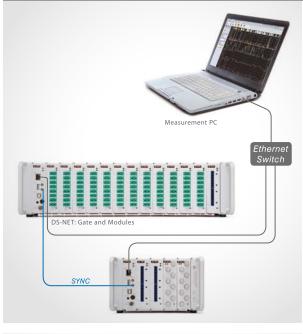
E°

- Process Performance Testing
- Structural Monitoring

DS-NET

APPLICATION AREAS

ETHERNET DATA ACQUISITION SYSTEM





STAND ALONE DATA LOGGING



Every DS-NET system is ready to be used as a rugged stand-alone data logger - without any additional costs! The logging process is configured by a single click in DEWESoft® software. Measurement data and calculated values can be stored to a USB memorystick: up to a limit of 32 GB.

For triggered storing an aggregate sampling rate of max. 160 kS/s and up to 2 million samples per trigger event

are the limit.

DS-NET is a very flexible and compact Ethernet based data

acquisition system. There is a portable line as well as a 19" rack-mount line. Both lines offer very precise galvanically isolated signal conditioning and enhanced features and reliability. Usually the DS-NET system is connected to a host computer running DEWESoft® online data acquisition software. Up to 160 kS/s can be received from a single DS-NET

system and then be processed, visualised and stored on the

But DS-NET also offers real-time performance! Since Microsoft Windows[®] is no real-time operating system it can not guarantee certain reaction times. DS-NET runs its own internal real-time operating system and can handle output

and alarm functions directly inside the instrument. Thus accurately defined response times are guaranteed - com-

host computer.

pletely independent of any PC.

FIXED LATENCY TIME

Alarm handling inside module

For continuous storing an aggregate sampling rate of max. 20 kS/s is the limit. Data is stored into files of max. 2 million samples each without any gap between the files.

USB sticks can be hot-swapped during measurement without losing any data thanks to the internal buffer memory. Data analysis can be done offline in DEWESoft[®] software.

REDUNDANCY IN DATA ACQUISITION



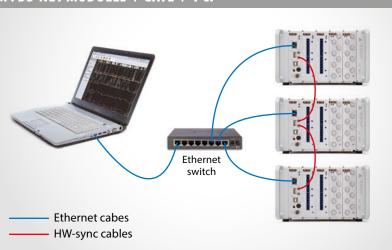
The combination of the data logging feature and DEWESoft[®] online recording software gives you redundancy in data acquisition for maximum reliability. Both, a USB stick and a measurement PC (via Ethernet), are connected to the DS-NET system in parallel. Data is logged to the USB stick while you are using DEWESoft[®] to process, analyse and store the very same data at the same time!

As a result, even if your Ethernet connection should break during a measurement, your data is safe, since it is logged to the USB stick.

DS-NET SYSTEM ARCHITECTURE:

1. ETHERNET BASED DAQ - SYSTEM : DS-NET MODULES + GATE + PC:

The DS-NET system starts with one DS GATE as the base interface between up to 16 DS-NET modules and the computer. Data with a total sampling rate of 160 kS/s can be transferred from each DS – GATE. The GATE HS can transfer up to 1.6 MS/s. The number of channels can be easy expanded with DS- NET systems up to 1000 channels. The distance between the gates can be up to 100 meter with Ethernet cables, or 1000m with optic Ethernet links. The synchronization between the DS-NET systems can be done by software, hardware cable or GPS links without cables.

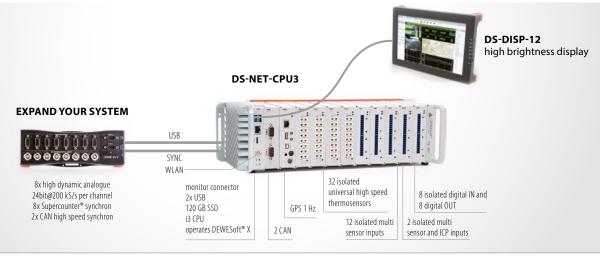


| | DS GATE | DS GATE-HS |
|--------------------------------|----------|--------------------|
| PC - Interface Ethernet | Ethernet | Gigabit/s Ethernet |
| Max. module support | 16 | 64 |
| max. total data transfer rate | 160 ks/s | 800 kS/s |
| typ. transfer for 100 channels | 1 kS/s | 8 ks/s |
| RS485 interfaces | 2 | 4 |

2. ALL IN ONE ETHERNET BASED DAQ - SYSTEM : DS-NET MODULES + GATE + DS-NET-CPU3:

Just add the powerful DS-NET-CPU3 to your DS-NET system and enjoy the ALL IN ONE DAQ system with the powerful DEWESoft[®] user interface. If you need additionally dynamic data channels, just add the powerful SIRIUS[®] or DEWE-43 DAQ modules with 200kS/s or even 1 MS/s. All data from DS-NET, SIRIUS[®] or DEWE-43 hardware are fully synchronized!

| | DS-NET-CPU3 |
|-------------------|--------------|
| Software | DEWESoft® X2 |
| CPU | i3 |
| solid state HDD | 120 GB |
| RAM | 4 GB |
| WIFI | 802.11g |
| DISPLAY INTERFACE | Mini HDMI |



| Module type | ACC2 | CFB2 | BR8 | BR4 | BR4-D | V8 | V8-B | V8-200 | V4 | V4-B | V4-HV | TH4 | TH8 | TH8-C | D108 | A04 |
|------------------------------------|------------------|-----------------------|-----------------------|-----------------|-----------------|-----------------|-----------------------|-----------------------|--------------|------------------|-------------------|-------------------|-----------------|-----------------|-----------------------|------------------|
| Max. Samplerate[Hz] | 10k⁴ | 10k | 10k | 1(|)k⁴ | 1 | 0k | 10k | 1 | 0k | 10k | 10k | 1(| D0 ⁵ | 10k | 10k |
| Isolation Voltage [V] ⁶ | 500 ⁷ | 500 ⁷ | 500 ⁷ | 50 | 00 ⁷ | 50 | 00 ⁷ | 500 ⁷ | 1 | .2k ⁸ | 1.2k ⁸ | 1.2k ⁸ | 50 | D0 ⁷ | 500 ⁹ | 500 ⁷ |
| | | | | | | AN | ALOGUE IN | PUT TYPES | | | | | | | | |
| Voltage | 2 | | | 4 | 4 | 8 | 8 | 8 | 4 | 4 | 4 | 4 | 8 | 8 | | |
| max. Range | ±60V | | | ±10V | ±10V | ±10V | ±10V | ±200V | ±10V | ±10V | ±1kV | ±80mV | ±80mV | ±80mV | | |
| Current Range (025mA) | 2 | | | 4 | 4 | 8 ¹⁰ | 8 ¹¹ | | 411 | 4 ¹¹ | | | | | | |
| Resistance | 2 | | | 4 | 4 | | | | | | | | | | | |
| Potentiometer | 2 | | | 4 | 4 | | | | | | | | | | | |
| Pt100, Pt1000 | 2 | | | 4 | 4 | | | | | | | | | | | |
| Thermocouple | 2 ¹² | | | 4 ¹² | 4 ¹³ | | | | | | | 4 | 8 ¹² | 8 | | |
| Full, ½, ¼ bridges | 2 ¹⁴ | 2 ¹⁵ | 8 | 4 ¹⁶ | 4 ¹⁷ | | | | | | | | | | | |
| Inductive full ½ bridges | | 2 | | | | | | | | | | | | | | |
| LVDT | | 2 | | | | | | | | | | | | | | |
| IEPE/ICP Sensors | 2 | | | | | | | | | | | | | | | |
| | | | | | | DI | GITAL INP | UT TYPES | | | | | | | | |
| Frequency | | | | | | | | | | | | | | | 4 | 2 |
| Pulse Width | | | | | | | | | | | | | | | 4 | 2 |
| Counter | | | | | | | | | | | | | | | ✓ 18 | √ 19 |
| Time | | | | | | | | | | | | | | | 4 | 2 |
| Status | 2 | 4 | | | | 2 | | | | | | | | | 8 | 4 |
| | | | | | | ANAI | LOGUE OUT | PUT SIGNA | L | | | | | | | |
| Voltage (±10V) | | 2 | | | | | | | | | | | | | | 4 |
| Current (420mA) | | | | | | | | | | | | | | | | 4 |
| | | | | | | DIG | ITAL OUTP | UT SIGNAL | | | | | | | | |
| Frequency | | | | | | | | | | | | | | | 8 | 4 |
| Pulse Width | | | | | | | | | | | | | | | 8 | 4 |
| Status | 2 | 4 | | | | 2 | | | | | | | | | 8 | 4 |
| | | | | | _ | | CONNEC | TORS | _ | - | | _ | - | - | | |
| ✓ standard connectors, | | | ectors | | | | | | | | | | | | | |
| Screw | ✓ | ✓ | | \checkmark | | \checkmark | | ✓ | \checkmark | | | | \checkmark | | ✓ | \checkmark |
| BNC | V ²⁰ | | | | √ 21 | | ✓ | | | ✓ | √ | | | | | |
| DSUB 9 | | | ✓ | | \checkmark | | | | | | | | | | | |
| Thermocouple | | | | | | | | | | | | | | ✓ | | |
| Spring Terminal | | | | | | | MISCELLA | NEOUS | | | | ✓ | | | | |
| Sensor supply [V] | | | | | <=12 | | | | | | | | | | | |
| Approx. Weight [g] ³ | 400 | 400 | 800 | 400 | 450 | 400 | 500 | 400 | 400 | 500 | 600 | 400 | 400 | 500 | 400 | 400 |
| | | | | | | | | | | | | | | | | |

DS-NET MEASUREMENT MODULES:

4) only 8Hz for thermocouples

5) only 8Hz with active mains rejection

b) on one minutestic manary rejection
 b) solation voltage: channel, to power supply and to interface (unless otherwise noted on the module specifications)
 c) 1kVDC peaks, 500VDC for some minutes, 250VDC permanent
 a) 1.2kVDC permanent

2.5

2.5

2.5

2

2

2

2

2

2

2

2

2

2

2

2.5

Approx. Power

Consumption [W]

9) isolation voltage between group/group (connector/connector): 1kVDC peaks, 500VDC for some minutes, 250VDC permanent 10) V8-SHUNT adapters are available as option

2

IO) VS-SHUNI adapters are available as option
 with external shunt (no adapter available)
 external CIC adapters are available as option (see TH8-CIC, BR4-CIC, ACC2-CIC)
 differential temperature measurement only (no CIC adapter available)
 Wridge completion adapters ACC2-120/ACC2-320 are available as option

15) ¼ bridge completion adapters CFB2-120/CFB2-350 are available as option 16) ¼ and ½: bridge completion adapters BR4-120/BR4-350 are available as option

10) % and %: bridge completion adapters BR4-120/BK4-530 are available as option
17) % and %: bridge completion adapters BR4-D-120/BR4-D-350 are available as option
18) only 2 quadrature four wire counters can be used, or 4 standard, up/down or quadrature two wire counters
19) only 1 quadrature four wire counter can be used, or 2 standard, up/down or quadrature two wire counters
20) possible with optional adapter: ACC2-BNC (only for IEPE measurement)
21) possible for BR4-D module with optional DSUB-BNC adapter (only for voltage measurement)

| JS-N | E | ·AC | (2 | |
|------|---|-----|----|--|
| | | | | |



| 2 galvanically isolated universal analogue input channels | voltage: $\pm 60 \text{ V}, \pm 10 \text{ V}, \pm 1 \text{ V}, \pm 100 \text{ mV}$ current: 025 mA potentiometer, resistance: 100 kΩ, 4 kΩ, 400 Ω Pt100 & Pt1000: -200850 °C thermocouple types: B, E, J, K, L, T, U, N, R, S bridge: $\pm 2.5 \text{ mV/V}, \pm 500 \text{ mV/V}$ (@ 2.5 V excitation) IEPE sensors: $\pm 10 \text{ V}$; constant current 4 mA |
|---|--|
| Resolution | 24-bit |
| Sampling rate | 10 kHz per channel (thermocouple 8 Hz) |
| 2 digital I/O channels | input: state, tare, memory reset / output: state alarm, threshold / voltage: max. 30 V |
| Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| TEDS | class 1 and class 2, according IEEE 1541.4 |
| Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V |

| DS- | DS-NET-CFB2 | | | | | | |
|---------|---|-----------|-----|--|---|--|--|
| Carrier | Carrier Frequency and AC/DC Bridge Module | | | | | | |
| U | | Ū | 7 | 2 isolated analogue input channels | Strain gauge and inductive measuring bridges (full, half, quarter), LVDT, RVDT | | |
| E | Ł | \subset | | DC and carrier frequen- cy (CF) principle | DC excitation, 600 Hz CF excitation, 4.8 kHz CF excitation for bridges | | |
| 1 | 17 | | | 2 analogue output | Voltage ± 10 V, 10 kHz | | |
| ~ | Š. | \sim | 🛃 🔹 | Resolution | 24 bit | | |
| < | \diamond | M | | 2 digital I/O channels | input: state, tare, memory reset output: state, alarm, threshold | | |
| ÷ | U/I OUT | | | Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm | | |
| | | PWM | | Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V | | |

DS-NET-BR4

| Multiple Input Module | | | | |
|-----------------------|------------|---------|---|---|
| | 1. | | 4 galvanically isolated universal analogue input channels | voltage: $\pm 10 \text{ V}, \pm 1 \text{ V}, \pm 100 \text{ mV}$ current: 025 mA, potentiometer, resistance: $100 \text{ k}\Omega$, $4 \text{ k}\Omega$, 400Ω Pt100 &Pt1000: -200850 °C thermocouple types (not for BR4-D): B, E, J, K, L, T, U, N, R, S bridge: $\pm 2.5 \text{ mV/V}, \pm 500 \text{ mV/V}$ (@ 2.5 V excitation) |
| | | | Resolution | 24 bit |
| | 1 • | /)* O . | Sampling rate | 10 kHz per channel (thermocouple 8 Hz) |
| | | ð. o. | Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| | | | Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V |
| MIL MAN PWM | · | | Option | D-SUB connectors model: DS-NET BR4-D / Lemo 10 pin |

DS-NET-BR8

| Bridge Input Module | |
|---------------------|--|
| | |

| | 8 strain gauge | ± 1 mV/V, ± 5 mV/V guarter bridge |
|-----|--------------------|--|
| | input channels | ±2 mV/V, ±10 mV/V half-, full bridge ±2 mV/V, ±10 mV/V half-, full bridge excitation: 2V, 4V selectable selectable shunt: 100 kOhm full, half and quarter bridge 3-, 4-, 5-, 6-wire |
| | Resolution | 24 bit A/D with AAF filters 1 kHz |
| 15 | Sampling rate | 10 kHz per channel |
| 0 2 | Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| 0. | Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V |
| | Option | adapter for screw terminal available |

DS-NET-V4

High Isolation Voltage Module



| 7 | - V4 | 7 |
|---|--------|---|
| 0 | | |
| Ó | BUDDE | |
| Ó | NAME | • |
| 0 | 1 DEBE | |

| 4 galvanically isolated input channels | Voltages at high potential, ranges 100 mV, 1 V, 10 V current via an external shunt |
|---|--|
| Resolution | 24 bit |
| Sampling rate | 10 kHz per channel |
| Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| Galvanic isolation | 1200 V short-term 5 kVpk |
| Option | BNC connectors model: V4-B |

DS-NET-V4-HV

High Voltage Module



| 4 galvanically isolated input channels | Voltages, range 40 V, 120 V, 400 V, 1000 V |
|---|--|
| Resolution | 24 bit |
| Sampling rate | 10 kHz per channel |
| Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| Galvanic isolation | 1200 V short-term 5 kVpk |
| Option | HV BNC connector cable |

DS-NET-V8

| Voltag | e Modul | e | | | | |
|----------|---------|-----|---|-----|---|---|
| U | 1 | 1 | | | 8 galvanically isolated input channels | differential voltage ± 10 V , current via shunt 25 mA (V8-SHUNT - not for V8-B), common mode voltage: 100 V permanent |
| 5 | E | | | | Resolution | 24 bit |
| <u> </u> | 4 | | | 0 | Sampling rate | 10 kHz |
| 1 | | | | 0 | 2 digital I/O channels (not for V8-B) | input: state, tare, reset output: state alarm max. 30 V |
| \sim | \sim | _ | | 0 | Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm |
| <u> </u> | U/L | | | 0 | Galvanic isolation | of I/O-signals (each channel), power supply and interface / isolation voltage 500 V |
| | | PWM | - | 0.1 | Option | BNC connectors model: DS-NET V8-B |

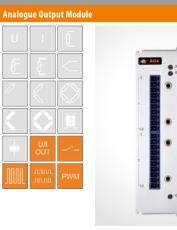
DS-NET-V8-200 Voltage Module

| e | | | |
|-------------------|----|---|---|
| | -7 | 8 galvanically isolated input channels | isc |
| | | Resolution | 24 |
| | • | Sampling rate | 10 |
| $\langle \rangle$ | | Signal processing | lin |
| | | Galvanic isolation | of |
|][| | Guivanic Isolation | iso |
| | | | |
| PWM | | | |
| | e | | B galvanically isolated input channels Resolution Sampling rate |

| 8 galvanically isolated input channels | isolated differential input voltage ±200 V | |
|---|--|--|
| Resolution | 24 bit | |
| Sampling rate | 10 kHz | |
| Signal processing | linearisation, digital filter, average, scaling, min/max storage, RMS, arithmetic, alarm | |
| Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V | |

| Digital Input/Output Module | | |
|-----------------------------|---|---|
| | 8 digital inputs and 8 digital outputs | configurable as counter, frequency, PWM and time inputs, frequency or PWM output, state in or output |
| | State in- and outputs | process- and host controlled, programmable threshold |
| | Frequency in- and outputs | frequency measurement up to 1 MHz (Chronos method), frequency output up to 10 kHz |
| | Counter | forward/backward counter, quadrature counter with reference zero recognition (reset/enable), up to 1 MHz |
| | PWM in- and outputs | measurement of duty cycle and frequency, output with variable frequency and/or duty cycle |
| | Time measurement | |
| • | Galvanic isolation | of I/O-signals (group/group), power supply and interface isolation voltage 500 Veff |

DS-NET-A04



| 4 galvanically isolated analogue outputs | voltage ± 10 V, current 420 mA selectable | |
|---|---|--|
| DAC resolution 16 bit | 10 kHz sample rate | |
| 4 digital input and 4 digital output channels | configurable as 2 counter, 2 frequency, or 2 PWM inputs, 2 frequency or PWM output, state in- or output, max. 30 V | |
| Frequency in- and outputs | frequency measurement up to 1 MHz (Chronos method), frequency output up to 10 kHz | |
| Counter | Forward/backward counter, quadrature counter with reference zero recognition (reset/enable), up to 1 MHz | |
| PWM in- and output | measurement of duty cycle and frequency, output with variable frequency and/or duty cycle | |
| Time measurement | | |
| Outputs freely scalable | | |
| Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V | |

DS-NET-TH4

High Isolation Thermocouple Module

| U | | Ĺ | The second se | 4 galvanically isolated input channels | for non-isolated thermocouples at high potential |
|---------------------------|-----------|-------------------|---|---|---|
| Æ | Ł | < <u>4</u> | *: 123 @ | Cold junction compensation | internal |
| 1 | \langle | $\langle \rangle$ | | Dynamic linearisation | Optimum positioning of interpolation points in selected range, types B, E, J, K, L, T, U, N, R, S programmable |
| // | | | | Resolution | 24 bit |
| $\mathbf{x}_{\mathbf{x}}$ | | - | | Sampling rate | 10 kHz per channel |
| | U/I | | | Signal processing | digital filter, average, scaling, min/max storage, arithmetic, alarm |
| | | PWM | | Galvanic isolation | 1200 V short-term 5 kVpk |

DS-NET-TH8

Thermocouple Module



| 8 galvanically isolated input channels | thermocouples and voltages in the range of ± 80 mV, common mode voltage: 100 V permanent | | |
|---|---|--|--|
| Cold junction compen- sation | DS-NET TH8-C: internal DS-NET TH8: TH8-CJC connectors available (option) | | |
| Dynamic linearisation | Optimum positioning of interpolation points in selected range, types B, E, J, K, L, T, U, N, R, S programmable | | |
| Resolution | 24 bit | | |
| Sampling rate | 100 Hz per channel (~8 Hz with activated mains rejection) | | |
| Signal processing | digital filter, average, scaling, min/max storage, arithmetic, alarm | | |
| Galvanic isolation | of I/O-signals (each channel), power supply and interface isolation voltage 500 V | | |
| Option | DS-NET TH8-C: with integrated CJC | | |

SOFTWARE

DS-NET OPTIONAL MODULES:

DS-NET-CAN2 CAN Bus Input Module

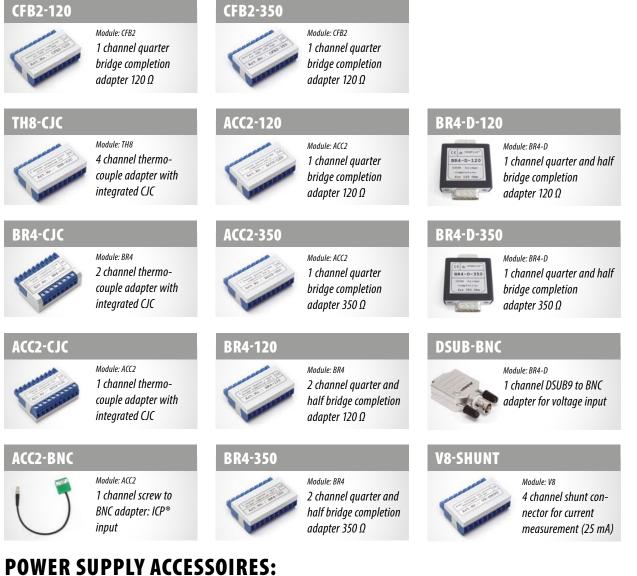
2 high speed CAN interface channels, up to 1MBit/s Isolated CAN input 500V OBDII, 11939, CAN output Supports CAN 2.0b standard Functions: send, receive, listen (silent), buffer

max. 2 modules connected to one DS-NET CPU

DS-NET-SUPPLY / - BNC Sensor Power Supply Module 4 galvanical

| 4 galvanically isolated DC sensor supply voltages | +5 V, +12 V, +15 V, +24 V |
|---|---|
| Voltages combina- tions | the voltages can be can be con- nected to get any possible voltage combination (e.g. 17 V, 20 V,) |
| Supplied Power | 5 W per output voltage |
| Galvanic isolation | each voltage is galvanically isolated with 1.5 kV |
| Only one SUPPLY mod | ule can be used per DS-NET system. |
| | isolated DC sénsor supply voltages Voltages combina- tions Supplied Power Galvanic isolation |

DS-NET OPTIONAL CONNECTOR – ADAPTERS:



CAR-UPS-3 BATTERY/UPS BOX WITH ISOLATED SUPPLY

96 Wh Li-lon battery, Input range: 9-36 VDC Output voltage: 24 V (powered); 14 V (battery) Maximum output power: 80 W

Operating temperature -20 $^{\circ}$ C to +60 $^{\circ}$ C discharge/UPS mode (0 $^{\circ}$ C to 40 $^{\circ}$ C charge mode)



Software

Software MEASUREMENT INNOVATION WITH DEWESoft® X



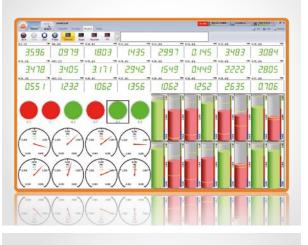
DEWESoft[®] data acquistion software is the solution to acquire signals simultaneously from different sources (even with different sampling rates), display and store them in one file. With the postprocessing feature, all the powerful mathematic and analysis functions can also be used for the already stored data.

With the focus on our own powerful hardware, the release of the innovative DEWESoft[®]X software leads to improved, intuitive operability, shortened setup time and reduced setup mistakes. This avoids repeating measurements, which saves time and money.

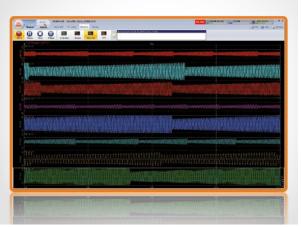
Data Acquisition

FREELY CONFIGURE YOUR INSTRUMENT SCREEN:

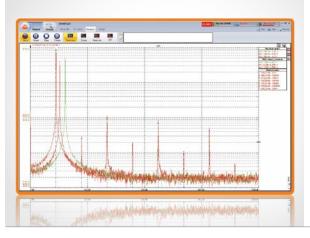
Digital and Analogue Meter



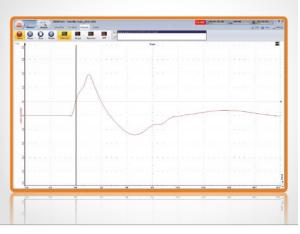
Recorder



FFT Analyser



Scope Mode/Trigger



In- and Outputs

ANALOGUE INPUTS



Voltage, current, temperature, vibration, strain gauges

DEWESoft[®] X offers the interface to all DEWESoft® instruments like DEWE-43A, DS-NET, SIRIUS. The perfect match of DEWESoft® hardware and software allows powerful technology like high dynamic dual-core AD, auto-detection, TEDS and many more. Up to 2000 analogue channels with sampling rates from kS/s to MS/s up to 24 bit vertical resolution are supported.

VIDEO INPUT

cameras



For applications requiring video which is truly synchronized to the dynamic sample rate, there is support for DS-Cameras. A high quality image with automatic shutter speed (selectable) is controlled directly by the A/D card, which generates a pulse to drive the camera. The result is a stunning correlation between each frame and the data.

Thermo cameras are supported from FLIR, NEC and MICRON, and high speed cameras from Photron which can acquire more than 100000 frames per second.

VEHICLE BUS INTERFACES



J1939 and J1587 interface support

| Table | TOBALS1 | 100.00 |
|------------|-------------------------|-------------------------|
| 20121-202 | | 00 54 88 FC F0 00 30 54 |
| 28127,996 | 22 29 24 AE 34 82 94 78 | |
| 20-27.808 | 10 50 13 ME BC 41 14 72 | |
| 89:97,970 | | 60 E4 D6 PT 70 60 80 83 |
| 121-37.514 | 29 40 22 A8 P0 40 94 30 | |
| 12:37,918 | 96 MA 20 AE 20 80 94 18 | |
| 521-37.905 | | 86 E4 CE FC F0 68 90 23 |
| 10:37.354 | 28 15 15 10 10 17 14 15 | |
| N- acor ev | <u></u> | - A |
| | -ff | |

One of the most important vehicle buses today is the CAN (controller area network) bus. DEWESoft® X supports following CAN devices: DEWE-43A, DS-NET, DS-CAN-2 and SIRIUS. Today the CAN bus is present in cars, trucks, boats, tanks, tractors, harvesters and basically anything which has a modern engine built in.

GPS INTERFACES



Advanced GPS support and capabilites



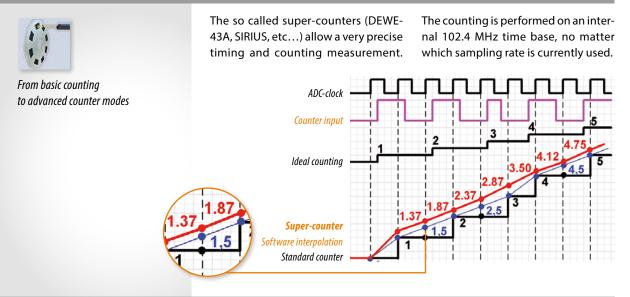
GPS technology is used in three main application areas: to find the position on earth, to determine the velocity of an object and to get precise absolute time information. DEWESoft® X uses all three areas. For basic positioning, DEWESoft® supports NMEA GPS interfaces. If you have a GPS receiver which sends the data according to NMEA specification, it will work in DEWESoft® up to a real-time rate of 500 Hz.

AEROSPACE INTERFACES



PCM telemetry, ARINC, chapter 10 and MIL-STD-1553 interaces support Aircrafts as well as space vehicles such as the US Space shuttle acquire onboard data, digitize them, then send the data to ground stations. They do this via pulse code modulated data stream, also known as PCM. DEWESoft[®] supports the Ulyssix Tarsus PCM-01 card to decode, visualise and store this PCM data. The data is equipped with an IRIG clock time stamp and therefore can be matched to the analogue FM channels, video channels, and other data sources. For more info, see the PCM data solution report.

COUNTER INPUTS



DEWESoft® KEY FEATURES

- ▶ Perfect sync of analogue, digital, counter, CAN, GPS, Video, ARINC, 1553 data . . . and even more
- ▶ Fast and easy setup of all kinds of input channels
- ► Failsafe and simple sensor setup by TEDS or sensor database
- ▶ Powerful online data processing, MATH functions, filters, statistics, reference curves
- Attractive online display of all kinds of data, creation of displays is a matter of seconds
- ▶ Various storing strategies, stream data to hard disk (160 MB/s and more), triggered storing or database storing
- Analogue, digital or CAN data output, powerful function generator, alarms, CAN messages
- Build test procedures in a form of workflow diagram by means of our sequencer
- ▶ Fast data analysis, reload GB files in seconds
- ▶ Post processing the data files is possible on any computer, even without any license
- Ready to use applications, Power calculations, Combustion analysis, Torsional Vibration, Order tracking, Sound analysis, Frequency response function, Human vibrations, Balancing ...

Recording/Control Solutions



The DEWESoft[®] KRYPTON data recorder are widely used for high speed and low speed signals from mHz to MHz. DEWESoft[®] offers a wide range of signal amplifiers and A/D converters in different chassis. The DEWESoft[®] software offers ease of use and sophisticated online and offline mathematic functions.

The flexible DS NET system even offers real time control solutions with guaranteed response times (no Windows[®] operating system involved). Simple PLC or sophicticated PID controller applications are available.

MAIN FEATURES: RECORDING

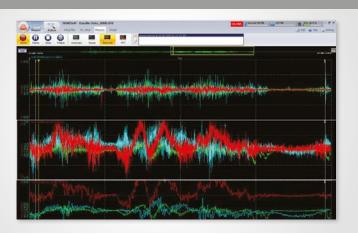
- ▶ Multi sensor input
- ▶ Distributed systems
- ► Easy to use software
- ► Advanced triggering to capture events

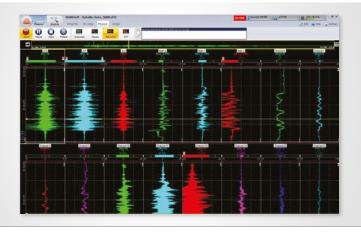
MAIN FEATURES: CONTROL

- ▶ Real time alarms, PID
- ► Fixed low latency
- ▶ High speed (10 kHz)
- ▶ Stand alone operation
- ⊾ Reliable

DATA RECORDING

Instead of printing to paper, your data are streamed directly to a hard drive. DEWESoft®'s unique capability to store the data with over 160 MB/s will never let you lose your data even when recording hundreds of channels at the same time. You can start storing as easily as pressing the STORE button, or as elaborately as having separate - even multiple, triggers on each input channel. Recorder chart screens in DEWESoft® can be either vertical or horizontal, it's your choice.





TRIGGERED STORING

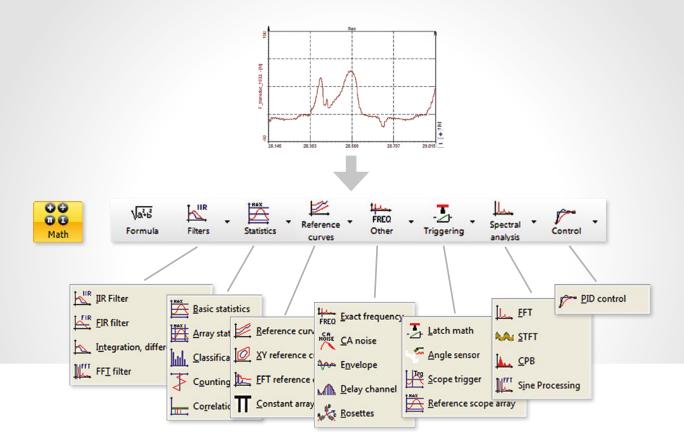
Quite often the system needs to monitor the data for several days or weeks, looking only for very specific events. Store all the data to the hard drive and then searching for these events is of course a bad idea. To avoid this DEWESoft[®] offers an extensive triggering feature– we can use start/stop triggers and use pre/post time for triggering. The trigger conditions can be:

- **Simple edge:** either rising or falling slope
- **Filtered edge:** edge plus rearm level either slope
- ► Window trigger: two levels entering or leaving logic
- **Pulsewidth trigger:** longer or shorter than duration logic
- ▶ Window and Pulsewidth: completely selectable as above
- ► **Slope Trigger:** either rising or falling slope with steepness selection

SOLUTIONS FOR TYPICAL RECORDING APPLICATIONS

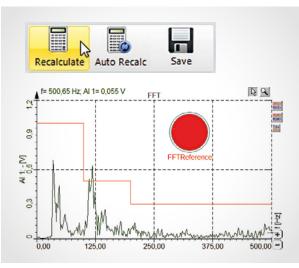
| Application | Description |
|-------------|--|
| Automotive | In-vehicle: ride handling, brake tests, steering performance, evapo, fuel efficiency, passanger comfort, |
| Military | Portable recording and troubleshooting, system performance, shock and vibration, |
| Industrial | Machine diagnostics, advanced triggering on failure conditions |
| Paper/Pulp | Tension monitoring, (also use camera to record machine operation) |
| Metals | Monitor power systems, closed-loop systems test, process monitoring and recording |
| Power | 3-phase analysis (50, 60, 400 Hz), circuit breaker & fault monitoring |
| Medical | Chemical tests, pharmaceutical manufacturing, process monitoring |
| | |

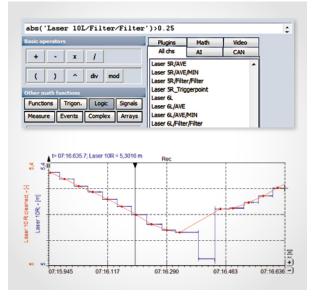
Data Processing Capabilities



Over the past years we have covered lots of application areas with expert modules, so that the user is only a click away from the total solution. But also the standard mathematic is very powerful, and sometimes underestimated.

With the new post-processing capability, the data processing power can also be used on already stored data files. Just record raw data and apply the mathematics later! Imagine you have a big data file of a long-term battery test. With the formula mathematics you can define logical conditions (e.g. if current > 10A AND temperature > 70° C) to quickly find the positions you are interested in. By the way, it's also possible to exclude faulty data points, such as spikes, just by defining logical conditions.





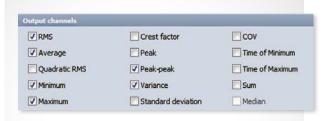
Furthermore, often used functions like delta time measurement between two signal edges, counting how often conditions appear, or holding the signal value on a condition and many more are already prepared. Use the complex section to split a signal into real and imaginary part, while the array section is used e.g. to cut arrays or determine min/max and their positions.

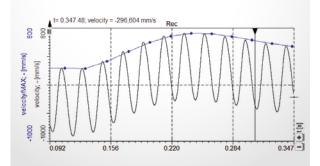
Sometimes, when you experience noisy sensor output or when the desired signal band is overlapped by other major frequencies, filtering appears on the scene. The major advan-

IR Filter Letur 55 Low pass 6 07:13:511:4: Laser 10R = 5:2731 r 5,277 hellite alley IRO/Laser 10R/Filter, - (-) Ξ 10R _ase_ 5,2512 t s + 07:13.454 07:13.469 07:13.483 07:13.498 07:13.512

tage of the FIR filter is no phase delay in pass band, the IIR filter is used for doing integration (acceleration -> velocity -> displacement) or derivation, the FFT filter completes the picture.

Statistical function are mainly used for calculating RMS, AVG, MIN, MAX... on time or sample base, or overall. Variance, standard deviation and higher sophisticated functions such as classification and counting are also supported; even working with array data – which can come e.g. from an FFT analysis.





MATH FEATURES

- ▶ Filtering (FIR, IIR, FFT filter, integration, derivation, ...)
- ► Logical conditions
- ▶ Basic Statistics (RMS, AVG; Min, MAX, ...)
- ▶ Advanced Statistics (Std deviation, variance, classification, counting . . .)
- Reference curve (time, XY and frequency domain)
- Converting time-based to angle-based domain (resampling)
- ► Envelope function
- Delay channel (previous value, delta-calculation)
- Latching (hold value on certain condition)
- ▶ Angle sensor math (convert analogue input signal from tacho probe to freq. + angle)
- ▶ Scope trigger
- Spectral Analysis (FFT, STFT, CPB, SineProcessing)

DEWESoft® X Features

CREATING SMART SENSORS (TEDS)

Now it is possible to create "smart sensors" inside DEWESoft[®]. Just equip the sensor with a chip, and store scaling, offset, calibration data ... according to the TEDS standard – and beyond! DEWESoft[®] X additionally stores the amplifier settings to the chip: just connect the sensor, everything is set up and you can start the measurement!

| albration date | 18.11.2 | 2012 | 0- | |
|---|---------|--------------|------|---|
| albration period | 730 | Cal initials | KS | |
| Allow user to defi Write channel nar | | or | | |
| Save sensor | | Write to | TEDS | ш |

AUTO-DETECTION OF HARDWARE

When plugging in the USB connector, the power and synchronization status of the system is checked and displayed. This self-check helps identifying if all cabling is done correctly.



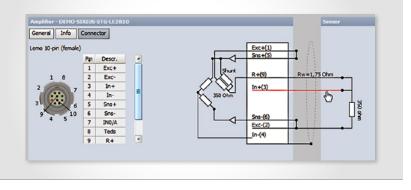
CHANNEL SETUP GRID

Just double click one amplifier in the picture of the system configuration shown on the left: the channel setup will open. Select multiple channels to set them to e.g. IEPE mode. In bigger systems use the search field to quickly find the wanted channel.

| 100000 · Prec. span: 32000 Hz | Select | al De | select | all Balance ser | nsors Balance any | plifiers | Short on | Shu | nt on \$1 | hunt cal check. | Zero al | Reset | le ons |
|----------------------------------|--------|--------|--------|-----------------|-------------------|----------|------------|-----|-----------|-----------------|----------|-------|--------|
| Haleh) 💽 | Search | _ | G |] | | | | | | | | | |
| evice preview | ų | Used | c | Name | Ampl. name | . H | easurement | | Rang | e 🔳 | Physical | qua. | Units |
| | A-1 | Unused | | AI 0 | SIRDUS-ACC | ٧ | oltage | | 10 V 01 | | | | ٧ |
| | A-2 | Unused | | AI 1 | SIRJUS-ACC | V | oltage | | 30 V 06 | | | | v |
| 666666880 | A-3 | Used | | AI 2 | SIRJUS-ACC | V | oltage | Ŧ | 10 V | | | | ٧ |
| | A-4 | Used | | AI 3 | SIRJUS-ACC | 8 | Voltage | | | | | | ٧ |
| | A-5 | Unused | | AI 4 | SIRJUS-ACC | | IEPE | N | | | | | v |
| | A-6 | Unused | | AI 5 | SIRJUS-ACC | v | oltage | -13 | 20 V | | | | ¥. |

CONNECTOR WIRING DIAGRAMS

Depending on the used amplifier and operation mode, the correct connector pinout and the needed connections to the sensor are shown. No need to search for additional documents.



Many more small features are built in.

Go to http://www.dewesoft.com/download and get a 30-days-evaluation license with all features.

Fast Data Storing

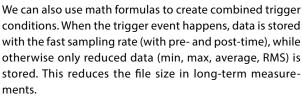
Through the entire history of DEWESoft® the performance in storing was one of the most important issues. The PC technology has advanced through the years and we are using all possible resources to get more from the system. We achieve more than 160 MB/second sustained stream rates. Even with such high rates, DEWESoft® prepares the data to be reloaded in a matter of seconds.

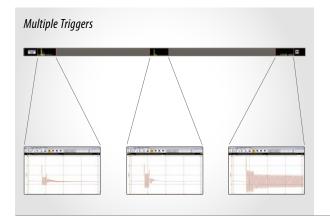
STREAMING

With a very specific data file structure we can write the channel setup, display setup, all the events, fast analogue data and slow asynchronous data from different sources in a single file. For long term measurement DEWESoft® offers to roll-over the file automatically when certain file size is reached or after a specified time (for example after 24 hours the current file is closed and a new one is created automatically). DEWESoft® makes sure that no data is lost during the file roll-over.

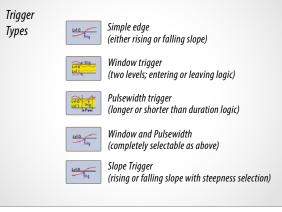
TRIGGERED STORING

Quite often the system needs to monitor the data for several days or weeks, looking only for very specific events. Store all the data to the hard drive and then searching for these events is of course a bad idea. To avoid this DEWESoft® offers an extensive triggering feature - we can use start/ stop triggers and use pre/post time for triggering.





ments.



DATABASE STORAGE

For applications which require long term storage and off line post processing, DEWESoft® offers a database storage solution where accumulated data is sent to a remote database server. The slow speed data is stored continuously

and in case of a trigger event the full speed data is acquired and stored. Database storage is mainly used for distributed applications.

Distributed Acquisition with DEWESoft®-OPT-NET

With the OPT-NET option your measurement system can be controlled remotely with ease of use you couldn't imagine before. OPT-NET also serves as the center of Distributed Data Acquisition systems where you have multiple systems located either together or scattered across an entire continent. IRIG and GPS time will take care that data will stay synchronized, no matter how long the acquisition runs. OPT-NET offers three basic modes of operation (1:1 mode, x:1 mode, 1:x mode). With these three modes almost any application can be covered. From single channel expansions over remote control to distributed measurements over hundreds of kilometers - everything is possible.

1:1 MODE

1:1 mode works with single measurement system and single client. In this mode there are two types of operation: full remote control and data view only. In full remote control

the client computer acts as the master of the measurement system. When the master client changes to the setup screen, the measurement system also changes to setup screen.



X:1 MODE

Multiple measurement systems and a single client are used in case of distributed measurements or if the acquisistion rates are too high to be managed by a single measurement unit. The measurement systems have to be clock-synchronized either with hardware clock (one unit is the clock master, the others are slaves) or with an external clock source which is either IRIG or GPS. sition rate. In this case only one connection option is possible – the client is always the master. It starts and stops the measurement on all units in the measurement network. At any time the client has access to view mode - but only to one measurement system (one-to-one connection like in single measurement system & single client configuration). Additional view devices are possible, but they can access only a single measurement system.

All measurement systems have to run with the same acqui-



1:X MODE

The third network configuration is to have a single measurement system controlled by one master client and additional view clients. The master client is able to change the measurement system setup, storing strategy, start and stop measurements, and many more. The view clients are only allowed to use a few channels from the measurement unit (up to the bandwidth limitation) and view and store the data on their local hard disk.



EXAMPLE SYSTEM

For bigger measurement tasks you can use the DEWESoft®-OPT-NET option to combine several measurement units to one big system of up to 1000 channels and more: simply connect them via GLAN and sync. And if the measurement is done, just disconnect and use each one independently again. The load can be distributed over the individual SBOXes. And since each SBOX has more than enough power, even for most demanding math operations of its 32 channels, all performance problems belong to the past! The SBOX supports also 1 Hz (for precise time sync) or 100 Hz GPS receiver with Real Time Kinematic option for < 2 cm position accuracy.



Analyse and Publish

Even though the main focus of DEWESoft® is on data acquisition and storage, it also offers powerful analysis features including post processing.

The file preview of DEWESoft® is completely free of charge, so DEWESoft® can be downloaded and used for file preview without any cost or license.

One of the most outstanding feature of DEWESoft® is that data files, even if they are several gigabytes in size, are loaded in a matter of seconds. A special data structure allows fast reloads and zooming. You can select any part of the data in the recorder and zoom in to show all the interesting details.

EXPORT DATA

Since the main focus of DEWESoft® is on data acquisition and storage, it has extensive support for exporting the data to other file formats for post processing. You can choose different export file types, use scripting for direct reporting and export raw, reduced or angle based data.

DEWESoft® offers templates with Flexpro, MS Excel® and Famos. These templates allow you to prepare the reports

Supported data formats are:

- ▲ Microsoft Excel[®]*
- ▶ Flexpro*
- ⊾ Text

once and execute them after DEWESoft® data export. In this way you can automate report generation and simplify the measurement process.

Alternatively you can export your measurement screen to AVI. This allows to replay the file with every standard video player without the need of installing DEWESoft®.

⊾ UNV ▶ WAV ► CSV ► FAMOS ▶ Google Earth[®] KML ► TDM ⊾ BWF ▶ TDF ▶ NSOFT ► ASCII ▲ Sony[®] ⊾ ATI ▶ and more ... ► RPC III ⊾ SDF ► MATLAB® ▶ WFT ▶ Diadem® ▲ Comtrade[®] * export only possible if the program is installed on the measurement PC

REPORTS

When you are reviewing data in the analyse mode, you can make hard copies as easily as clicking the Print button in the top toolbar. Any display can be directly printed to PDF or printer. Even if we have black background as default, DEWESoft[®] will invert the colors to be printer friendly. Even the channel setup can be printed for documentation purposes.



REPLAY

To get an impression how the measurement was done, especially when we have video streams in the measured file, DEWESoft® offers file replay capabilities. We can choose a specific portion in the file and replay the data with the same speed as it was stored or with higher/lower speed. For example it is very interesting to view high speed videos in slow-motion.

DEWESoft® does not only show the data, but it can also replay the data through sound card. Any channel can be chosen for replay through speakers.

DEWESoft® can also replay data of any channels through SIRIUS AO8 option.

INSTRUMENTS

APPLICATIONS

DEWESoft® X VERSIONS

| | EVALUATION | PROFESSIONAL | DSA | ENTERPRISE | AUTOMOTIVE |
|---|---|--------------|----------------|----------------|----------------|
| High speed acquisition cards | | _ | | _ | _ |
| DEWESoft* | FREE | FREE | ✓ | ✓ | ✓ |
| Low/medium speed acquisition devices | | | | | |
| DEWESoft® DS-NET | ✓ | ✓ | ✓ | ✓ | ✓ |
| CPAD | ✓ | ✓ | ✓ | ✓ | ✓ |
| Signal conditioning | | | | | |
| DEWESoft [®] instruments | FREE | FREE | ✓ | ✓ | ✓ |
| Other sources | | | | | |
| CAN/J1939 devices | ✓ | option | option | ✓ | ✓ |
| GPS receivers | ✓ | ✓ | ✓ | ✓ | ✓ |
| DEWESoft [®] timing devices | ✓ | ✓ | ✓ | ✓ | √ |
| Gyro platform | ✓ | option | option | option | √ |
| Kistler wheels | ✓ | option | option | option | √ |
| J1587/J1708 devices | ✓ | option | option | option | ✓ |
| Flexray | ✓ | option | option | option | ✓ |
| XCP interface | ✓ | option | option | option | \checkmark |
| PCM telemetry | ✓ | option | option | option | option |
| ARINC/1553 devices | ✓ | option | option | option | option |
| ScramNET | ✓ | option | option | option | option |
| XSENS Gyro | \checkmark | option | option | option | option |
| NMEA weather station | ✓ | option | option | option | option |
| Aerospace Chapter 10 | ✓ | option | option | option | option |
| Modbus protocol support | \checkmark | option | option | option | option |
| Cameras | | | | | |
| DirectX cameras (webcam) | \checkmark | ✓ | ✓ | ✓ | ✓ |
| DS-CAM | \checkmark | ✓ | ✓ | ✓ | ✓ |
| GIGE cameras | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| Basler camera | \checkmark | ✓ | \checkmark | ✓ | \checkmark |
| Photron hi-speed | \checkmark | option | option | ✓ | option |
| Micron IR cameras | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| FLIR thermovision camera | \checkmark | option | option | option | option |
| Video post synchronization | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| Other | | | | | |
| Sensor database | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| TEDS support | \checkmark | ✓ | \checkmark | \checkmark | \checkmark |
| Outputs | | | | | |
| Alarm monitoring | \checkmark | ✓ | \checkmark | ✓ | \checkmark |
| Analogue replay of data | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| CAN output | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| Multichannel function generator | \checkmark | option | option | ✓ | - |
| Online/Offline Math | | | | | |
| Formula editor, Filters, Statistics, Reference curve, Latch, Combustion noise, Angle sensor math | \checkmark | ✓ | ✓ | ✓ | \checkmark |
| Human body vibration | ✓ | option | ✓ | ✓ | option |
| Order tracking | \checkmark | option | ✓ | √ | option |
| Torsional vibration | \checkmark | option | ✓ | √ | option |
| Sound level | ✓ | option | ✓ | ✓ | option |
| Power module | \checkmark | option | option | ✓ | ✓ |
| Combustion analyzer | \checkmark | option | option | option | option |
| FRF | \checkmark | option | ✓ | ✓ | option |
| SRS | \checkmark | - | ✓ | ✓ | option |
| Sound power | \checkmark | - | FlexPro script | FlexPro script | FlexPro script |
| Polygon vehicle dynamic test | ✓ | option | option | option | ✓ |
| Psophometer | ✓ | option | option | option | option |
| FUSI (functional safety) | ✓ | option | option | option | ✓ |
| Brake test | ✓ | option | option | option | ✓ |
| CAPS / ACC | ✓ · · · · · · · · · · · · · · · · · · · | option | option | option | ✓ |
| Energy calculation | ✓ · · · · · · · · · · · · · · · · · · · | option | option | option | ✓ |
| | | • | | · · | |

Database storing

The Online Data Export (ODE) plugin can export DEWESoft® measurement data during storing directly to a database or to .csv files (that can later be imported into the database), so

that the data can be used for statistical analysis or real-time analysiss of production status.

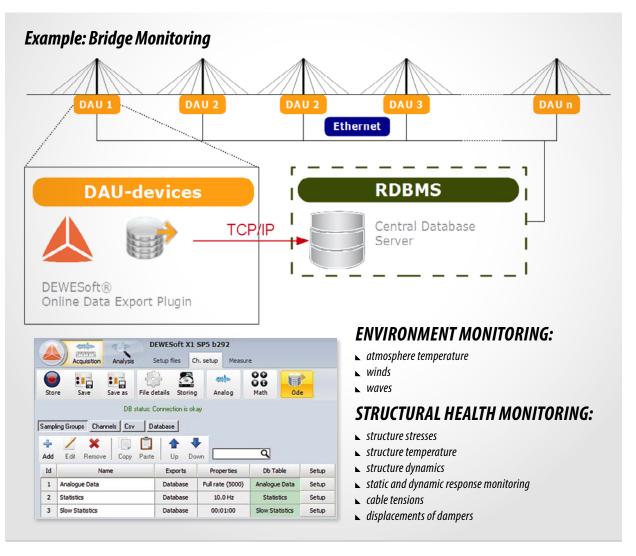
SCOPE

The ODE plugin will store the measurement into the database. The customer may use any visualisation or analysis tool that can access the data in the database. DEWESoft® does not offer any visualisation or analysis features or programs.

1. PERMANENT DB STORING

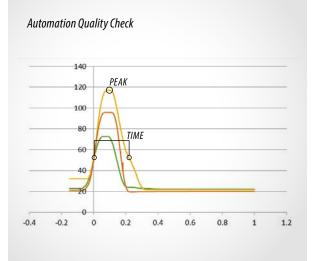
REALTIME MONITORING

The ODE plugin is well suited for realtime monitoring over long periods of time: i.e. store slow analogueue or statistical data continously into your database to monitor the conditions of the measuring object.



PROCESS MONITORING

The ODE plugin stores the production data continously into the database, so that real-time analysis, statistical analysis



Supported Database Systems

Currently the ODE plugin supports MySQL® and Microsoft SQL Server® databases. Other databases (e.g. Oracle®, PostgreSQL®, ..) can also be supported on customer demand (please ask our sales departement for a quotation).

Performance

Storing data into a database is not as fast as storing data into a file (e.g. DEWESoft[®] datafile or .csv file). The maximum possible amount of data is highly dependant on your database software, database server (hardware) and on your database design.

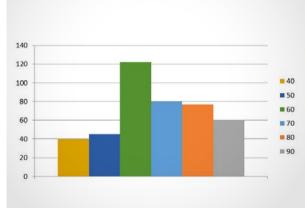
Example:

- ► Hardware: i7-2630QM CPU @ 2.00GHz, Samsung 840 Pro SSD-drive
- ▶ Software: Windows 7 64-bit, MySQL server 5.6
- ▶ Continously store 100 channels @ 5000Hz



and reporting on the measurement data are possible on customer request.

Statistic Analysis



TYPICAL APPLICATIONS

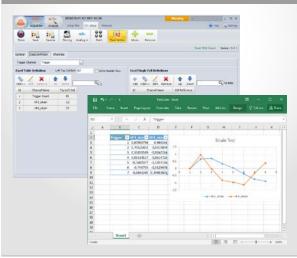
- **Cycle based manufacturing**
 - ▶ Pressing Machine
 - ▶ Turbine Blade Quality Control
 - ▶ Injection Modling Quality Control
- Predictive Maintenance
 - ▶ Machine Durability
 - ▶ Machine Reliability



Plugins

REPORT

EXCEL WRITER



Write data to Excel[®] during measurement

The Excel® Writer plugin can write numeric and textual DEWESoft® data during maeasurement to Excel®. You can select a trigger channel and define which channels should be written to Excel®. Whenever the trigger fires, the data will be written to Excel® and can be show immediately: e.g. display in a chart or do real-time calculations (check values, use conditional formatting, etc.).

The plugin requires Excel 2007 or higher.

- ▶ write data to Excel[®] during measurement
- ▶ supports numeric and textual channels
- ▶ customer defined trigger channel
- ▶ Excel[®] can then use the data for online calculations, charts, etc.

ONLINE DATA EXPORT

| 14 | -0000 | 4 P | DEWES | Soft X1 ! | SP5 b29 | 92 | | | |
|------------|--------------------|-----------|----------------|------------------|-------------------|--------------------|--------------------|--------|-------|
| | Acquisition | Analysis | Setup | files Ch | n. setup | Measu | re | | |
| Stor | re Save | Save as | File details | Storing | Ana | te alog | 00 00 Math | Ode | |
| | | DB | status: Connec | ction is oka | w. | | | | |
| ampl | ing Groups Char | nnels Csv | Databas | e | | | | | |
| iampl 4 | ing Gioups Chai | | | e 1 Up Dov | | | ٩ | | |
| + | Z X Edit Remove | | Paste | ☆ ₹ | wn | erties | С. Db Та | able | Setup |
| + Add | Z X Edit Remove | e Copy | Paste B | Up Dov | Prop | erties 2 (5000) | | | Setup |
| Add Id | Edit Remov | e Copy | Paste B | Up Dov | Prop Full rate | | Db Ta | e Data | |

Export data during measurment to a database and csv files

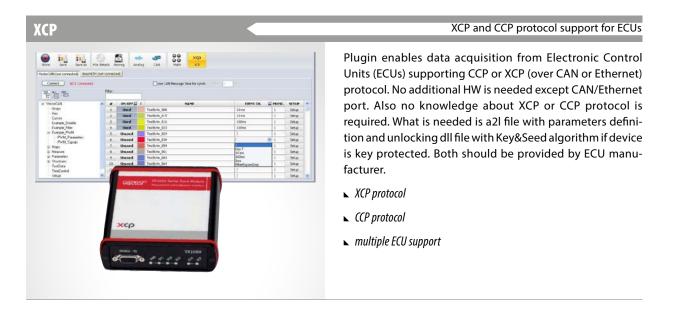
The Online Data Export (ODE) plugin can export DEWESoft® measurement data of numerical channels during storing directly to a database (currently MySQL® and Microsoft SQL Server® are supported) or to .csv files (that can later be imported into the database, Excel®, ...).

Note: array channels (like FFT) are not supported.

- ▶ write data during measurment to a database
- ▶ MySQL[®] and Microsoft SQL Server[®] supported
- ▶ write data during measurment to .csv files

| DEWESoft EXCEL REPORTING | I Add-in for loading and comparing multiple DEWESoft data file |
|--|--|
| INCLUENCESSE IN | DER is an Excel 2013 Add-In that can be used to create Excereports based on multiple DEWESoft® data-files. Feature use channel-data (full-speed or reduced), DEWESoft® heaer information and easily create charts. Time can be relating to the first trigger (use-case: Brake Test Reports). It also includes the DEWESoft® DER Auto plugin (automa cally start Excel to generate the report after you stop storing in DEWESoft®). <i>Access to channel-data (full-speed or reduced)</i> <i>DEWESoft® header information and easily create charts</i> <i>time can be relative to the first trigger (use-case: Brake Test Reports)</i> |

DATA INTERFACE



FLEXRAY PLUGIN

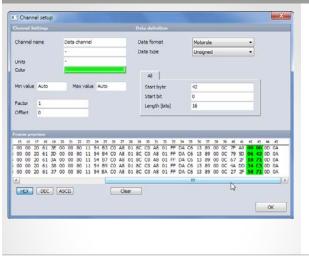


Plugin for FlexRay system bus with FIBEX support

Plugin for FlexRay system bus, with FIBEX library import option, mainly designed for use in automotive industry. All Vector FlexRay cards are supported.

- ▶ decodes FlexRay bus
- ▶ FIBEX support
- ▶ works with Vector FlexRay cards

ETHERNET RECEIVER



Ethernet sniffer with filtering capabilities and data decoding

Ethernet sniffer with simple filtering capabilities and data decoding in order to extract data channels from ethernet streams. Streams can be filtered by various parameters like MAC and IP addres, source and destination port or by manual data filters.

Supports many data encodings: intel, motorola, signed, unsigned, IEEE float:

Linear and non-linear (polynomial) scaling is possible.

- can receive multiple ethernet streams
- ▶ different filters capabilities (TCP/IP, UDP, data filter,...)
- ▶ data decoding with various formats (intel, motorola, float, signed,...)
- ▶ linear and non-linear scaling

| JENIALCOM | S | ERI | AL | .CO | Μ |
|-----------|---|-----|----|-----|---|
|-----------|---|-----|----|-----|---|

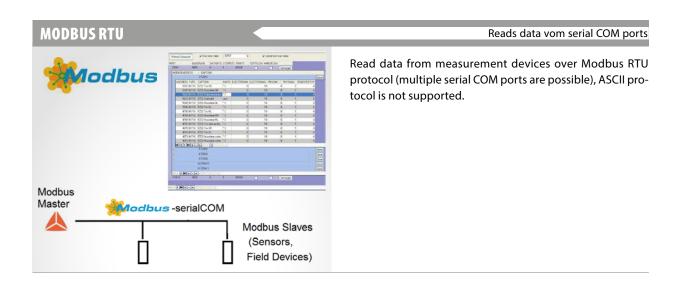
| Name | Wind S | peed and Angle | Startative | g: Vi | I De | pected Rate (Hz): 200.0 | | |
|-----------------|----------------|-----------------|------------|-----------------|----------|--------------------------|---------------------------|-------|
| 4 A55 | + 00 | Edt Remove Du | plicate | Copy Paste | to Down | Test Response: (\$1/24/0 | .265.R.5.7,M.A*30 | est |
| | Status | Name | Len | Data Type | | Device Data | Converted | _ |
| 1 | vald | D | W3M | Ignore response | | | | |
| 2 | vald | Wind Angle | | Numeric | 265 | | 265.000 * 1.00 + 0.0 = | 265 |
| 3 | vald | Reference | - | Text | R | | R | |
| 4 | vald | Wind Speed | - | Numeric | 5.7 | | 5.700 * 1.00 + 0.0 + | - 5.3 |
| 5 | blev | Wind Speed Unit | | Text | м | | м | |
| 6 | vald | Status | • | Text | A | | A | |
| 7 | vald | Check Sum | | NMEA-QUAD VD | CRC okay | | WIMWV, 265, R, S, 7, M, A | - |

Read and write via serial communication (RS232 & compatible)

A generic plugin for Serial Communication (RS232 and compatible). It can receive serial data and extract text or numeric data from the byte stream. You can also send data to the serial device (e.g. on start of storing or every X seconds, ...).

- ▶ Generic protcol definition (ASCII or Byte protocols)
- Read and write text from serial devices
- ▶ RS232 and compatible devices supported
- ▶ Check sum calculation possible (Check-sum, XOR, CRC)
- ▶ Automatic mode or polling

MODBUS TCP/IP CLIENT Read data from a Modbus server via TCP/IP The DEWESoft® Modbus TCP/IP plugin can read Modbus Dev2 Device channels over TCP/IP. It supports Boolean, Int16, Int32 and Bate (Hz) Float32 (including Word-Swap) datatypes. Note: writing to uts Holding Rea isters Input Registers the Modbus device is currently not supported. × 4 Edi Q 2 ▶ Read Coils and Registers Id Start Address End Addr 2025 65535 egisters 6553 Int16 ▶ Modbus TCP/IP Modbus Slaves ▶ Word-swap support (Sensors, Field Devices) Modbus Master dodbus-TCP read data Modbus TCP/IP Client



INET PLUGIN

Plugin

Reproducer settings

Device type

Input type

Port number

Enable multicast

Multicast IP address

:

Shown Shown

R

iNET Plugin

Version: 1.0.2 Vendor: Dewesof

INET reproducer

Etherne

224.0.0.0

ACQ ACQ ACQ 500 500 500

5555

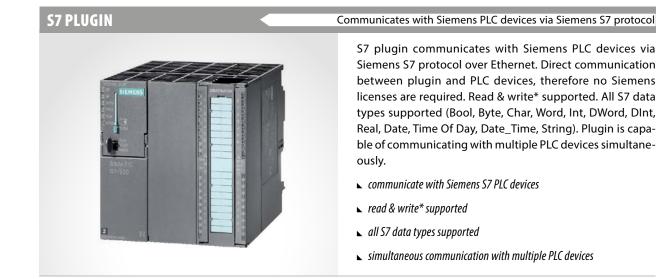
88

NET channel3 NET channel3

Captures iNET compliant data over UDP and stores it to DEWESoft

iNET plugin captures iNET compliant data using iNET network packet protocol. More specifically, the plugin complies with the TTC NPD data packet protocol version 3 which evolves towards compatibility with the iNET standard for network packet protocols. The NPD message protocol is an application-layer protocol that operates on top of the standard IPv4 over Ethernet network protocol and UDP transport protocol. Each NPD packet contains a 20-byte NPD Packet Header followed by one or more NPD Data Segments containing the actual data (such as ACQ carrying PCM analogue acquisition data). The iNET plugin can operate by capturing the iNET data from a local UDP port or by joining the specified multicast address and capturing a multicast iNET data stream.

- ▶ capture and store iNET compliant data
- autodect incoming iNET streams and data types
- ▶ capture data from local UDP port or by joining multicast session
- capture iNET data from multiple NICs- capture and store iNET compliant data



0

TCP/IP BINARY CLIENT

| tening fo | | nnected | | Update Data | a Show online values | | | | |
|-------------|---------|---------|---|----------------|----------------------|--------|-----|--|--|
| aterarag it | Ji Udid | | | Exit Command | | | | | |
| d L | Jacd | Stored | с | Name | Unit | Value | | | |
| 1 L | ised | Stored | | Temperature Ch | °C | 22.000 | [°C | | |
| 2 L | Jsed | Stored | | Sample Number | = | 22 | [#] | | |
| | | 19555 | | | | | | | |

External programs can send data to DEWESoft® via TCP/IP

The DEWESoft® TCP/IP Binary Client plugin can receive data from external applications (e.g. LabView, ...) via TCP/IP and add this data to DEWESoft® channels. The external application must send the data in the protocol specified in the documentation: i.e. the software-team of the external application must do some programming to make their application talk to this plugin.

- ▶ allows external programs to add data to DEWESoft®
- ▶ proprietary TCP/IP protocol

| | | Free defails Starting | Antros 97 Years 7 Partportors 17.70.2012 J.96.2210 12 Part postors 17.70.2012 J.96.2210 12 Part postors 17.70.2012 J.96.7310 03 Continuous Licolation Particle Continuous Licolation Particle 07.1225 | n Coule of Pairs | 07 15 Set dae paster) Set dae paster) | Ethernet sniffer with simple filtering capabilities and decoding in order to extract data channels from ethe streams. Streams can be filtered by various parameters MAC and IP addres, source and destination port or by nual data filters. |
|-------|--|-----------------------|--|----------------------------------|--|---|
| Index | Status | Name | Oata Type | tale | Setup | |
| | Unused 5 | letup Record | Computer Generated Data, Format 1 | THATS generated by bitmats | Set et. | Data can be encoded by different formats: intel, moto |
| 0 4 | | Necording Events | Computer Generated Brata, Formet 2 | No Cata | Set etc | - |
| | | 104E Channel-1 | Tene Data, Forvat 1 | 17.10.2012 7:60:60 | SH (t). | signed, unsigned, IEEE float: |
| | | 950-avel 2 | URAT Date, Formal 0 | 236.2 Of No of Al Channels, 1 | Set ch. | Linear and non-linear (net/memial) scaling is nessible |
| | and the owner of the owner, where the ow | WOR1_Channel1 | Video Date, Format 2 | Video Data | Set d). | Linear and non-linear (polynomial) scaling is possible. |
| 1 | - | | | | | capability to record and playback IRIG-106 Chapter 10 files capability to receive and send Chapter 10 UDP Ethernet packets complete, all-in-one processing and recording package |



ARINC 429 and MIL-STD-1553 protocol support

Handles multiple ARINC 429 and MIL-STD-1553 data-buses. It can capture, filter, display and record data bus traffic. It includes extensive possibilities to convert binary data to user recognizable format. In addition to read and store bus data it can also transmit data to the bus. It provides easy to use transmit schedule designer for ARINC 429 and frame designer for MIL 1553 bus controller functionality.

- ► AltaDT and Ballard HW support
- ▶ Chapter10 input support
- ▶ RX and TX support (ARINC 429)
- ▶ BM (bus monitor) and BC (bus controller) support (MIL 1553)

PCM PLUG-IN

H

PCM telemetry support

PCM plug-in includes the bit sync, frame sync, decommutation, PCM encoder and simulator for PCM data sources. These sources can be from hardware icluding the DEWESoft PCM-FS2, Ulyssix cards or Chapter 10 plug-in. It can decode several thousand channels from those interfaces, supports embedded streams and FFIs. The data are again perfectly synchronized with the use of IRIG to the analogue data and video streams.

- ▶ Bit sync, Frame sync, Decommutator, PCM Encoder and Simulator
- ▶ DEWESoft PCM-FS2, Ullysix cards and Chapter 10 support
- ▶ Embedded streams, FFIs support
- ▶ Digital recording with full analysis playback
- ▶ perfectly synchronized with the use of IRIG

SENSORS

Photron high-speed camera support

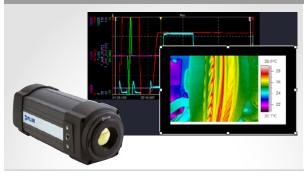
Plugin for FLIR Thermovision cameras



Adds video support for Photron hi-speed cameras. Allows video data acquisition of megapixel image resolution recording at up to 20,000 fps and up to 2.000.000 fps with limited resolution (depends on camera model). Video is fully synchronized with other data sources. Supports software or external triggering.

- ▶ multiple camera support
- ▶ fully synchronized

FLIR THERMOVISION



Plugin adds support for data visualisation, analysis and storage of FLIR Thermovison cameras (models: A300, A310, A315, A320, A325, A615, SC305, SC325, SC645, SC655).

▶ FLIR thermovision cameras support

MARCATOR

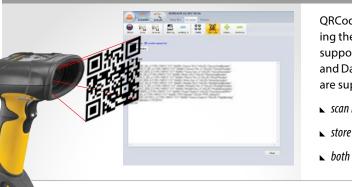


MAHR digital callipers and dial indicators support

Enables data acquisition from MAHR digital callipers and dial indicators. Supports wire (USB) and wireless devices.

- ▶ adjustable update rate
- ▶ multiple device support

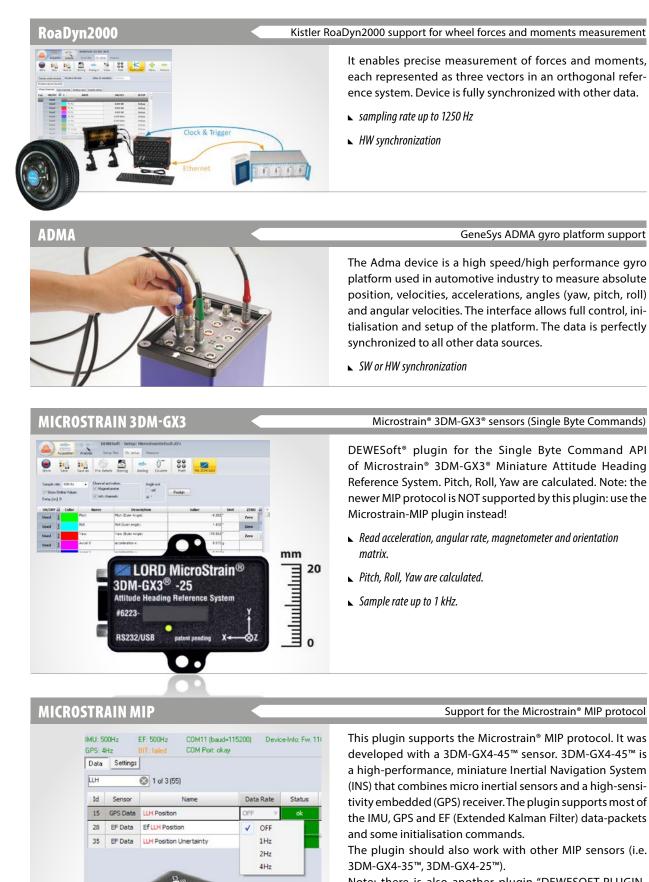
QR CODE PLUGIN



Scans 1-D and 2-D barcodes and stores them into the Dewesoft data header

QRCode plugin serves for scanning the barcodes and storing their content into the Dewesoft data header. The plugin supports both 1-D as well as 2-D barcodes, such as QR code and Data Matrix. Both handheld scanner and camera modes are supported.

- scan linear barcodes, QR codes and Data matrices
- store barcode content into the Dewesoft data header
- **both handheld scanner and camera modes supported**



Note: there is also another plugin "DEWESOFT-PLUGIN-MICROSTRAIN" which supports the older byte-based protocol.

- ▶ support for Microstrain[®] sensors that use the MIP protocol
- ► support for IMU, GPS and EF data packets- support for IMU, GPS and EF data packets

CROSSBOW 440



Read data from CrossBow 440 devices

The DEWESoft[®] plugin for CrossBow 440 Series Inertial System can read angular rates, accelerometer and temperature data from the CrossBow device at user definable sample rates.

- angular rates
- ▲ accelerometer
- ⊾ temperature

GRS-1



Topcon GRS-1 (portable GPS with RTK)

Plugin for Topcon GRS-1 devices (portable W-LAN GPS with RTK option). The plugin supports TCP/IP and UPD. RTK allows for submeter accuracy (i.e. in combination with the ADMA plugin).

- ▶ portable GPS/RTK
- ▶ WiFi (TCP/IP, UDP)

NMEA WEATHER STATION



NMEA compatible Weather Stations

This plugin supports one NMEA compatible Weather Station Device (e.g. Vaisala WXT520) via RS232 interface. Currently MWV and XDR messages are supported. The device must be configured to send the data automatically.

- ▶ NMEA Weather Station support
- ⊾ *RS232*
- ▶ MWV, XDR sentences

UTILITY

| Weight of the second | Whenever the measurement system is unattended in remote location, there is the need of getting a note about the system status, whenever parameters reach critical lin its. This plugin will send an e-mail or SMS (by the use of e-mail to SMS service) to one or more recipients, if an Alarr appears in DEWESoft. Multiple alarm constraints can be specified (the combinations are endless by using Math resulting in different text, sent per mail (e.g. "Temperatu Sensor 1 too high!"). Alarm on e-mail or SMS Multiple alarms |
|---|--|
|---|--|



FREE



Easy data transfer to USB memory stick

Small tool, which automatically transfers all datafiles from a selected local folder to the USB memory stick, in the moment the stick is connected. It can also remove the original files to free disk space.

| DATA MANAGER | | Plugin for copying data files to FTP server or to local folder. |
|--------------|--|---|
| DS-NET | With the set of | Plugin for copying acquired data to an FTP server or to a local folder. It can also shut down the computer after the file is transferred. This plugin is able to copy in background while the multifile storing is still going on. This allows the user to live-copy files on a different computer, and already start the export process by sequencer, which means saving time! |
| | | ▶ copies data files to FTP or local folder |
| | | ▶ is able to shut down computer after file transfer |
| FTP-SERVER | | copy files during multifile storing! Start exporting already during measurement! |

OTHERS

TEXT IMPORT

| WCSoft data file : | NAL PARTY OF THE P | | | | | |
|-------------------------|--|-----|---------|----------|---------------|---|
| Test2 | | | | | | |
| older D:\DEWESoft\Da | ita\ | | | | | |
| ruporting uptions | | | | | | |
| Start import at row. | it at sowr. 🔟 😽 | | Preview | N: | | |
| Start import at col | 1 | | Row | Type | Channel 0 | |
| | ė. | (#) | 38 | Ch. Name | AI 1 [V] I IA | |
| Decimal symbol: | | | 39 | Value 0 | 6.6085815 | |
| Channels type: | Sync | ٠ | 40 | Value 1 | 6.0995483 | |
| | Relative time | | 41 | Value 2 | 5.5072021 | |
| | | | 42 | Value 3 | 5.0436401 | |
| | UTC time | - | 43 | Value 4 | 4.6606445 | |
| Sample rate: | 1000 | | -44 | Value 5 | 4.1438647 | |
| Delimiters | | | 45 | Value 6 | 3.4088135 | |
| Tab | | | 46 | Value 7 | 2.4954224 | |
| C Space | | | 47 | Value 8 | 1.5905762 | |
| O Other: | | | -48 | Value 9 | 0.83496094 | - |

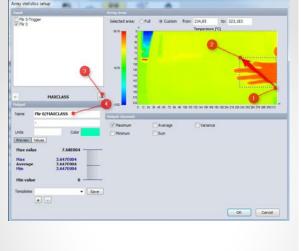
Imports text files

FREE

Text import plug-in imports data for text files (*.txt). It supports different channel types as well as different time formats.

- ▶ imports text files
- ▶ supports different sync and async channels
- ▶ supports different time formats (absolute time, relative time etc.)

SELECTIVE STORE (FLIR ALARM)



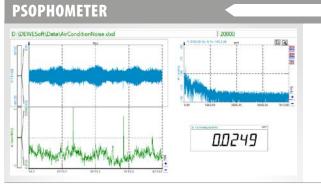
Select when to store 2d-array channels (e.g. FLIR image)

The DEWESoft[®] Selective Store plugin can be used to store the data of array channels only when a custom condition is true. You can easily define simple alarm-conditions and a pre-post trigger time. This will work with any 2D array channels, but is commonly used for FLIR cameras.

A typical use-case is that you want to store a DEWESoft® data-file and only when the FLIR camera detects that a certain region gets too hot, you also want to store the FLIR data to the DEWESoft® datafile, to see what's going on.

- ▶ works with any 2D array channels (e.g. FLIR image)
- ▶ custom conditions when to store the data
- example usecase: store FLIR image data only to the DEWESoft[®] datafile in certain condi-

tions to reduce the size of the DEWESoft® data-file



Used for testing of telecommunication equipment

Psophometer is used for testing telecommunication equipment. It shows us audible effects of disturbing voltages of various frequencies. Psophometer uses weighting network in frequency domain. Applications

Power Analyser

POWER ANALYSIS

MOTOR











E-MOBILITY



POWER QUALITY ANALYSIS & POWER SYSTEM TESTING

SMART GRID & ENERGY MANAGEMENT



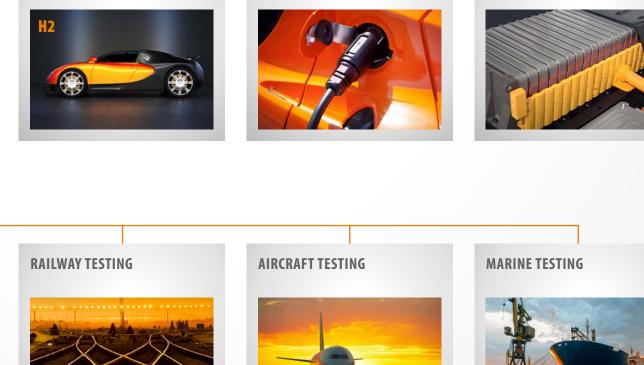
POWER QUALITY ANALYSIS



RENEWABLE TESTING



POWER



BATTERY TESTING



STANDBY-POWER

HYDROGEN VEHICLE

LIGHTING



EQUIPMENT

CHARGING ANALYSIS





Power Instruments

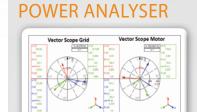
WIDE-BAND HIGH PRECISION POWER ANALYSER



R8D POWER

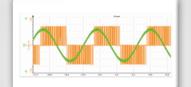
- ► High Precisison Power Analyser 0,03% basic accuracy from DC to 1kHz
- ▶ Raw data storing
- ▶ 0,5ms Power calculation
- ► Combination of multiple products (Scope, FFT-Analyser, PQ Analyser etc.)
- ► Mobile applications & Testbed use with one instrument
- ► Power Supply of all current transducers directly out of the instrument





▶ P, Q, S, PF, cos phi, more than 100 calculated values

OSCILLOSCOPE



▶ Scope and Vector Scope

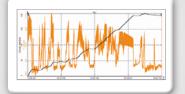


► FFT, Harmonic FFT, Harmonics, Interharmonics, Higher Frequencies, Flicker, Flicker emission etc.

SOFTWARE

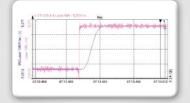
► Triggering on analogue, math or power channels





 Raw data storing in full sampling rate

POST PROCESSING



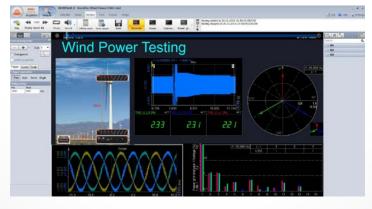
 Powerful analysis after measurement

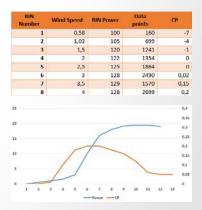
| | DEWESoft [®] DS-R8D POWER | DEWESoft [®] DS-R3 POWER | DEWESoft [®] DS-R2DB POWER | DEWESoft® SIRIUS® POWER | | | |
|------------------------------|---------------------------------------|--|---|----------------------------|--|--|--|
| OVERVIEW | | | | | | | |
| Max. isolated ChnNo. | 64 | 24 | 16 | 8 | | | |
| Sample Rate/Res 1 | 1MS / 16 Bit | 1MS / 16 Bit | 1MS / 16 Bit | 1MS / 16 Bit | | | |
| Bandwidth | 2MHz | 2MHz | 2MHz | 2MHz | | | |
| Sample Rate/Res 2 | 200 kS/s / 24 Bit | 200 kS/s / 24 Bit | 200 kS/s / 24 Bit | 200 kS/s / 24 Bit | | | |
| Bandwidth | 75 kHz | 75 kHz | 75 kHz | 75 kHz | | | |
| Base accuracy | 0.03% | 0.03% | 0.03% | 0.03% | | | |
| Max. Range | 1600V DC | 1600V DC | 1600V DC | 1600V DC | | | |
| 3 PHASE SYSTEMS | 8 | 3 | 2 | 1 | | | |
| Tacho / Counter | 16 | 4 | 4 | 2 | | | |
| CAN | up to 8 | up to 3 | up to 2 | optional (SBOX up to 2) | | | |
| Option Fanless | | - | - | \checkmark | | | |
| Digital Inputs | 192 | 72 | 48 | 24 | | | |
| Digital Outputs | 64 | 24 | | 8 | | | |
| Analogue Outputs | 64 (optional) | | 16 (optional) | 8 (optional) | | | |
| Time Synchronisation | IRIG, GPS, NTP | IRIG, GPS, NTP | IRIG, GPS, NTP | IRIG, GPS, NTP | | | |
| HIGH VOLTAGE INPUT | | | | | | | |
| ADC type | | 16 bit SAR with 100 kHz 5th o | order analog AAF filter or bypass (2 N | IHz) | | | |
| Sampling rate | | | Itaneous 1 MS/s | | | | |
| Ranges | | | 0 V, ±200 V, ±100 V, ±50 V, ±20 V | | | | |
| Typ. SNR @ 100 kHz | | | 85 dB | | | | |
| Input coupling | | | DC | | | | |
| Input impedance | | 10 M | Ω in parallel 2pF | | | | |
| Overvoltage protection | | | GND: 2 kVpk-pk , CAT II 1000V, CATIII 60 | DOV | | | |
| LOW VOLTAGE INPUT | | | | | | | |
| ADC type | | 16 hit SAR with 100 KU+ 0 | ith order analog AAF filter or bypass | | | | |
| Sampling rate | | | | | | | |
| Ranges | | Simultaneous 1 MS/s | | | | | |
| Br ranges @ 10 Vexc | | ±100V, ±50V, ±20V, ±10V, ±5V, ±2V, ±1V, ± 500mV, ±200mV, ±100mV and 50mV 1000 mV/V, 100 mV/V, 10 mV/V | | | | | |
| Input coupling | | | z (3 Hz, 10 Hz per SW) | | | | |
| Input impedance (100 V range | a) | | ween IN+ or In- and GND | | | | |
| Bridge modes | c) | | Full bridge | | | | |
| TEDS | | | - | | | | |
| | | | apters, only on DSUB 9 version | DA / DW | | | |
| Sensor Excitation | Danas | | , sw programmable (16 bit DAC), max 0,2 c): Pango > 10 V: 300 V cont : 1000V | | | | |
| Overvoltage protection | Kange | e < 10 V: 100V (200 V peak for 10msec | | with valialia pluy | | | |
| Connector | | BNC, D20B 3, F | Banana, Screw Connector | | | | |

Power Quality Analysis



Power Quality Analysis for Renewables, Grid, Troublehooting ...





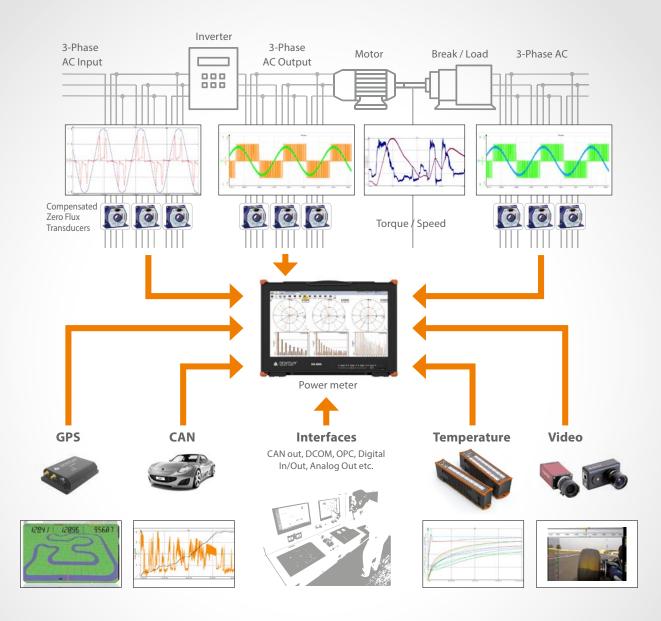
Static analysis with report generation



Dynamic analysis with Raw Data and ½ period PQ parameters



Power Analysis



Drawbacks of other instruments:

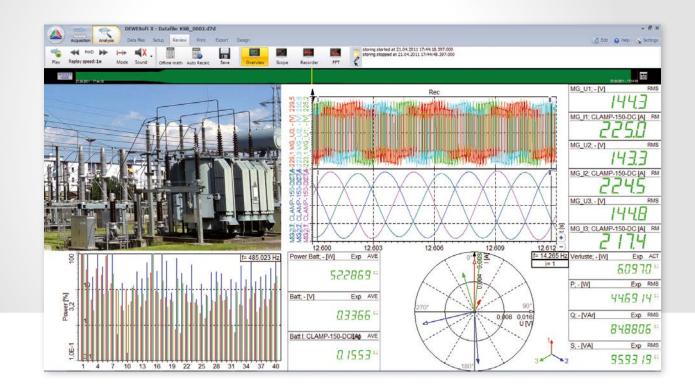
- Usage of multiple data acquisition systems (Multimeter, Power Analyser, CAN Logger, Data Logger, Videorecorder, etc.)
- ► Time synchronization between the DAQ systems
- ► Data merging (Data storage in different systems and formats)
- No continuous raw data acquisition
- Slow Calculation cycles of power Analyser
- ► No Connection of additional sensors
- ▶ No mobile measurement system
- ▶ Only basic Power Quality Analysis
- ... no comprehensive analysis possible

Benefits of the DEWESoft® Power Analyser:

- ► Combination of multiple products (Power Analyser, Oscilloscope, Data Logger, Spectrum Analyser, CAN logger, etc.)
- Synchronous acquisition of all data
- Data storage in one system and one format
- Combined Power Analysis and Raw Data storing
- Live Power calculation (1ms values)
- **Enhanced Power Quality Analysis**
- Any number and type of input channels
- Mobile measurement system
- Additional Sensor Software Calibration
- ... Comprehensive Analysis within one measurement device

INSTRUMENTS

DEWESoft® Power Software



The POWER option of DEWESoft[®] is an absolutely high-performance tool for the calculation of power, harmonics and all related parameters. This toolbox is an excellent combination of many features and nearly all applications can be realized by using DEWESoft[®] hardware.

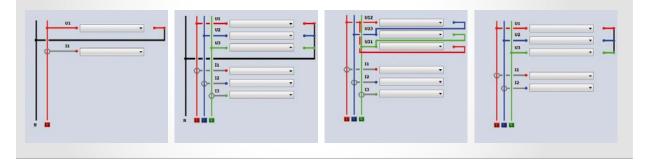
The unique system architecture of the DEWESoft[®] Power Analyser makes it possible to fulfill a couple of tasks within just one device. The DEWESoft[®] Power Analyser combines the functionality of a Power Analyser, a Combustion Analyser, a Data logger, a Scope, a Vector Scope, a Transient Recorder and a FFT – Harmonics Analyser. Acquiring different signals (analog, digital, counter, CAN, video etc.) simultaneously from different sources with different sampling rates and storing them in one file allows comprehensive, not yet experienced analysis for all type of applications.



SOFTWARE

WIRING SCHEMATICS

Different wiring schematics allow the power calculation for all possible connections. These are single phase, star connection, delta connection, V connection, Aron connection and a combined star / delta connection. All of course with or without currents. It's even possible to analyse 6-, 7-, 9- or 12-phase motors due to the combination of powerful hard- and software.

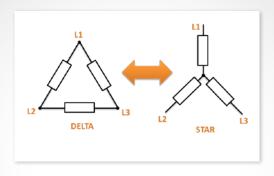


POWER CALCULATION

| | 2 2 I | | | | | 185 | | 1-9-1- |
|--|-----------------------------------|---------|----------|-----------|----------|------|--------|--|
| | | And and | 1 1 A A | | | | | CONTRACT OF |
| latic lans Inforte at | 09949 | 383 | 100 | 1147 | 1 188 | | | - mja - Mja - Aja |
| · · | -578 | 2682 | 26.76 | -219 | 750 | -511 | 2385 | - 1,40,4 - 1,40,1 - 1,40,1 |
| interesting and interesting an | 02635 | | | 23448 | | | | < (#1204) 0.543 0.532(m) 0.0423 |
| Married and | 09949 | | | | I IBB | | 09530 | - 521 - 6201 - 644 - 644 |
| No. of State | | GLN P | GOR W - | R(1.34) - | GL3H P | | GLDs P | 41 41404 40401 |
| | 100.00 P | - 1457 | | 23448 | 21113 | | | |
| | 0990 596 100 1 141 1 188 990 0953 | | | | | | | |
| | NUMBER OF | 1000 M | GOUDE IN | BAUGH P | 60.0H | | | |
| | U.F.34. P | 10 M | DOR M P | | CAULIN W | 1eri | 6 103 | |

- ▶ *P, Q, S, D*
- **L** Cos φ , power factor
- P, Q, cos φ for each harmonic

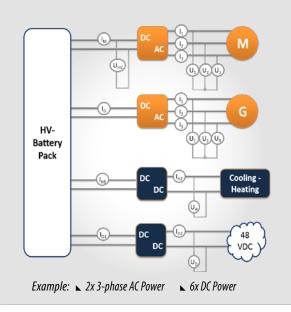
STAR – DELTA CALCULATION



► It is possible to calculate out of a delta connection all values and the waveform for the star connection and vice versa.

► Waveform: U1, U2, U3 <> U12, U23, U31

MULTIPLE POWER CALCULATIONS



It is possible to do a number of power analysis within just one device. For example with the DEWESoft® R8D you can measure 8 three phase systems completely synchronous. Furthermore it is possible to do the analysis for different frequencies (DC, 50Hz, variable frequency etc.) and wiring schematics (1 phase, 3 phase etc.). Any additional mechanical values like torque, speed, noise, temperature and vibration can be captured and synchronously analysed.

Typical Configurations:

- ► Motor & Inverter Measurement 3x 3-phase AC power (var. frequency) ► E-Mobility
- ∠ E-moonity
 4x 3-phase AC power (var. frequency)
 6x DC power
 ∧ Aircraft
- Aircraft 5x 3-phase AC power (400 Hz) 1x 1-phase AC power (50 Hz) 5x DC power
- ⊾ Marine
 - 7x 3-phase AC power (50 Hz) 4x 1-phase AC power (50 Hz) 1x DC power

► Railway 1x 3-phase AC power (50 Hz) 3x 1-phase AC power (16.7 Hz) 3x DC power

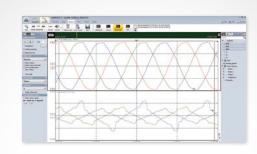


The software PLL guarantees a very accurate frequency calculation (mHz). On one system multiple power systems can be measured and each can have its own frequency. With the use of the different instruments from DEWESoft[®] the values can be shown in several ways.

Possible line frequencies:

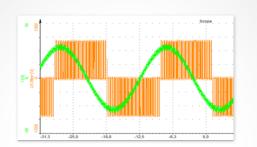
16.7 Hz: Railway Sector, 50 Hz: Public Grid, 60 Hz: Public Grid, 400 Hz: Aerospace, 800 Hz: Aerospace, Variable frequency: Inverter (from 0.5 Hz to 3 kHz).

SCOPE



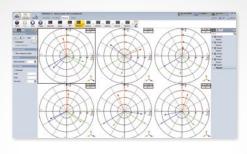
- ▶ Selectable graphs
- ▶ U1, U2, U3, U12, U23, U31: Line to line and line to earth voltages are supported
- ▶ Up to 8 graphs in one diagram
- ► Zoom in and out are supported online
- Waveforms can be stored

FREQUENCY SOURCE



In DEWESoft[®] you can choose whether you use voltage, current or an external source as frequency source. This is a very helpful feature especially at inverter measurements. Due to the PWM modulated voltage signal the correct period time often can not be determined right. The current is much less distorted because of the high inductance of the motor coil. Therefore it's to often better to use the current as frequency source at inverter measurements. This feature ensures correct frequency determination for every application.

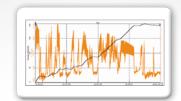
VECTOR SCOPE



- ▶ Vector scope for 3 phase systems
- **•** Each individual harmonic can be shown
- ▶ More vector scopes can be displayed on one screen
- ▶ Different power systems can be shown on one screen
- ► With the "transparent" function direct comparisons of phasors are possible

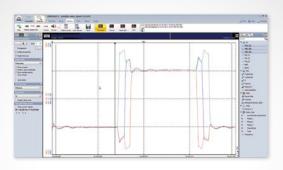
- ▶ U, I, P, Q, S, PF for each phase and total
- Symmetrical Components (U, I, P, Q for positive-, negativeand zero sequence system)
- ▶ Definable Cycle Calculation (1/2, 1, 2 or 4 cycles)
- ▶ Overlap of up to 99 % (1ms sliding)

RAW DATA STORING



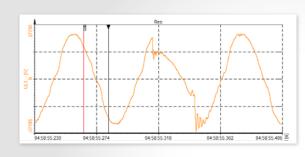
With a very specific data file structure we can write the channel setup, display setup, all the events, fast analog data and slow asynchronous data from different sources in a single file. For long term measurement DEWESoft® offers to roll-over the file automatically when certain file size is reached or after a specified time (for example after 24 hours the current file is closed and a new one is created automatically). DEWESoft® makes sure that no data is lost during the file roll-over.

RECORDER



- Recording of all parameters in individual intervals
- ▶ Individual screens can be defined
- ► Zoom in and out
- ▶ Storing fast (full sampling rate) or reduced (e.g. 600 sec.)
- ▶ Detailed zoom-in to pulse width!

FAULT RECORDER & TRANSIENT RECORDER



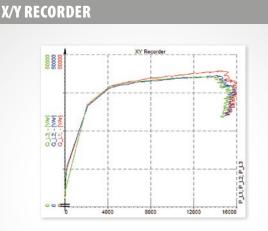


Simple edge (either rising or falling slope) Window trigger (two levels; entering or leaving logic)

Pulsewidth trigger (longer or shorter than duration logic)

Window and Pulsewidth (completely selectable as above)

(rising or falling slope with steepness selection)



► Orbitals can be generated online

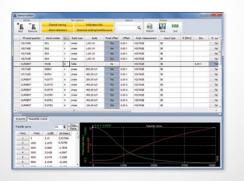
- ▶ *P* over *Q* as example for this function
- ▶ Trigger on all channels possible (analog, digital, power, math, etc.)
- Setting a trigger on all parameters of the power module!
- \checkmark U, I, P, Q, S, D, cos φ , power factor, ...
- ► Each harmonic!
- ▶ Pos-, neg-, zero-sequence systems
- ► Very fast glitch detection (up to MS/s)
- ▶ Math. channels (rpm, torque, efficiency,...)

We can also use math formulas to create combined trigger conditions. When the trigger event happens, data is stored with the fast sampling rate (with pre- and post-time) while otherwise only reduced data (min, max, average, RMS) is stored. This reduces the file size in long-term measurements.



CALIBRATION/ACCURACY

LHO IN



Voltage and Current transducers always have a frequency dependent amplitude error and phase shift. With Dewesoft's unique software calibration technology amplitude and phase can be corrected for the full frequency range from DC up to 1 MHz. All internal curves like filter response are corrected inside the software and the sensor database includes correction curves for each clamp, rogowsky coil, transformer or which sensor ever is used.

TRANSDUCER SPECIFICATIONS

| DEWESoft [®] Shunt | 5 ohm | 5 ohm | 2 ohm | 2 ohm | 1 ohm |
|---|----------------------|----------------------|----------------------|----------------------|----------------------|
| Inner diameter | 26 mm | 26 mm | 26 mm | 30 mm | 30 mm |
| Test voltage 50/60 Hz, 1 min | 5.4 kV | 5.4 kV | 5.4 kV | 4.6 kV | 3.1 kV |
| Rated isolation voltage rms, single isolation CAT III, polution deg. 2 IEC 61010-1 standards EN 50178 standards | 2000 V 1000 V | 2000 V 1000 V | 2000 V 1000 V | 1600 V 1000 V | 300 V 300 V |
| Angular Accuracy | < 0.025° + 0.06°/kHz | < 0.025° + 0.05°/kHz | < 0.025° + 0.09°/kHz | < 0.025° + 0.18°/kHz | < 0.025° + 0.09°/kHz |
| Frequency Influence | 0.04 %/kHz | 0.06 %/kHz | 0.06 %/kHz | 0.12 %/kHz | 0.06 %/kHz |
| Offset | < 0.025 % | < 0.008 % | < 0.004 % | < 0.005 % | < 0.005 % |
| Linearity | < 0.002 % | < 0.001 % | < 0.001 % | < 0.001 % | < 0.001 % |
| Bandwidth (0.5 % of Ip) | DC 800 kHz | DC 500 kHz | DC 500 kHz | DC 250 kHz | DC 500 kHz |
| Output Ratio | 100 mA at 60 A | 200 mA at 200 A | 200 mA at 400 A | 400 mA at 200 A | 1 A at 1000 A |
| Temperature influence | < 2.5 ppm/K | < 2 ppm/K | < 1 ppm/K | < 1 ppm/K | < 1 ppm/K |
| di/dt (accurately followed) | > 25 A/µs | > 100 A/µs | > 100 A/µs | > 100 A/µs | > 100 A/µs |
| Max. burden resistor (100 % of lp) | 10 ohm | 10 ohm | 2.5 ohm | 2.5 ohm | 2.5 ohm |
| Overload Ability Short Time (100 ms) | 300 Apk | 1000 Apk | 2000 Apk | 3500 Apk | 4000 Apk |
| Primary Current Range DC, RMS Sinus | 60 A | 200 A | 400 A | 700 A | 1000 A |
| | | | | | |
| | IT 60-S | IT 200-S | IT 400-S | IT 700-S | IT 1000-S |
| | | | | | |



| SIRIUSi-PWR-MCTS2 / SIRIUSir-PWR-MCTS2 | | | |
|--|--|--|--|
| Power supply | 9-36V DC | | |
| Max power consumption | 85 W | | |
| Physical dimensions | 265 x 140 x 65 [mm] | | |
| Operating temperature | -20 to 50°C | | |
| Storage temperature | -40 to 85°C | | |
| Humidity (@60°C) | 95% RH non-condensing | | |
| Output | 4x Isolated Power supply (1500V DC, 60sec) | | |
| Output voltage | +/-15V DC | | |
| Maximum output per channel | 20 W | | |
| Short circuit protection | indefinite (automatic recovery) | | |
| Over load protection | 150 % of lout max. typ | | |

This power supply is required for all zero-flux transducers: IT60-S, IT200-S, IT700-S, IT1000-S, and for the current clamps DS-CLAMP-200DC und DS-CLAMP-500DC.

SOFTWARE

INSTRUMENTS

| CURRENT CLAMPS AC/DC | | | | | |
|--------------------------------------|---------------------------------------|--------------------------------------|--------------------------------------|---------------------------------------|-------------------------------------|
| | DS-CLAMP- 200DC | DS-CLAMP- 500DC | DS-CLAMP- 500DCS | DS-CLAMP- 150DC | DS-CLAMP- 1800DC |
| | | | | | |
| Туре | Flux Gate sensor | Flux Gate sensor | Flux Gate sensor | Hall sensor | Hall sensor |
| Range | nominal 200 A rms / max. 400 A rms | 500 A rms or DC | 500 A rms or DC | 150 A rms / 300 A peak | 1800 Apk |
| Bandwidth | DC to 500 kHz | DC to 100 kHz | 200 kHz | DC to 100 kHz | DC to 20 kHz |
| Accuracy | 0.3 % of reading | 0.3 % of reading | 0.3 % of reading | 1 % + 2 mA | 2.5 % +/- 0.5A |
| Phase | \leq 0.1 $^{\circ}$ (up to 100 Hz) | \leq 0.1 $^{\circ}$ (up to 100 Hz) | \leq 0.1 $^{\circ}$ (up to 100 Hz) | - | - |
| TEDS | Fully supported | Fully supported | Fully supported | Fully supported | Fully supported |
| Sensitivity | 10 mV/A | 4 mV/A | 4 mV/A | 20 mV/A | 1 mV/A |
| Resolution | - | - | - | ±1mA | ±1mA |
| Overload Capability | 500A (1min) | 1000 A DC | - | 500A DC (1min) | 2000A DC (1min) |
| Dimensions (Clamp opening) | 153mm x 67mm x 25mm (Ø 20 mm) | 238mm × 116mm × 35 mm (Ø 50 mm) | 153mm x 67mm x 25mm (Ø 20 mm) | 205 mm x 60 mm x 15 mm ((Ø 32 mm) | 205 mm x 60 mm x 15 mm (Ø 32 mm) |

CURRENT CLAMPS DC

CUDDENT CLAMDS AC/DC

| | DS-CLAMP- 5AC | DS-CLAMP- 15AC | DS-CLAMP- 200AC | DS-CLAMP- 1000AC |
|-------------------------------|---|--|---|--|
| | A | DAC | ZUAC | TOUAL |
| Туре | Iron-Core | Iron-Core | Iron-Core | Iron-Core |
| Range | 5 A | 15 A | 200 A | 1000 A |
| Bandwidth | 10 kHz | 10 kHz | 10 kHz | 10 kHz |
| Accuracy | $1 - 12 A$: $\pm 0,5 \%$ of reading $0.5 - 1 A$: $\pm 1 \%$ of reading $5 mA - 0,5 A$: $\pm 2 \%$ of reading | 1% for currents of 1 - 15 A 2.5% for currents < 1 A | 1% for currents of 100 - 240 A 2,5% for currents of 10 - 100 A 3,5% for currents of 0,5 - 10 A | 0,3% for currents of 100A - 1200 A 0,5% for currents of 10A - 100 A 2 % for currents < 1A |
| Phase | 1 - 12 A: ± 1° 0.5 - 1 A: ± 1° 5 mA - 0.5 A: ± 2° | \leq 3° for currents of 1 - 15 A \leq 5° for currents < 1 A | \leq 2,5° for currents of 100 - 240 A \leq 5° for currents of 10 - 100 A not specified for currents of 0,5 - 10 A | 0,7° for currents of 100A - 1200 A 1° for currents of 10A - 100 A not specified for currents of < 1A |
| TEDS | Fully Supported | Fully Supported | Fully Supported | Fully Supported |
| Sensitivity | 60 mV/A | 100 mV/A | 10 mV/A | 1 mV/A |
| Resolution | - | 0.01 A | 0.5 A | 0.001 A |
| Overload Capability | - | Crest Factor of 3 | Crest Factor of 3 | 1200 A for 40 minutes |
| Dimensions (Clamp opening) | 102 x 34 x 24 mm (Ø 15mm) | 135 x 51 x 30 mm (Ø 22mm) | 135 x 51 x 30 mm (Ø 22mm) | 216 x 111 x 45 mm (Ø 53mm) |

| ROGOWSKY COI | ROGOWSKY COILS AC | | | | |
|--------------|--------------------------|--------------------------|--------------------------|--|--|
| | DS-FLEX-3000-35 | DS-FLEX-3000-80 | DS-FLEX-3000-120 | | |
| | | | | | |
| Туре | Rogowski coil | Rogowski coil | Rogowski coil | | |
| Range | 3 A, 30 A, 300 A, 3000 A | 3 A, 30 A, 300 A, 3000 A | 3 A, 30 A, 300 A, 3000 A | | |
| Bandwidth | 10 Hz to 20 kHz | 10 Hz to 20 kHz | 10 Hz to 20 kHz | | |
| Accuracy | 1% | 1% | 1% | | |
| Coil Length | 350 mm (Ø 100 mm) | 800 mm (Ø 250 mm) | 1200 mm (Ø 380 mm) | | |
| TEDS | not supported | not supported | not supported | | |

Further Rogowsky coils available on request! Ranges from 0.3 A to 30,000 A. Bandwidth 1 Hz to 30 MHz. Accuracy up to 0.2 %. Variable coil length.

SHUNTS AND AC/DC TRANSDUCER

| | DS-SHUNT-05 | DSIi-10A |
|----------------|---------------|---|
| | DS-SHUNT-05_1 | O DSIL-10A O A senter |
| Туре | Shunt | Isolated Current Transducer |
| Range | 5 A | 10 A (overload capability 80 A for 1 sec) |
| Bandwidth | - | 100 kHz |
| Accuracy | 0.1 % | 0.5 % |
| Resistance | 0.05 0hm | - |
| Safety Voltage | 600 V CAT III | 600 V CAT III |
| TEDS | not supported | Fully Supported |

| Functionality | DEWESoft® Power Analyser | | |
|---------------------------------|--|--|--|
| Power Analysis | \checkmark | | |
| Power Quality Analysis | \checkmark | | |
| Database Storing | \checkmark | | |
| Post Processing | \checkmark | | |
| Math Library | \checkmark | | |
| Data logging - Raw data storing | ✓ (data Storing in Full Sampling rate of 1MS/s per channel) | | |
| Scope | ✓ (up to 8 graphs in one diagram, Zoom In- and Out) | | |
| Vector Scope | ✓ (1-, 2-, 3-phase systems) | | |
| FFT | 🗸 (up to ½ of Sampling Rate) | | |
| Harmonic FFT | 🗸 (up to ¼ of Sampling Rate) | | |
| Transient Recording | ✓ (up to 1MS/s) | | |
| Triggering Channels | Analog, Digital, Counter, Math, Power, etc. | | |
| Triggering options | Simple edge (rising, falling), Window (two-levels: entering, leaving), Pulsewidth (longer or shorter than duration), Window Pulsewidth, Slope Trigger (rising or falling slope with steepness) | | |

POWER ANALYSIS

| Functionality | DEWESoft® Power Analyser | | |
|--|---|--|--|
| Power Analysis for DC and AC | \checkmark | | |
| Power Analysis | P, Q, S, PF, cos phi, D (Distortion), DH (Harmonic distortion), QH (reactive power of harmonics) (for each phase and total) | | |
| Fundamental Power | P_H1, Q_H1, S_H1, cos phi_H1, phi_H1 (for each phase and total) | | |
| Voltage and Current | RMS, RM, AVE (star and delta) | | |
| Energy Calculation | Total, positive and negative (e.g. Recuperation) | | |
| Efficiency | \checkmark | | |
| Wiring Schematics | DC, 1-phase, 2-phase, 3-phase delta, 3-phase star, 3-phase V, 3-phase Aron, 6-phase (R2DB, R8D), 7-phase (R2DB, R8D, 12-phase (R8D) | | |
| Star-Delta Calculation | ✓ (waveform and RMS values) | | |
| Frequencies | 16,7 Hz, 50 Hz, 60 Hz, 400 Hz, 800 Hz, Variable from 0,5Hz up to 1,5 kHz | | |
| Frequency Source | Voltage, current, external | | |
| Period Values | U, I, P, Q, S, symmetrical components for $\frac{1}{2}$, 1, 2 or 4 periods and selectable Overlap up to 99% | | |
| Number of Cycles for Power Calculation | 5 - 12 | | |
| Power Averaging | Selectable - starting from 1ms , Multiple Averaging (e.g. 20ms, 60s, 600s) possible | | |

POWER QUALITY

| Functionality | DEWESoft® Power Analyser | |
|---|--|--|
| Harmonics (according to IEC61000-4-7) | up to 150 kHz for voltage, current, active-, reactive power, phase angle and impedance | |
| Variable Sidebands and Half Sidebands (according to IEC61000-4-7) | \checkmark | |
| Harmonic Smoothing Filter (according to IEC61000-4-7) | \checkmark | |
| Interharmonics (according to IEC61000-4-7) | \checkmark | |
| Total Harmonic Distortion (THD) (according to IEC61000-4-7) | Voltage and current (Total, odd and even) - selectable up to 150 kHz | |
| Total Interharmonic Distortion (TIHD) and K-factor (according to IEC61000-4-7) | Voltage and current (Total, odd and even) - selectable up to 150 kHz | |
| Higher Frequencies (according to IEC61000-4-7) | up to 150 kHz (grouping in 200Hz bands) | |
| Flicker (according to IEC61000-4-15) | selectable PST and PLT | |
| Flicker Emission (according to IEC61400-21) | \checkmark | |
| Rapid Voltage Changes (according to IEC61000-4-15) | selectable steady state and hysteresis | |
| Symmetrical Components (according to IEC61000-4-30) | Zero-, positive- & negative system for voltage and current (absolute or relative to fundamental) | |
| Additional Symmetrical Components (according to IEC61400-21) | Active and reactive parts for zero-, positive- & negative system | |

Automotive Applications



DEWESoft® offers

- ▶ the most flexible solutions in hardware and software on the market,
- ▶ short setup preparation time and additional quick and easy installation, which saves a lot of time and troubles,
- ▶ synchronised measurement of multiple inputs (analogue, digital, CAN, GPS, IMU, FlexRay, XCP, RoadDyn 2000, video & many more),
- ▶ possibility to capture different software modules (vehicle dynamics, combustion analysis, vibrations,...) in one synchronized data file.

SOFTWARE

INSTRUMENTS

Automotive Instruments



SBOX WITH INTEGRATED SIRIUS®

- ► Multiple combination of inputs (all the SIRIUS[®] modules + additional CAN)
- ► 2x 24 bit ADC, 160 dB dynamic
- ▶ 200 kS/s or 1 MS/s sampling rate
- ▶ High-end computer with the latest i7 generation processor
- SSD with up to 1 TB of storage
- With optional battery pack for continuous measurement
- ► Additional 12-inch display with High-brightness

| | DEWESoft [®] SBOX + SIRIUS [®] | DEWESoft® SIRIUS® | DEWESoft® DEWE-43 |
|---------------|---|----------------------|----------------------|
| | | | |
| | Up to 1000 | 8 / slice | 8 |
| es. – opt 1 | 200 kS/s / 2x 24 Bit | 200 kS/s / 2x 24 Bit | 200 kS/s / 16 Bit |
| es. – opt 2 | 1MS / 16 Bit | 1MS / 16 Bit | / |
| | 0.05 % | 0.05 % | 0.1 % |
| P/XCP | \checkmark | \checkmark | \checkmark |
| tion Analyser | \checkmark | \checkmark | limited |
| | \checkmark | _ | _ |
| | option | - | _ |
| culation | \checkmark | \checkmark | \checkmark |
| | | | |

Max. Channels Sample Rate/Res Sample Rate/Res. Base accuracy CAN/FlexRay/CCP **Option Combusti** Camera Integrated GPS Customised calcu option option option Analogue output FFT \checkmark \checkmark \checkmark \checkmark \checkmark \checkmark Harmonics \checkmark Integrated GPS -_ \checkmark \checkmark \checkmark **Option DSA package** \checkmark \checkmark limited **Option Power** \checkmark \checkmark Storing raw data \checkmark

DS-IMU NEXT GENERATION OF NAVIGATION INSTRUMENTS



- Ruggedized and reliable GPS aided inertial navigation system including AHRS that provides accurate position, velocity, acceleration and orientation under most demanding conditions
- Ruggedized Combination of gyroscopes, accelerometers, magnetometers and pressure sensor with a GNSS receiver
- ► Inertial sensors together with GNSS receiver coupled in a sophisticated fusion algorithm to deliver accurate and reliable navigation and orientation
- ► GNSS receiver supports GPS, GLONASS, BeiDou, GALILEO, WAAS, EGNOS, Gagan and Real-time kinematic --> RTK
- ▶ IP68 & MIL-STD-810G environmental protection
- ▶ Up to 500 Hz output data rate
- Hot start in < 3 s
- ▶ Connected over USB
- ▶ Fast and easy installation



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DS-IMU1

DS-IMU1 is a **100 Hz** GPS / MEMS based inertial measurement system for standard vehicle measurement applications.



DS-IMU2

DS-IMU2 is a 500Hz GPS / MEMS based inertial measurement system for advanced applications which require high position accuracy, high update rate and static heading.

| | DS-IMU1 | DS-IMU2 |
|---|--|--|
| Navigation | | |
| Horizontal position accuracy GPS / DGNSS/ OMNISTAR/ RTK | 2.0 / 0.6 / - / - m | 1.2 / 0.6 / 0.1 / 0.01m |
| Vertical position accuracy GPS / DGNSS/ OMNISTAR/ RTK | 3.0 / 1.0 / - / - m | 2.0 / 1.0 / 0.2 / 0.02 m |
| Velocity accuracy | 0.05 m/s | 0.007 m/s |
| Roll & Pitch accuracy (dynamic) | 0.2 ° | 0.15 ° |
| Heading accuracy (dynamic with GNSS) | 0.2 ° | 0.1 ° |
| Slip angle accuracy | 0.3° | 0.2° |
| Range | Unlimited | Unlimited |
| Hot start time | 500 ms | 500 ms |
| Output data rate | 100 Hz | 500 Hz |
| GNSS | | |
| Supported navigation systems | GPS L1, GLONASS L1, GALILEO E1, COMPASS L1 | GPS L1, L2, L5 , GLONASS L1, L2, GALILEO E1, E5, BeiDou B1. B2 |
| Supported SBAS systems | WASS, EGNOS, MSAS, GAGAN, QZSS | WASS, EGNOS, MSAS, GAGAN, QZSS, OMNISTAR HP/XP/G2 |
| Additional features | | |
| PPS output | \checkmark | \checkmark |
| RTK | - | \checkmark |
| Static heding (dual antenna) | _ | \checkmark |
| Hardware | | |
| Interface | USB | USB |
| Operating voltage | 5 to 36 V | 5 to 36 V |
| Power consumption | 100 mA @ 5 V | 220 mA @ 12 V |
| Operating temperatures | -40 °C to 85 °C | -40 °C to 85 °C |
| Environmental protection | IP 67, MIL-STD-810G | IP 67, MIL-STD-810G |
| Dimensions | 30x40.6x24 mm | 90x127x31 mm |
| Weight | 25 g | 304 g |
| Applications | | |
| General Vehicle Dynamics | \checkmark | \checkmark |
| Brake Test | \checkmark | \checkmark |
| Acceleration Test | \checkmark | \checkmark |
| Lane change | \checkmark | \checkmark |
| Circle drive | \checkmark | ✓ |
| Chassis development | \checkmark | ✓ |
| Assistent systems | \checkmark | ✓ |
| Comfort testing | ✓ | ✓ |
| Validation | \checkmark | |
| ADAS | - | · · · · · · · · · · · · · · · · · · · |
| Pass by Noise | - | · · |
| FUSI | _ | • ./ |
| | _ | • • • • • • • • • • • • • • • • • • • |
| RTK positioning | | V |

| Inertial sensors | Accelerometer | Gyroscope | Magnetometer | Pressure |
|------------------------|---------------|----------------------------|----------------|---------------|
| Range (dynamic) | 2g, 4g, 16g | 250 °/s, 500 °/s, 2000 °/s | 2 G, 4 G, 16 G | 10 to 120 kPa |
| Bias stability | 20 ug | 3 °/hr | 1 | 100 Pa/yr |
| Scale factor stability | < 0.05 % | < 0.05 % | < 0.05 % | / |

Sensor Connection Options

ANALOGUE INPUTS

The analogue inputs are able to acquire data from sensors like pedal force sensors, brake cylinder pressure, temperature of brake discs and others.



Counter inputs can be used for measurement of brake pedal switch, speed and distance from external velocity sensor, speed of four wheels, steering wheel position and others.

High quality counter inputs are able to perform basic counting, encoder measurement and frequency measurement in the famous Supercounter[®] mode, which dramatically increases the accuracy of counting.





GPS DATA, DS-IMU2, ADMA, Oxford, Racelogic

GPS built in S-BOX, provides velocity, position, orientation information which is used for brake test calculations.

CAN, OBD II, J1939, CCP, XCP, FlexRay, GMLAN

The full speed CAN interface connects to vehicle CAN or other CAN sensors; CAN output feature included.



VIDEO

Different video devices can be added and acquired synchronously with other sources.



RoaDyn measuring wheels

Ethernet based acquisition of Kistler RoadDyn 2000 with hardware synchronisation for getting the wheel force and torque in all 3 dimensions.



Vehicle Dynamics

INTRODUCTION



The Vehicle Dynamics Test System is covering all kinds of R&D tests (handling, lane change, lane departure, tire, brake and ABS tests -> covering also regenerative braking and hybrid). Such a flexible system brings us in another dimension of testing, where one system with several software options is capable of doing multiple different tests.

Online checks for validation, visualised online results including postprocessing and reporting make the DEWESoft® Vehicle Dynamics system a complete all-in-one solution.

The Vehicle Dynamics system is based on a combination of GPS with IMU which is very simple and easy to set up. This system is a guarantee to have a signal where only GPS reception is not enough.

Brake testing is a wide and flexible field of different requirements for which our multifunctional solution guarantees a safe investment. The same equipment is also capable of tire tests, acceleration tests, odo calibration, fuel consumption, handling tests etc...

MAIN FEATURES

- ▶ Quick and easy installation
- ▶ Online data transfer between multiple systems
- ► Measurement results available online
- ▶ Scalable systems for multiplepurpose usage
- ► Multiple data sources (analogue, digital, CAN, GPS, IMU, FlexRay, XCP, CCP, RoadDyn 2000, video & many more),
- ▶ Realtime Math channels,
- Synchronisation between all data sources,
- Possibility to capture different software modules (vehicle dynamics, combustion analysis, vibrations,...) in one synchronized data file.
- **•** Export to many different file formats.

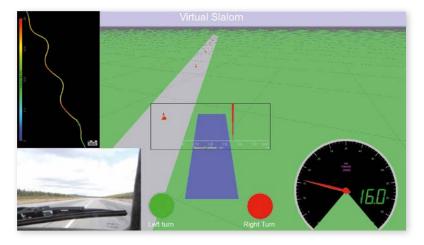
Handling Testing



One of the vehicle dynamics segments is handling, where inertial parameters such as Roll, Pitch and Yaw combined with GPS information, which comes out of DS-IMU2, are key factors for designers.

Additional data sources such as CAN, CCP, XCP, Video, OBDII , digital and a wide range of analogue sensors (potentiometers, accelerometers, strain, voltage, temperature, etc.) all synchronized together with the latest PPS-Sync technology over comes issues with correlating the parameters in post analysis and therefore saves a lot of time by processing the data.

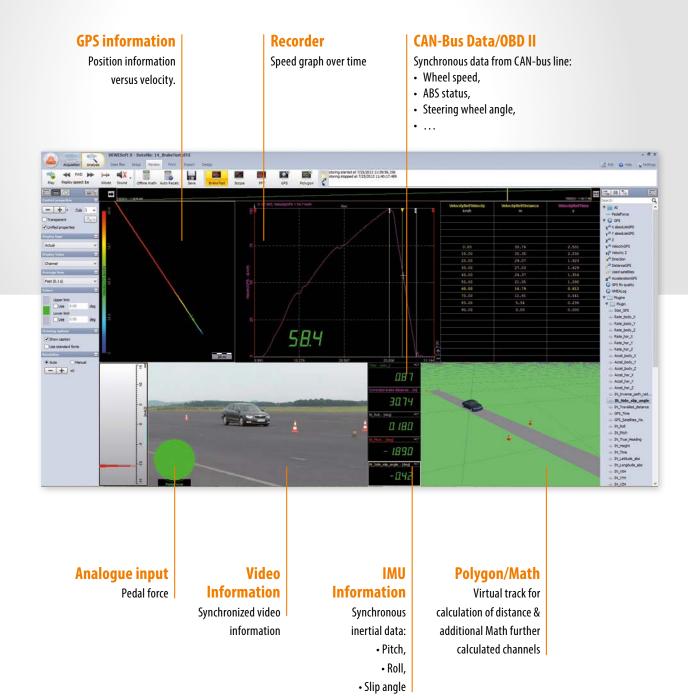
With the polygon plugin you can visualise and calculate distances between different objects on a track, or drive on a virtual map without using any cones.



Vehicle Dynamics

BASIC BRAKE TESTING





VEHICLE DYNAMIC CALCULATION



The setup of the vehicle dynamic calculation is done in the brake test setup page shown in this screenshot. Start and stop condition are set and also the required channels can be configured.

For each output channel you can choose a name and the proper unit. You can also configure the color and set a minimum and a maximum value used as a preset for its graphical display in DEWESoft[®].

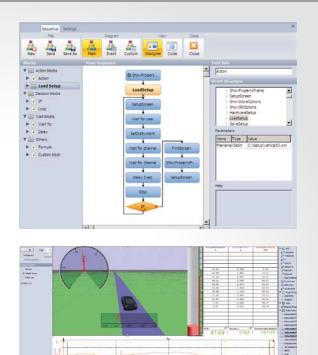
The additional parameters which are calculated are:

- Start speed when pushing brake pedal
- Stopping time
- ► Corrected braking distance, calculated as Sc=Sm*Vd²/Va²
- ► Mean fully developed deceleration MFDD (calculation see ECE R13-H)
- ▶ Brake deceleration over complete measurement
- **Contract Series and S**

BRAKE TEST SEQUENCE

The sequencer is a tool to predefine process steps in a sequential format. The interface can be graphically programmed or in a code oriented view. The sequence is stored in a file format. Therefore it's possible to manage these sequences centrally to guarantee a standardized and defined measurement procedure.

Within the sequencer you can access all relevant DEWESoft® features. In addition you can apply actions, calculate formulas and make decisions, wait for interaction or a preset delay and define your customised sequences. So it's possible to define different sequences and fit them together in a single sequence, where the sub sequences are done sequentially. The sequences can be controlled by the user or by an event caused by a certain channel. For a specific test which consists of different steps and loops it's possible to configure such a test sequence. As shown in this simple example for brake testing.



EXCEL REPORT



Testing procedure can be completed with the usage of excel report macro, where you can prepare templates and operate with data from multiple files. With this tool it is possible to make comparision between different files and also build a report which can fit to the standards.

Online Visualisation



Wheel Force Measurement Telemetric recipient for all wheel forces

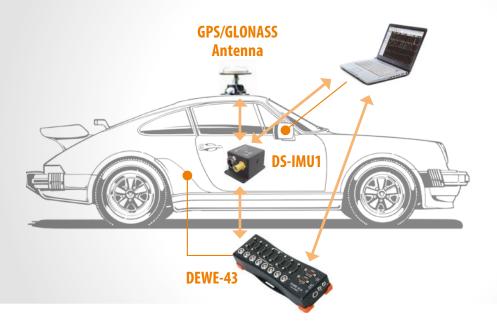
GPS Information

3D visualisation and analysis with Polygon Plugin for position data



System configuration

BASIC VEHICLE DYNAMICS SYSTEM



Possible R&D applications

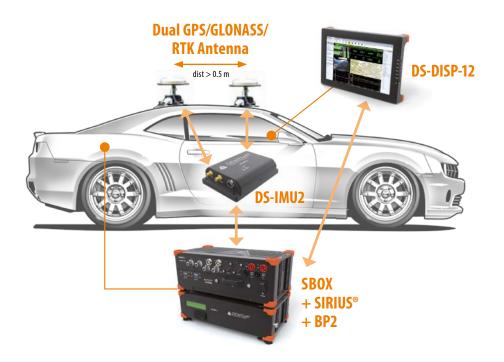
- ► Handling test,
- ► Brake/Acceleration test,
- ⊾ Lane change,
- Circle drive,
- ▶ Tire testing,
- ▶ Performance testing,...

Key features of the system

- 100 Hz update rate
 Distance measurement
- accuracy < 10 cm ► Additional inertial sensors
- (roll, pitch, angular velocity,..)

All DEWESoft® Automotive systems focus attention on

- ▶ Quick and easy installation
- ▶ Measurement results available online
- Scaleable systems for multiplepurpose usage
- Multiple data sources (analogue, digital, CAN, GPS, IMU, FlexRay, XCP, CCP, RoadDyn 2000, video & many more),
- Synchronisation between all data sources,
- ▶ Possibility to capture different software modules (vehicle dynamics, combustion analysis, vibrations,...) in one synchronized data file.
- **•** Export to many different file formats.



Additional R&D applications

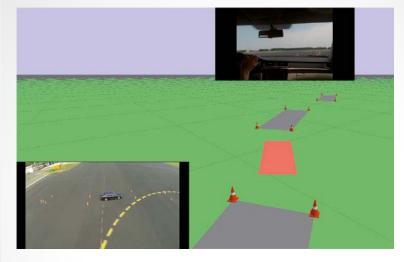
- ► Advanced driver assistance systems (ADAS) tests
- ▶ Pass by noise
- ⊾ FUSI

Key features of the system

- ▶ 500 Hz update rate
- ► High absolute position accuracy using RTK ±2 cm
- ► Dual antenna for 0,1° heading accuracy

Automotive Polygon Plugin

APPLICATIONS

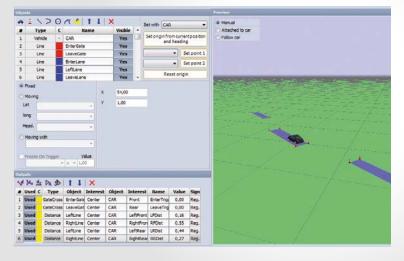


- ► All kinds of vehicle dynamics testing
- ▶ Brake test
- ▶ Pass-by noise test
- ▶ ISO lane change
- ► LANE departure warning (LDW) test
- ► CAPS (active passive safety)
- ▶ Functional safety
- ▶ Hybrid car testing
- ► Tyre testing

FEATURES

- ▶ Easy definition of test polygons for all kinds of vehicle dynamic and other moving vehicle involved tests
- Supports multiple vehicles and other moving or fixed objects
- ▶ Easy test polygon definition
- ▶ 3D visualisation with easily adaptable viewing angle
- ▶ Free definable outputs like distances, angles, gate crosses

EASY SETUP

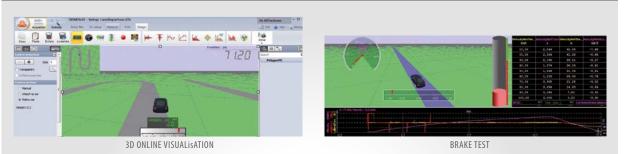


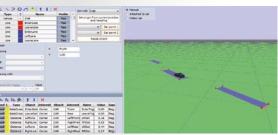
You can easily add moving or fixed, visible or hidden, simple or complex objects. There are six types of objects available:

- ⊾ Vehicle
- ▲ Simple object
- ⊾ Line
- ⊾ Route
- ⊾ Circle
- ▶ Travel radius

Each type has its specific properties, behavior, calculation options...

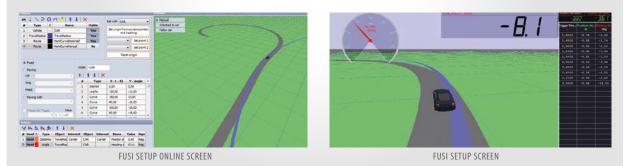
EXTENDED 3D VISUALISATION AND ANALYSIS





ISO LANE CHANGE MEASUREMENT

LANE DEPARTURE MEASUREMENT



BASIC DEWESoft® FUNCTIONS

- ► Analogue setup screen with TEDS
- ► CAN setup (DBC import/export + custom channels, time correction)
- ► ADMA Plug-in
- ▶ Video, visualisation
- ▶ Export, sequencer

OPTIONAL FUNCTIONS IN DEWESoft® X



- ► Noise and vibration testing including SOUND LEVEL MEASUREMENT
- ► Torsional and rotating anaylsis including BALANCING
- ▶ FFT and transfer functions
- ► CAN analysis and recording, FlexRay support
- ► GPS RTK (real time kinematic) and relative online calculation between several objects (cars)
- ► CAPS (active passive safety testing) automated online analysis
- Synchronized video camera support up to 100 000 frames per second
- ▶ Thermo camera support
- ► ALL SYNCHRONIZED (including IRIG and GPS absolute time UTC)
- ⊾ XCP, OBD II

ADAS Test System

TECHNOLOGIES THAT PROVIDE A DRIVER WITH ESSENTIAL INFORMATION, AUTOMATE DIFFICULT OR REPETITIVE TASKS, AND LEAD TO AN OVERALL INCREASE IN VEHICLE SAFETY FOR EVERYONE.



SYSTEM OVERVIEW

The latest GPS based position measurement technology is used to provide a highly accurate, easy-to-use ADAS test system. This is possible due to the RTK (Real Time Kinematic with 2 cm accuracy) option for GPS sensors. An immoveable GPS base station sends the correction data over a simple RF modem to all DS-IMU2 in wide area to achieve this accuracy.

Data from two or more vehicles provides very accurate position and distance information relative to each other and/or a fixed object, which is the basis for an ADAS test system. In addition DS-IMU2 provides accurate measurement of all vehicle dynamics, including side-slip angle.

All data is transfered to master system to obtain a measurement result during the test run. This is the standard functionality of DEWESoft®-OPT-NET and the Polygon mathematic module.

A robust WLAN solution is used to keep the communication between the systems for up to a distance of 1 km. There is theoretically no limit in the number of vehicles within this measurement— only the WLAN bandwidth limitation. All other data sources from any vehicle like analogue, counter, video, CAN, CCP/XCP, FlexRay and so on are synchronized together due to the GPS-PPS synch technology.

In addition to the features of the ADAS-Basic test system with IMU and GPS-RTK, the ADAS-Professional system includes the GeneSys IMU fiber optic gyro for applications where a GPS signal is not available for a longer period, such as in tunnels. This combination provides accurate measurement of all vehicle dynamics, including side-slip angle.

KEY FEATURES

- ▶ Ruggedized and reliable miniature GPS aided inertial navigation system and AHRS with High dynamic (500 Hz)
- ► Combination of gyroscopes, accelerometers, magnetometers and a pressure sensor with a dual antenna RTK GNSS receiver
- ► Highest precision and easy to use (fully integrated in DEWESoft® X)
- ► Any SIRIUS[®] module configuration
- ▶ Expandable with DEWE-43, SIRIUS® or DS-CAN2
- ► Many additional synchronized data sources like, Video, CAN, Flex Ray, XCP, OBDII...

THE FOLLOWING ADAS ARE JUST A FEW TESTING POSSIBILITIES THAT CAN BE DONE WITH THE LATEST TECHNOLOGY OF DEWESoft $^{\circ}$:

COLLISION AVOIDANCE TESTING



Real-time updates about relative distances, velocity, acceleration, detection of unavoidable obstructions around of a moving vehicle and ability to store all the other information of target vehicles which are need for collision avoidance testing.

BLIND-SPOT DETECTION TESTING

In automotive sense of the term, blind spots are areas outside of a vehicle that the driver is unable to see. To test and validate such system it's possible to use DS-IMU2, which provides up to 2 cm accurate position and real-time tracking.

30.04 27.03 125.35 3.14 TRT 13.59 3.54 -5499 2179 288 75.46 -2.04 105 - 1.13 399 1002 6.19 H_{11}

ACC is a system that is capable of automatically adjusting the speed of a vehicle to match the speed of the car or truck in front of it. If the lead vehicle slows down, adaptive cruise control can automatically match it. When traffic picks back up, these automatic systems are also capable of acceleration. It is critical to test such systems with different drive maneuvers, where systems developed by DEWESoft[®] are reliable, easy to use and time saving, because of quickly prepared setups.

ADDITIONAL APPLICATIONS

- ▶ All vehicle dynamics tests,
- ▶ Lane departure warning,
- ▶ Forward collision warning,
- Lane change warning,
- ⊾ Pre-crash,
- ▶ Intersection assistance,
- Rear collision warning
- ▶ Driver drowsiness detection testing, ...

ADAPTIVE CRUISE CONTROL TESTING

Road Load Data

INSTRUMENTS

DS-R8 WITH ANALOGUE OUT

- ▶ Multiple combination of up to 128 inputs (all the SIRIUS® modules)
- ▶ Up to 64 analogue outputs
- ▶ Up to 1 MS/s sampling rate

- ▶ Up to 8 CAN inputs
- ▶ High-end computer with the latest i7 generation processor
- ▶ SSD with up to 1 TB of storage



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| LD | | | | | | | | | SIRIUS | 5 - |
|----|---|---|---|---------|---|---|---|--|--------|-----|
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| | | | | | | | | | _ | |
| | | | | INCOMES | | | | | | |



| Max. isolated ChnNo. | 64 | 8 / slice | | |
|----------------------------|----------------------|----------------------|--|--|
| Sample Rate/Res. – opt 1 | 1MS / 16 Bit | 1MS / 16 Bit | | |
| Bandwidth – opt 1 | 2 MHz | 2 MHz | | |
| Sample Rate/Res. – opt 2 | 200 kS/s / 2x 24 Bit | 200 kS/s / 2x 24 Bit | | |
| Bandwidth – opt 2 | 75 kHz | 75 kHz | | |
| Base accuracy | 0.05% | 0.05% | | |
| Customised calculation | \checkmark | \checkmark | | |
| Analogue output | Up to 64 ch | Up to 8 ch | | |
| CAN/Flexray/XCP | \checkmark | \checkmark | | |
| Camera | \checkmark | \checkmark | | |
| Integrated GPS | \checkmark | - | | |
| Option Combustion Analyser | \checkmark | \checkmark | | |
| Option DSA package | \checkmark | \checkmark | | |
| Option Power | \checkmark | \checkmark | | |
| Storing raw data | \checkmark | \checkmark | | |
| | | | | |

INSTRUMENTS



The Road Load Data system provided by DEWESoft[®] is capable of recording the data during real test drives or at test rigs either for a whole vehicle or certain component. Afterwards this data can be replayed with the same system on a test bed to simulate all the forces and vibrations in the laboratory boundaries.

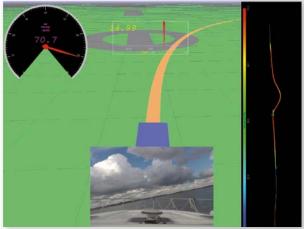
Such systems are also used in material research, process and parts approval, where it's important to optimise mechanical components to a real-life environment.

KEY FEATURES

- ▶ Connection of any sensor,
- ▶ Scalable from 8 to 1000 channels
- ▶ Input protection and optical ±1000 V ISOLATION
- ▶ Simultaneous sampling
- ▶ Anti aliasing filters
- ▶ Programmable analogue outputs
- ▶ TEDS functionality
- ▶ Quick and easy installation
- ► Highest precision and easy to use (fully integrated in DEWESoft[®] X)
- ► Measurement results available online
- ► Many additional sychronized data sources like analogue, digital, CAN, GPS, IMU, FlexRay, XCP, CCP, RoadDyn 2000, video & many more
- Possibility to capture different software modules (vehicle dynamics, combustion analysis, vibrations,...) in one synchronized data file.
- **•** Export to many different file formats

Related Applications on the sea





Vehicle Dynamics system provided by DEWESoft® is due to it's flexibility, quick and easy installation capable of testing also on the sea side.

Additionally because the systems are scaleable and therefore suiting for multiplepurpose usage, it's possible to measure different components of the ship. From engine with Combustion analysis, to electrical engines and batteries with Power module and in the end also vibrations all synchronized together.

APPLICATIONS ON THE SEA

- Handling testing (different slaloms),
- Pass by Noise,
- Avoiding obstacles,
- ► Component testing,
- Performance testing,...



Related Applications in the air



Due to ruggedness, high environmental protection and flexibility of the Advanced Vehicle Dynamics System it's possible to test an airplane, where all the components are under difficult conditions high G forces and huge temperature differences. It's crucial to get precise and accurate data while performing such a maneuvers especially orientation parameters such as Roll, Pitch, Heading and Angular Velocity, which are the key values for designers of the plane.

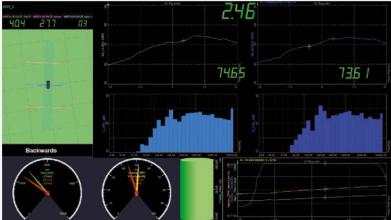


APPLICATIONS IN THE AIR

- ▶ High G maneuver testing,
- ▶ Component testing,
- ▶ Performance testing,..

Pass by noise





The DEWESoft[®] Pass by Noise system is a **flexible Research & Development measurement package**. In addition to hardware it contains powerful software for online check and validation of results.

Guiding the driver through a measurement is done with the help of DEWESoft[®] Sequencer module, which can be easily modified.

PPS-Sync technology and DEWESoft® NET software option allows the communication between different computers in Master/Slave mode. Online process and visualisation of the data is done on the Master computer.

ADDITIONAL APPLICATIONS WHICH CAN BE DONE WITH PASS BY NOISE SYSTEM

- ► Tire acoustic,
- ▶ Engine and gearbox acoustic,
- ▶ Tyre to road sound emission,
- ▶ Intake and Exhaust noise
- ► Sound pressure level emitted by stationary roadvehicles,...

SIRIUS[®] Combustion Analyser



SIRIUSi Combustion Analyser systems from DEWESoft[®] are used for engine research, development and optimisation. Also for component development and testing – such as ignition systems, exhaust systems and valve control gear. The system consists of our top of the notch isolated **SIRIUSi** hardware and the well-known DEWESoft[®] X software package for measurement and analysis.

It supports angle and time-based measurement and uses highly sophisticated algorithms for online or offline mathematics and statistics – calculating heat release and other thermodynamic parameters.

The combustion analyser can be fully integrated within a test bed and also supports data from other sources: e.g. Video, CAN, Ethernet, ...

If the powerful integrated post processing features of DEWESoft[®] are not enough, you can even export the data to several different file formats.

In addition to combustion analysis, the system can be expanded to handle other measurement applications such as hybrid testing on the power train, noise and vibration measurement together with **synchronized** video or GPS data.



Encoder OR 60-2 sensor

MAIN FEATURES

- ► 8 analogue inputs with sensor supply for any sensor and signal type
 - · Charge, IEPE, Voltage, Temperature...
- **•** Two versions in speed and resolution:
 - \cdot 16 bit, 1 MS/s for high speed engines
 - \cdot 24 bit, 200 kS/s for low rpm diesel engines
- ► Direct connection of any rpm sensor: InCar (e.g. 60-2), Encoder, CDM+Trg
- ▶ 1 isolated High speed CAN bus interface
- **Expandable to higher channel count**
- ▶ Interface to Test bed and INCA
- ► Simultaneous online analysis of
 - Torsional and rotational vibration
 - Order tracking
 - Electrical Power
 - \cdot Combustion noise
 - \cdot Sound power
 - \cdot and much more...

| HARDWARE | | SOFTWARE |
|-----------------|--|----------|
| SIRIUSi-HS-CA | A/D converter: 16bit, 1 MS/s SNR: 89 dB @ 100 kHz BW 0.1° resolution @ 6000 rpm and 8 channels | CA-BASE |
| SIRIUSi-CA | A/D converter: 2 x 24 bit dual core, 200 kS/s SNR: 150 dB @ 100 kS/s 0.1° resolution @ 1650 rpm 0.2° resolution @ 3300 rpm | |
| Common features | 4 CHG modules supporting: Charge signals up to 100 000 pC Voltage (up to 10 V), DC and AC coupling | |
| | (0.1 Hz) IEPE with 4, 8 or 12 mA and full TEDS support 4 LV modules supporting: Voltage (up to 100 V), DC and AC coupling (1 Hz) Programmable sensor supply up to 30 V/100 mA Full DSI support for any sensor signal 2 synchronized super-counters (LEMO 7 pin) | CA-OPT1 |
| | 1 CAN bus 2.0b isolated DS-TACHO with adjustable trigger level (max 100 V) All I/O fully galvanically isolated 1 kV USB2 interface, 6-36V supply, 2 sync connectors Optional channel expansion, battery packs BASE STATION (embedded PC) with 6x USB, HDMI, VGA, GigE, WLAN, GPS opt. CPU: Intel i7-3612QE 8 Core with 4 GB RAM Storage: 240 GB removable SSD Including DEWESoft® X Professional Edition and | CA-OPT2 |
| | Windows 7 Ultimate version (Multilanguage support) | CA-OPT3 |

• 9-36 V DC supply

| CA-BASE | Online mathematics, statistics, standard derivation Fast online displays: pressure, pV diagram, Time domain sampling, especially for cold start tests Includes on-line fast combustion "scope", configurable as pressure-volume diagram (pressure vs crank angle) Includes basic statistic, offline display, data storing, data export to ASCII (also Excel) and export to FlexPro and Concerto (AVL) |
|---------|---|
| CA-OPT1 | Extended mathematics, including online calculation of • Heat release • Standard deviation • IMEP, PMEP, NMEP • Thermodynamics • Knock detection |
| CA-OPT2 | Torsional vibration and rotational vibration analysis software (software only!) • Torsional vibration and static torsion measurement • Differential revolution and slippage measurement • Angle resolution up to 0.00075° at 10000 rpm • Supports all incremental position encoders • Rotational vibration analysis: requires only 1 encoder • Torsional vibration analysis: requires 2 encoders |
| CA-OPT3 | Combustion noise analysis (software only!) Online dB noise calculation based on the CA noise special filtering |



TEST BED APPLICATIONS



DEWESoft® Dynamic Signal Analyser

THE "5 IN ONE INSTRUMENT"

▶ FFT analyser

- ▶ Rotating machinery analysis
- ▶ Fast Data recorder
- ▶ From 4 up to more than 1000 channels
- ▶ Customized inputs, analogue, counter, CAN BUS

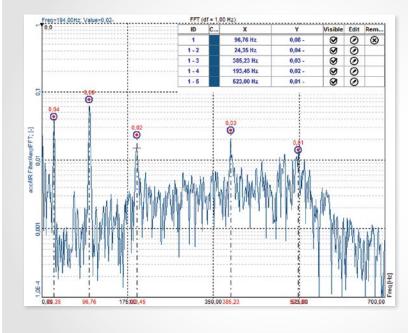


| | DEWESoft® DS-R8D- D S A | DEWESoft [®] DS-R2D - D S A | DEWESoft® SIRIUS -D S A | DEWESoft® SIRIUS -MINI - D S A |
|----------------------------------|----------------------------|---|----------------------------|-----------------------------------|
| | | | | |
| INPUT CHANNELS | | | | |
| Max. isolated ChnNo. | 64 | 16 | 8 | 4 |
| Bandwidth | 75 kHz | 75 kHz | 75 kHz | 75 kHz |
| Sample Rate | 200 kS/s | 200 kS/s | 200 kS/s | 200 kS/s |
| Base accuracy | 0.05% | 0.05% | 0.05% | 0.05% |
| Analogue input | IEPE or Voltage | IEPE or Voltage | IEPE or Voltage | IEPE or Voltage |
| Dynamic (2x24 Bit) | 160 dB | 160 dB | 160 dB | 160 dB |
| Counter inputs | 16 | 4 | 2 | 1 |
| INSTRUMENT - FUNCTIONS | | | | |
| FFT Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Order Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| CPB Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Envelope Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Time domain analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Modal Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Rotation Analyser | \checkmark | \checkmark | \checkmark | \checkmark |
| Analog output function generator | - | - | Option | Option |
| Analogue output data replay | - | - | Option | Option |
| ADDITIONAL - FUNCTIONS | | | | |
| CAN/Flexray/XCP | \checkmark | \checkmark | \checkmark | \checkmark |
| Additional Channels | Option | Option | Option | Option |

INSTRUMENTS

DEWESoft[®] DSA Instruments

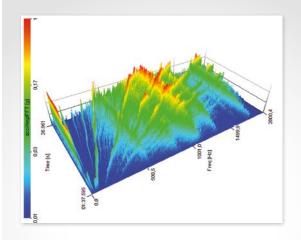
DEWESoft® FFT ANALYSER



Real-time, multi-channel FFT spectrum analysis, for vibration diagnostics, or narrow-band analysis of acoustic signals ► Auto spectrum and cross-spectrum

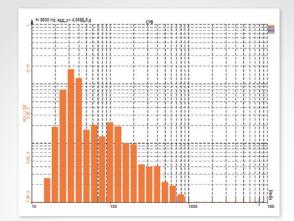
- ▶ Waterfall spectrum
- Resonance and damping estimation
- ► Harmonic and side-bands detection Pure tone detection
- Zoom FFT
- ▶ Cepstrum analysis
- ▲ Short time FFT
- ► Envelope (Bearing fault analysis)

DEWESoft® WATERFALL FFT - ANALYSER



The FFT waterfall shows e.g. a vibration spectrum of an engine runup versus time, it's like plotting multiple FFTs over the recording time. Critical frequencies can easily be identified by various displaying possibilities, such as lin / log / 2D / 3D

CPB ANALYSER



Real-time, standardized digital filter-based analysis using 1/1, 1/3, 1/12 and 1/24 octaves for analysing noise, determining sound power levels and machine vibration monitoring

- ▶ Sound level meter octave spectrum
 - complies with IEC61672
 - · Leq logging sound levels vs. time
- ▶ Sound intensity pure tone location while measuring
- ▶ Machine vibration level monitoring including pass/fail tolerance check
- complies with IEC61260 & IEC 60804

DEWESoft® DSA Instruments

MODAL ANALYSIS: EMA(EXPERIMENTAL MODAL ANALYSIS)



- ▶ SISO, MISO configurations
- NMA, normal mode analysis
- ▶ Spectral ODS
- ▶ Geometry editor with UNV import
- ▶ Mode indicator function MIF
- ▶ Circle fit analyse tool
- ▶ Function generator
- ▶ FRF from stored timed data
- ► Triggered, free-run measure mode
- ▶ Roving hammer excitation support
- ► Unv-file export for modal packages (ME-Scope, ...)
- ▶ Up to 1000 channels linked via OPT-NET

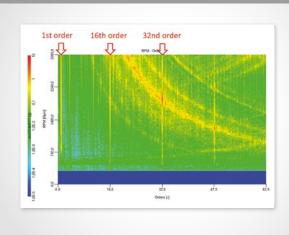
ROTATING MACHINERY ANALYSIS

Based on vibration and angle signals DEWESoft® offers a wide range of rotating machine analysis tools like:

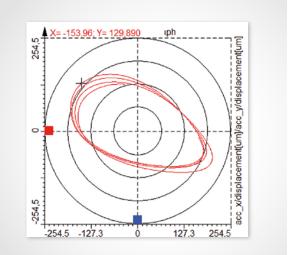
- Order Tracking Order analysis Order extraction
- ▶ Torsional and rotational Analysis, angle velocity and acceleration
- ▶ Orbit analysis
- ▶ ODS (Operating Deflection Shape)

ORDER TRACKING EXAMPLE

▶ Balancing



ORBIT GRAPH EXAMPLE



DEWESoft® DSA Sensors

DEWESOFT® DSA SENSORS

VIBRATION SENSORS

| | I1T-50G-1 | 13TI-50G-1 | l1TI-50G-2 | C1T-100G-1 | I1TI-500G-1 | I1AI-500G-1 | I3T-50G-1 | IH-440N-1 |
|----------------------|----------------------------|---------------------------|-------------------------------|---------------------------|-----------------------------|-------------------------------|--------------------------------|-------------------------------|
| | | | | Li Li | | | r C | Į |
| Number of axis | 1 | 3 | 1 | 1 | 1 | 1 | 3 | 1 |
| Sensitivity | 100 mV/g | 100 mV/g | 100 mV/g | 50 pC/g | 10 mV/g | 10 mV/g | 100 mV/g | 50 mV/lbf (=11,24 mV/N) |
| Range | 50 g | 50 g | 50 g | 100 g | 500 g | 500 g | 50 g | 100 lbf (=444,82 N) |
| Туре | IEPE | IEPE | IEPE | Ladung | IEPE | IEPE | IEPE | IEPE |
| Frequency range | +/- 5 %: 0.3 to 5000 Hz | +/- 10 %: 2 to 5000 Hz | +/- 10 %: 0.3 to 10 000 Hz | +/- 8 %: up to 5000 Hz | +/- 10 %: 1 to 10 000 Hz | +/- 10 %: 1.1 to 10 000 Hz | +/- 10 %: 0.3 bis 10 000 Hz | 75 kHz resonance frequency |
| TEDS | yes | yes | no | no | yes | yes | yes | yes |
| Features | miniature size | case isolated, triaxial | case isolated, industrial | high temperature | case isolated, modal | ultra-miniature | low noise, triaxial | modal hammer with TEDS |
| Dimensions | 10.2 x 10.2 x 10.2 mm | 15.5 x 15 x 15 mm | 17.5 x 42.2 mm | 12.7 x 24.4 mm | 19.4 x 12.7 x 16.1 mm | 9 x 6 mm | 12 x 12 x 11 mm | 221 x 71 mm |
| Weight | 4.3 g | 10 g | 44 g | 25 g | 10 g | 2 g | 5.6 g | 100 g (head) |
| Temperature range | -51 °C +85 °C | -51 ℃ +85 ℃ | -51 °C +121 °C | -51 ℃ +191 ℃ | -40 °C +85 °C | -51 ℃ +121 ℃ | -51 °C +82 °C | -40 °C +65 ℃ |

TACHO SENSORS

DS-TACH02

- optical tacho probe with LED
 Stainless steel with 2.5m cable
 - ▶ Up to 4kHz frequency
 - ▶ Distance to object up to 1m,
 - ► Power supply 3-15VDC, 45mA
 - Visible red pointer,
 - Control LED
 - ▶ Operating temperature -10°C to +70°C
 - ▶ Dimensions 73mm length, 16mm diameter
 - ▶ L1B7m connector for SIRIUS and DEWE-43 counter input
 - ▶ Incl. 30 cm reflector band

TACHO LEVEL CONVERTER

DS-TACH01

- ► Converts analogue tacho signal to TTL
- ► Fits to COUNTER input (Lemo 7pin) on DEWE-43 and SIRIUS
- ★100V input isolated, trigger threshold adjustable ±10mV ... ±2V

DS-TACHO3

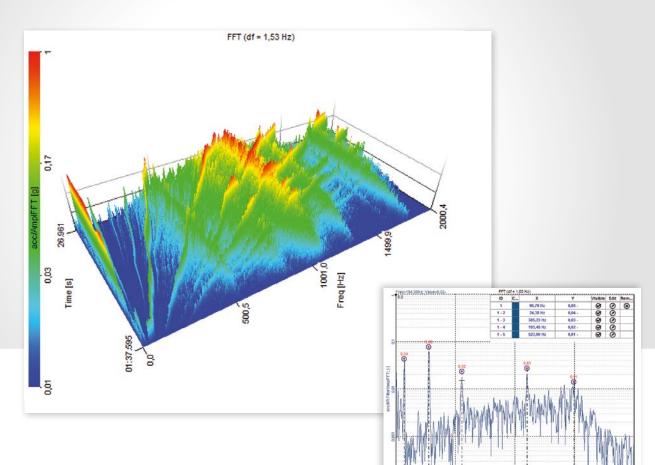
- optical tacho probe with LASER (red class2)
- Stainless steel with 2.5m cable
- Up to 4kHz frequency
- Distance to object up to 7.5m,
- Power supply 3-15VDC, 0,13W
- Visible red pointer, Control LED
- Operating temperature -10°C to +70°C
- ▶ Dimensions 73mm length, 16mm diameter
- ► L1B7m connector for SIRIUS and DEWE-43 counter input
- ▶ Incl. 30 cm reflector band

DS-TACH04

- Optical tacho probe with LASER (red class2)
- ▶ with 5m optical fiber and trigger box
 ▶ Up to 100kHz frequency
- ▶ Up to 100kHz frequency
 ▶ Distance to object 2-5mm
- ► Power supply 3-30VDC, 120mA
- ► Operating temperature -10°C to +70°C
- ► Dimensions M6 x 20mm2.5m cable with
- ▶ L1B7m connector for SIRIUS and DEWE-43 counter input
- ▶ Incl. 1 m reflector band with 2mm black/white grid



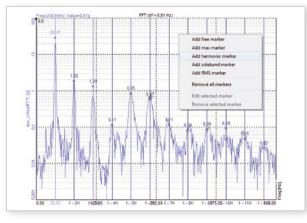
FFT Analysis



DEWESoft® offers various ways for sophisticated FFT analysis. With the release of DEWESoft® X2 a bunch of new useful features have been added.

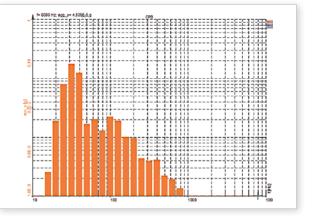
No matter if you need to see the seven highest peaks of the spectrum, or want to use the harmonic cursors to quickly identify all harmonics related to the fundamental – all just with one mouse click.

For acoustic applications the widely used octave plot can be utilised. The STFT is the instrument of choice when it comes to transient signals, such as shock and impact.



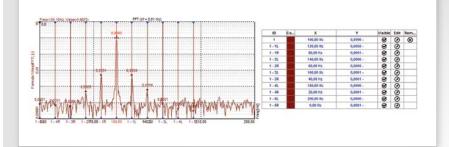
MAIN FEATURES

- ⊾ FFT
- Powerful markers (max, free, sideband, harmonic)
- ⊾ STFT
- ▶ CPB plot
- ▶ Auto-generated displays
- ▶ FFT waterfall plot
- ▶ Peak hold, Overall, RMS, amplitude weighting, ...

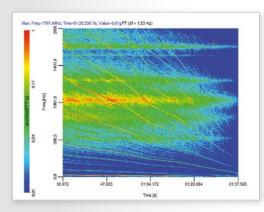


OVERVIEW

DEWESoft® X2 simplifies the way to set up instruments. Now you can add an FFT analyser just like any other module to your setup, and the according screen in measure mode is automatically generated. The added markers (free, max, harmonic, sideband) can of course also be displayed in a table as shown below.



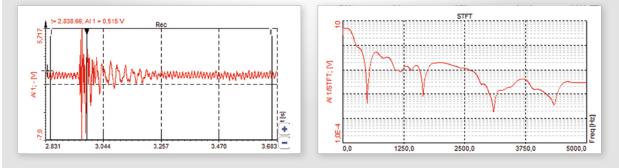




The FFT instruments and mathematics have all the different wellknown options, e.g. windowing, overlap, averaging, amplitude weighting, peak hold, overall spectrum, ... All these settings can also be done offline on the datafile, after the measurement was recorded.

The FFT waterfall shows e.g. a vibration spectrum of an engine runup versus time, it's like plotting multiple FFTs over the recording time. Critical frequencies can easily be identified by various displaying possibilities, such as lin / log / 2D / 3D.

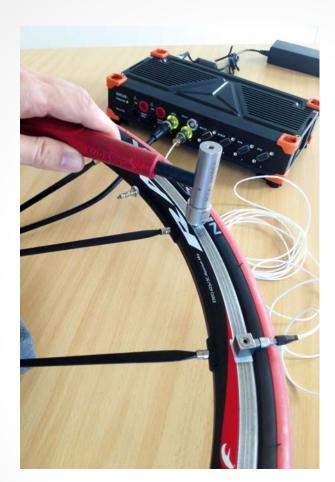
High frequency bursts are almost impossible to accurately analyse by standard FFT, because the calculation takes too long (during calculation the signal is quickly changing). For this reason DEWESoft® mathematics offers the STFT – short term Fourier transform –, which can have smaller blocks but still the same resolution as standard FFT. Therefore it's much faster.

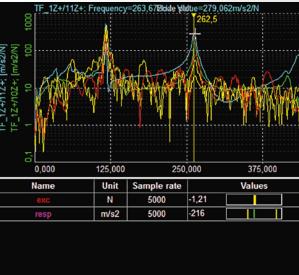


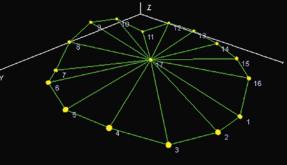
SUITABLE INSTRUMENTS



Modal-Structure Analysis







Modal analysis is needed in every modern construction. The measurement of system parameters, called modal parameters, is essential to predict the behavior of a structure.

These modal parameters are needed also for mathematical models. Parameters like resonant frequencies, structural damping, and mode shapes are experimentally measured and calculated.

DEWESoft[®] provides a hard- and software solution which is customized to your application. Starting from 8 channels used for maintenance, service and troubleshooting, up to 1000 channels used for complex structures.

The easy-to-use software is suitable for professional and occasional users.

MAIN FEATURES

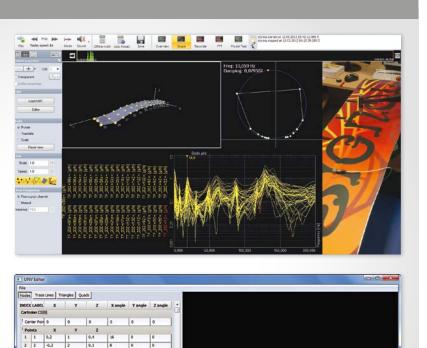
- ▶ SISO, MISO configurations
- ▶ NMA, normal mode analysis
- ▶ Spectral ODS
- ▲ Geometry editor
- ▶ Mode indicator function MIF
- ▶ Circle fit analyse tool
- ► Function generator
- ▶ FRF from stored timed data
- ► Triggered, free-run measure mode
- ▶ Roving hammer excitation support
- ▶ Unv-file export for modal packages (ME-Scope, ...)
- ▶ Up to 1000 channels linked via OPT-NET

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OVERVIEW

To measure an FRF of a structure basically two channels are needed. One channel is used to measure the excitation force, which could be an impact hammer or a shaker. This excitation force excites the structure, and at least one acceleration sensor measures the response of the structure. Out of that the transfer characteristic (FRF) and the modal parameters are calculated.

To determine the structure, you have to measure several points to get the whole system identified. This could be done either with one response or up to hundred or thousand channels depending on the complexity of the structure.



Add Cartesian Add Cylindrical CS

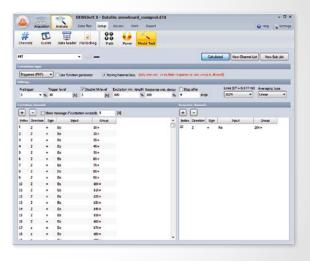
CHANNEL SETUP

In the channel setup the excitation-, and the response channels are defined. Most DEWESoft[®] devices support the state of the art TEDS interface which gives the maximum comfort especially at high channel count.

The FRF setup provides all parameters needed for the measurement

- ▶ Free run, triggered mode
- ▶ Average
- ▶ Excitation window length
- ▶ Response decay
- ▶ Trigger levels
- ▶ Overlap

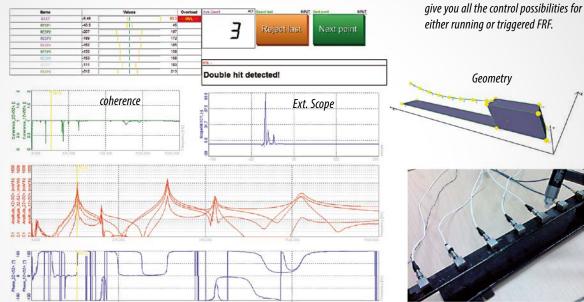
Also the channel definition according to the structure is done in the FRF setup. A structure could be imported from any other software with .unv file format or created with the included geometry editor.



Save and Exit

MEASUREMENT

Analogue overload indication



The tool bar provides all important and necessary functions which are needed during the measurement. At Single Input Single Output (SISO) measurement either the excitation or the response could be moved, because sometimes it is easier to move the excitation than the response. DEWESoft® supports both types of this measurement.



The prepared measurement screen will

ANALYSIS

In the analyse screen the FRF spectra are shown together with the geometry.

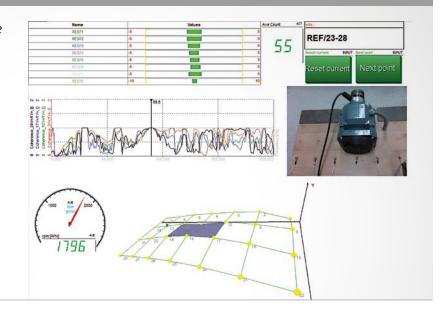
The included analyse tools like

▶ animation of the geometry,

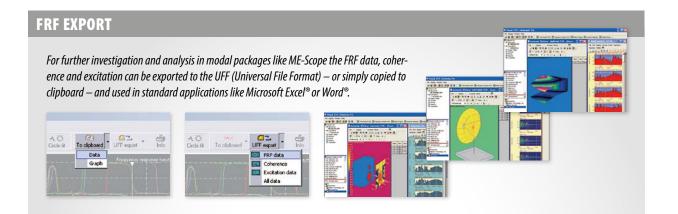
- ▲ circle fit,
- ⊾ MIF

are provided to determine the results immediately.

In case of an error the spectrum could be re-measured immediately. This saves time and money. Display options could be set according to the needs. Phase, Coherence, Re-, Imag, are only a few possibilities which could be set.



INSTRUMENTS



Frequency resolution like FFT

Exact resonant frequencies must be

calculated out of mathematical mod-

els. Circle fit, SDOF System (ME-SCOPE)

FUNCTION GENERATOR

For a running FRF the structure is excited with a shaker. Here either one shaker or multiple shakers for big structures are used. The shaker(s) have to be controlled mainly in amplitude, phase, waveform and frequency. DEWESoft® offers an integrated function generator of up to 16 channels which is fully software controlled. Various time patterns like

- Fixed
- Sweep
- ▶ Step sweep
- ⊾ Burst
- ⊾ Chirp

are configurable for any application.

Technical Data: Function Generator

- Smooth change for shaker control
- ▶ 24 bit D/A up to ±10 V
- ▶ Watchdog
- ▶ Frequency resolution 1 mHz with 10 ppm
- ▶ Phase adjustment 0.05°
- ▶ Sine, square, triangle, ramp, noise, ...
- ▶ Up to 1 MHz D/A rate SNR>80dB, THD<0,05%
- ▲ Arbitrary output/file replay
- ▶ Fix frequency, lin/log SWEEP, CHIRP, BURST Mode or STEP sine

Requirements (Hardware and Software)

NMT (NORMAL MODE TESTING)

Whats the difference to FRF?

Phase

- ▶ ICP®-Inputs
- ▶ DEWESoft® SIRIUS®
- ▶ DEWESoft[®] option FG
- ▶ DEWESoft[®] option FRF
- ▶ DEWESoft® option SRS



Resonant frequency will be

DEWE-FGEN.

MIF

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searched manually by changing

If Excitation and response have a

phase shift of 90deq this is called

Normal Mode and indicates the resonant frequency.

With this method no additional

mathematic is needed, because the frequency set at FGEN indi-

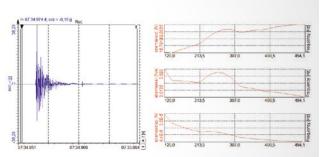
cated the resonant frequency.

the excitation frequency of the

SHOCK RESPONSE SPECTRUM (SRS)

The shock response spectrum shows the maximum responses of a series of uniformly damped single-degree-of-freedom (SDOF) systems caused by a shock waveform applied on the structure. After setting damping, resolution (1/12, 1/24, 1/48, 1/96/octave) and primary section, the spectra are calculated out of the time domain signals.

After the time domain signals are recorded, the data is analysed by the DEWESoft[®] SRS plugin. The easy-to-use user interface offers a convenient straight forward procedure for fast results.



Torsional and Rotational Analysis

SOFTWARE

Rotating machines and engines are sources of rotational and torsional vibration. Rotational vibration is a result of the change in shaft speed during one revolution and torsional vibration is due to angular twist in the shaft or drive train which may cause fatigue.

So you will observe: vibration, force, strain, voltage, current, power, CAN data and rotational- and torsional vibration with only one instrument at the same time.

That's unique!

MAIN FEATURES

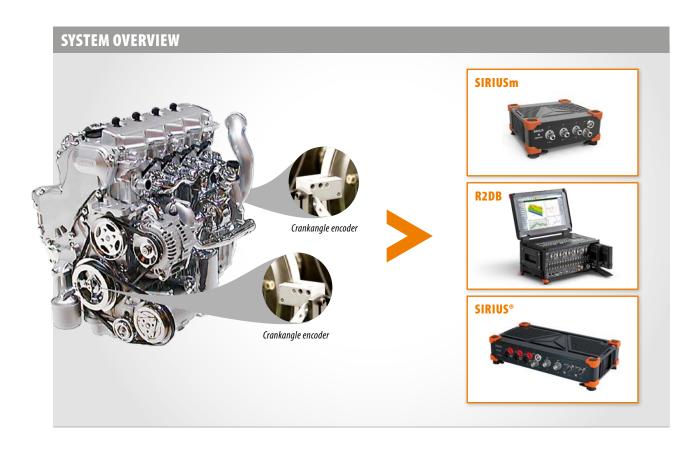
- ▶ Time domain measurement
- ▶ Angle based view
- ▶ In addition to other functions (analogue, CAN, GPS, video, ...)

چ ک

- ▶ Configurable display
- ► Direct sensor connection
- ▶ 102 MHz counter time base

APPLICATIONS

- ▶ Power train
- ▶ Paper mill
- ▶ Combustion engine
- ▶ Belt drive
- ▶ Engine test bench
- **Examination of rotating field**



SETUP

For rotational vibration measurement one rpm sensor is used to determine the rpm deviation and for torsional vibration there is one at each end of the power train. DEWESoft[®] hardware supports a wide range of different sensors e.g. encoder, pickup, RIE-360/720 and many others. These are connected directly to a counter input of the system. Each counter input provides a power supply, 3 differential inputs with selectable trigger level compatible with all sensor outputs.

The automatic display generation makes it easy to setup the measurement within minutes. Digital input filters, a sensor database and a reference curve eliminates sensor errors. Various output channels are immediately provided for further investigation:

- ▶ *Reference angle [deg]*
- ▶ RPM [rpm]
- ▶ Rotational angle [deg]
- ▶ Rotational velocity [deg/s]
- ▶ Rotational acceleration [w/s]
- ► Torsion angle [deg]
- ► Torsion velocity

The picture on the right shows a typical analysis screen. Data is shown either in

- ⊾ time domain or
- ▶ angle domain

together with all other measured channels. By selecting the order analysis module you will get order based results.



SIRIUS

Rotating machines and engines produce vibration from many sources, including rotational and torsional vibration. Also unbalanced rotating parts are sources for vibration. Unbalanced masses are distributed by the rotor causing vibration. To balance a system, we have to measure and correct the masses so that the rotor is returned to a balanced condition.

DEWESoft[®] provides an easy-to-use and straight-forward tool for single and dual plane balancing. This add-on is included as an option in every DEWESoft[®] instrument. One or two acceleration sensors and a tacho probe are needed.

MAIN FEATURES

- ▶ User interface which guides through all steps
- ▶ Order tracking based balancing method
- ▶ Single or dual plane
- ► Multiple balancing for two directions saves time (X, Y)
- ▶ 2D graph for plane view
- ▶ *RPM channel with color indicator (rpm range)*
- ► Alarm output if velocity exceeds predefined value
- ▶ Displays tacho probe time signal to set trigger
- ▶ Vector polar plots of 1st order of all runs (initial, trail, ...)
- ▶ Weight splitting
- ► Acceleration, velocity, displacement in recorder
- ▶ Time domain measurement

SOFTWARE

GENERAL

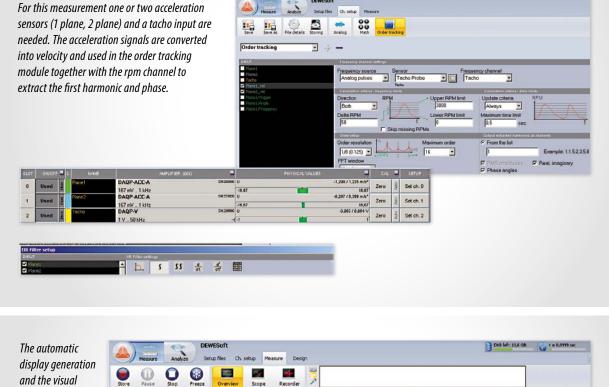
During construction or assembly of a machine or even through abrasion, a rotor could become unbalanced. This condition causes vibration, noise and fatigue of the material.

DEWESoft[®] provides an in-field-balancing method, which enables balancing of the machine. This saves time and money because balancing can be done in situ and the rotor is balanced in its operating condition, which includes the whole structure of the machine.

Balancing includes in general five steps:

- 1. Measuring the imbalance
- 2. Add a trial mass
- 3. Add the correction mass (balancing)
- 4. Measuring the balanced system
- 5. Repeat steps 2 to 4 if needed

Balancing is done either for one plane or two planes. One plane is used for small rotors, and two planes is used for long rotors.



display generation and the visual component in DEWESoft® provides step by step guidance through the whole balancing procedure.



MULTIPLE TEMPLATES LINKED TOGETHER

If a triaxial sensor is used, the balancing can be done on x and y direction of the plane(s) at the same time. Depending where you get the best result (x or y direction) you choose the correction mass. This saves time and guarantees a high quality of balancing.





MULTIPLE TEMPLATES LINKED TOGETHER

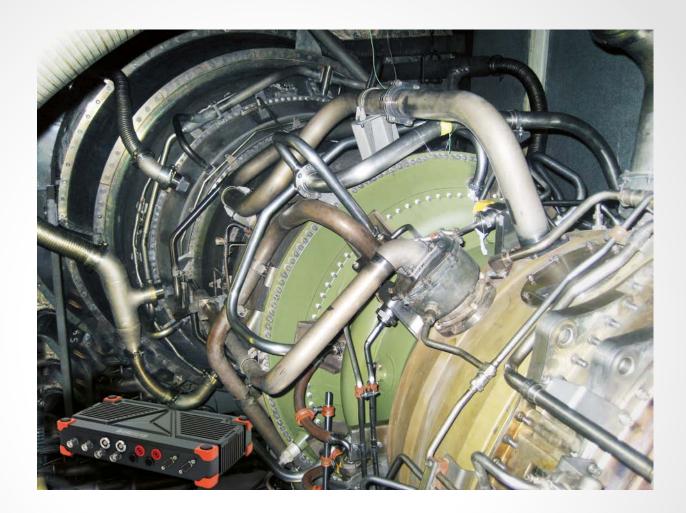
Acceleration sensor

R2DB

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INSTRUMENTS

Order Tracking



Rotating machines under operational conditions require additional analysis such as order tracking. Compared to normal FFT the spectrum is based to orders instead of frequency (time). The orders describe the fundamental or a multiple of the actual rotation speed [Hz]. With this method you can separate frequency components which are related to engine speed and that are related to structure.

DEWESoft[®] provides a powerful and very easy-to-use order tracking module for fast and efficient results. The data and the rpm information is recorded simultaneously in time domain and re-sampled in the order tracking module. Therefore we can show narrow band FFT, waterfall spectra, and still keep all other convenient functions in time domain.

MAIN FEATURES

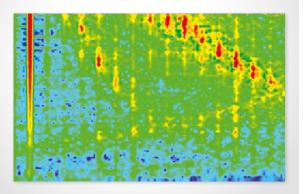
- ► Dedicated re-sampling method for sharp order separation
- ▶ Measurement in time domain to keep all benefits
- ▶ 2D, 3D waterfall in order or frequency domain
- ▶ Amplitude, phase extraction
- ▶ Recalculation in post processing
- Phase synchronous rpm input with 9.8 ns resolution
- ▶ Easy to setup

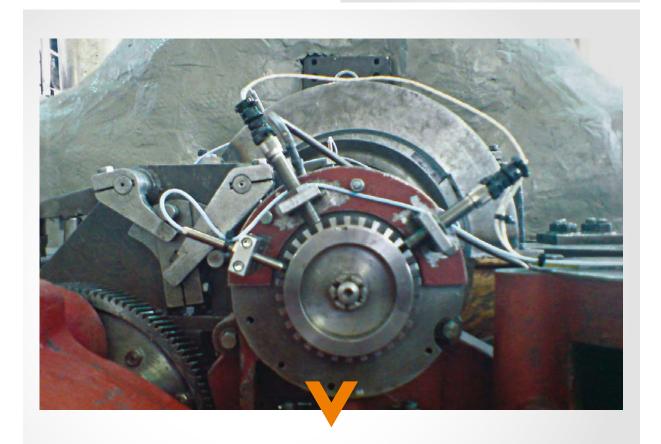
OVERVIEW

Order tracking requires two signals, the vibration signal and the rpm information. The measurement is done in time domain, and all the order related channels are calculated out of these time signals.

A fast state of the art re-sampling method produces the results online. Run-ups, coast-down or both are possible online.

Time based data recording enables recalculation even in post processing. Narrow band FFT, CPB spectrum and order tracking information could be shown at the same test run, saving time.







CHANNEL SETUP

Simply specify the channels to analyse, define the rpm channel and set the parameters for your run. This will only take a few minutes and you are ready for the test.

Immediately after configuration, you will get the calculated results which can be shown in dedicated instruments for analysis and reporting:

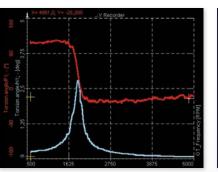
- ⊾ Amplitude
- ▶ Phase
- ▶ RE- Imag- Part
- ► Order resolution up to 1/64 order
- ▶ Upper- lower- rpm limits
- Extract specific orders for further investigation

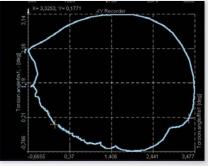
- 0 x 0 00 11 3 n-d • E0_CNT0 ▼ 100 ns ▼ 1.3.5.7.10 1/8 (0.125) • FT window •

ANALYSIS

In the easy-to-use analyse screens data could be shown and analysed in many different ways. So you could draw orders or narrow band FFT in 2D and 3D waterfall diagrams. Either displayed with time history or rpm. Specific orders or phase information could be recorded over time, rpm or any other physical value. All analysis screens could be arranged in a convenient way. <complex-block>

Amplitude or phase is shown over rpm, RE- IM- Part displayed in XY diagram to observe resonant frequencies.



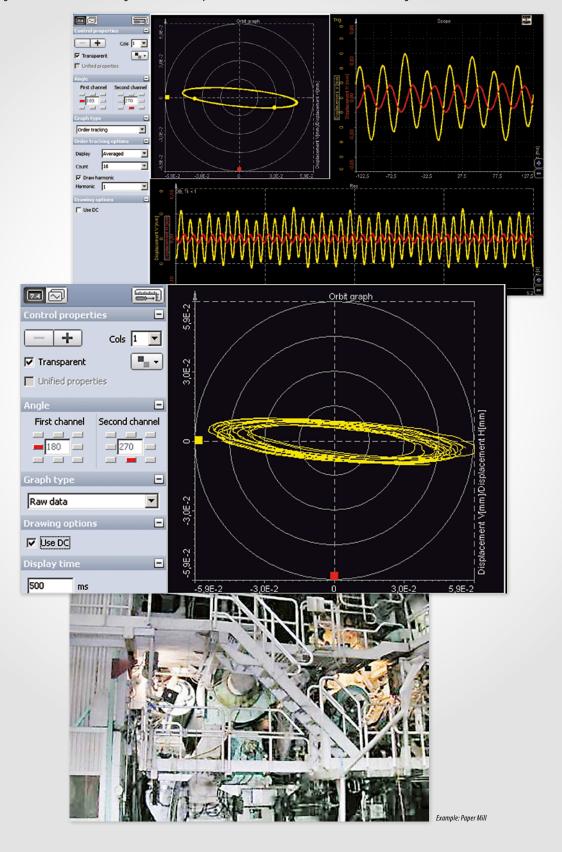


SOFTWARE

INSTRUMENTS

ORBIT VIEW TOGETHER WITH ORBIT TRACKING

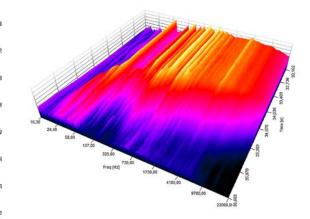
In addition, the order tracking module is also used to show an orbit plot which is used to observe bearings or movements of rotating machines. The order tracking module extracts specific harmonics in the orbit view and also averages them.



Industrial Acoustics

Frequency analysis is a big issue in acoustics. Octave and fractional octave bands are used for this in most cases. The Sound Level plugin (included in the DSA package) provides an extensive choice of tools for frequency analysis, where all weighting functions for time and frequency weighting are implemented.

For complex acoustic analysis, advanced measurement tools are available in addition to the standard analysis tools.

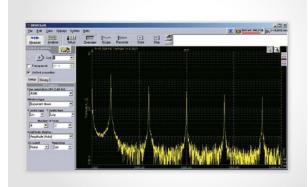


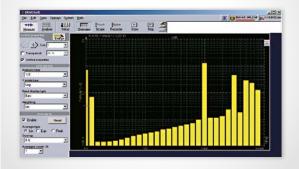
MAIN FEATURES

- ▶ Real time narrow band FFT
- ▶ 1/1, 1/3, 1/12, 1/24 band octave spectrum
- ► A-, B-, C-, D-weighting (frequency weighting)
- ► Fast-, slow-, impulse-weighting (time weighting)
- ▶ Leq-calculation
- Sound level meter

POST-PROCESSING FEATURES

- ► FFT, octave analysis and weighting
- Sound level meter
- ▲ Sound power measurement

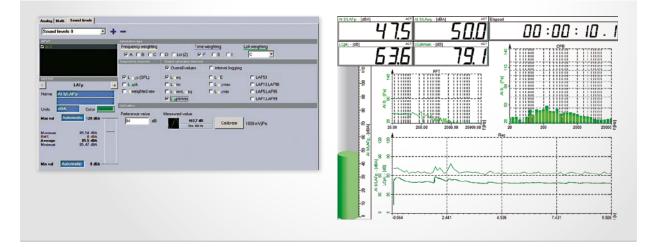




SOUND LEVEL METER

DEWESoft® calculates several parameters online:

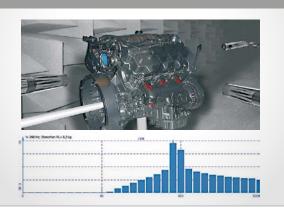
| FUNCTION | DESCRIPTION |
|---------------|--|
| Lp (8PL) | Time (F, 8, I) and frequency weighting (A, B, C,) sound level [dB] |
| Lpk | Current maximum sound level [dB] |
| Weighted raw | Frequency weighted (A, B, C,) sound level [dB] |
| Log | Equivalent sound level [dB] |
| Lim | Pulse weighted equivalent sound level [dB] |
| Lpkmax | Absolute maximal sound level [dB] |
| Lo | Sound exposure [dB] |
| Lmax, Lmin | Maximum and minimum Lp sound level |
| LAF50, LAF10, | Classes for 0, 1, 5, 10, 50, 90, 95 and 90 dB |



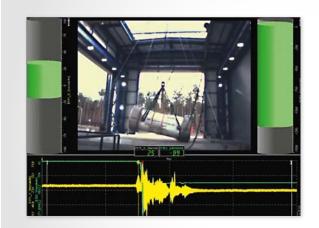
SOUND POWER MEASUREMENT

Sound power measurements are important for noise measurements and qualification of noise emission from machines and products (CE mark). They can be done with two measurement procedures, measuring the sound pressure or the sound intensity. Both are supported with the Sound Level plugin (included in the DSA package). Following corrections will also be done:

- ▶ Barometric pressure and temperature (K0)
- ▶ Background noise (K1)
- Surrounding correction (K2)
- ▶ Measurement area (Ls)



Transient Recorder



DEWESoft[®] brings a new faster version of the well-known and reliable SIRIUS[®] hardware. The new version is called SIRIUS*i*-HS (high speed) and has the following highlights:

- ▶ 1 MS/s/ch sampling rate
- 16 bit resolution
- ► Measurement modules (bandwidth 300 kHz):
- ► HS-ACC (ACC+): Voltage (+super-counters)
- ► HS-LV: Low voltage measurement
- ► HS-HV: High voltage measurement

SOPHISTICATED TRIGGER FUNCTIONS & ALARMS

The versatile trigger condition setup of DEWESoft[®] leaves nothing to be desired. The flexible trigger conditions can be used to start/stop the acquisition or to control a digital alarm channel: i.e. You could use this to to stop the engine in case of certain alarm conditions.

- When using the data-trigger conditions you can choose to trigger on
- ▲ The real data
- Average
- RMS (root mean square)
- Minimum
- ⊾ Maximum

It is possible to define a trigger within the Fourier spectrum using a FFT trigger for a certain range of frequency - so you can trigger from frequency and magnitude. Even relative or absolute time as a trigger source can be set to trigger an action. You can always press the manual TRIG button to force an acquisition at any time.

Trigger Types Simple edge (either rising or falling slope) Window trigger (two levels; entering or leaving logic) Pulsewidth trigger (longer or shorter than duration logic) Window and Pulsewidth (completely selectable as above) Slope Trigger (rising or falling slope with steepness selection)

ACQUISTION SPECIFICATIONS

| | ACQUISITION MODES |
|-----------------------|--|
| Scope/Transient | 300kHz bandwidth, 1MS/s, 16 bit ADC per channel, single shot or continuous |
| Frequency Analyser | Real-time FFT analysis up to 1MHz with simultaneous time domain displays |
| Signal Averaging | Both time and frequency domain averaging are available to reduce noise and increase resolution |

| ACQUISITION SPECIFICATIONS | | | | | | | | | |
|----------------------------|---|--|--|--|--|--|--|--|--|
| ACQUISITION SPECIFICATIONS | | | | | | | | | |
| Transient Memory | Limited by HD size; typical 128 GB | | | | | | | | |
| Sweep Length | Limited by HD size; typical 128 GB | | | | | | | | |
| Pre-trigger | Limited by internal memory | | | | | | | | |
| Post trigger | Limited by HD size; typical 128 GB | | | | | | | | |
| Trigger modes | Data/FFT/Time triggers on any channels | | | | | | | | |
| Trigger conditions | Simple edge, Window, Pulse width, Slope + any logical combinations | | | | | | | | |
| Number of triggers | Unlimited by multi file feature | | | | | | | | |
| Bandwidth | 300kHz | | | | | | | | |
| Filter type | All kinds of software filters | | | | | | | | |

HIGH SPEED STREAMING

Through the entire history of DEWESoft® the performance in storing was one of the most important issues. The PC technology has advanced through the years and we are using all possible resources to get more from the system. We achieve more than 160 MB/second sustained stream rates. Even with such high rates, DEWESoft® can reload large data files in seconds and you can zoom into the data until you see every individual data point. ing recording, your data files will not be corrupted. You will lose some of the last samples immediately before the power-loss but you can open the datafile and analyse it without any problem.

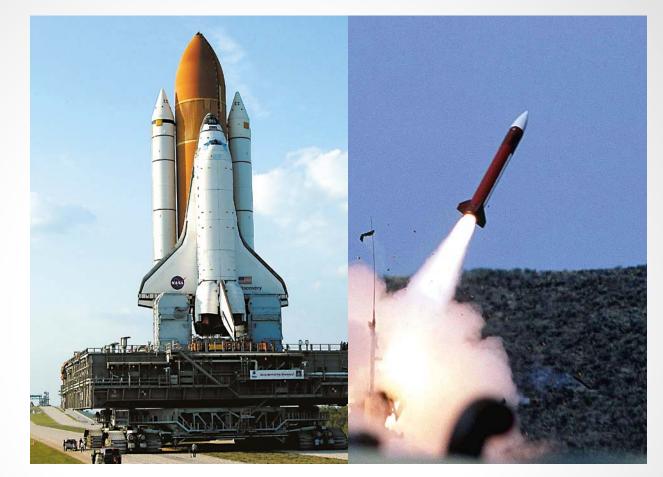
Even during recording of the measurement you can freeze the measurement screen and analyse the current data (in the meanwhile storing to the data-file will continue uninterrupted and you will not lose a single data point).

Even in disastrous events, such as complete power-loss dur-

| | SIRIUS-HS-ACC | | SIRIUS | e HS-CHG | o SIRIUS | -HS-STG | SIRIUS-HS-HV | SIRIUS-HS-LV | | | | |
|----------------------------|---------------|--------------|--------------|--------------|--|-----------|----------------------------|--|--------------|--|--|--|
| | sirius-i | 8 15-ACC+ | SIRIUS-I | B-CHG+ | SIRIUS- | NS-STG+ | - | SIRIUS-HS-LV+ | | | | |
| Module Type | HS ACC | HS ACC+ | HS CHG | HS CHG+ | HS STG | HS STG+ | HS HV | HS LV | HS LV+ | | | |
| Data Rate (up to) | 1 N | IHz | 1 MHz | | 11 | ИНz | 1 MHz | 1 MHz | | | | |
| Vertical Resolution | 16 bit | | 16 | i bit | 16 | bit | 16 bit | 16 bit | | | | |
| Isolation Voltage | 100 | 0 V | 10 | 00 V | 10 | 00 V | CAT II 1000 V | 100 | 00 V | | | |
| ANALOGUE | | | | | | | | | | | | |
| Input range | ±10 V to | o ±0.2 V | 100 000 pC | C to 1000 pC | 500 mV/V | to 2 mV/V | ± 1600 V to ± 20 V | ±100 V t | o ±50 mV | | | |
| IEPE/ICP Sensors | \checkmark | | • | / | DSI o | option | | DSI option | | | | |
| Sensor (excitation) Supply | 4 or 8 | 8 mA | 4 or 8 or 12 | mA, max 25 V | 0 20 V max. 0.1 A/0.8 W, 0 60 mA | | | 230V bipolar 024V unipol. max. 0.2 A/2 W | | | | |
| TEDS support | IE | PE | IEPE | | \checkmark | | | v | \checkmark | | | |
| Pt100, Pt1000 | | | | | \checkmark | | | DSI o | ption | | | |
| Thermocouple | | | | | DSI option | | | DSI option | | | | |
| Charge | | | ١ | / | DSI option | | | DSI option | | | | |
| Digital | | | | | | | | | | | | |
| Counter | 0 | 1 | 0 | 1 | 0 | 1 | | 0 | 1 | | | |
| Digital Input Channels | 0 | 3 | 0 | 3 | 0 | 3 | | 0 | 3 | | | |
| Digital Output | 0 | 1 | 0 | 1 | 0 | 1 | | 0 | 1 | | | |
| CONNECTORS | | | | | | | | | | | | |
| BNC | 1 | I | 1 | | 1 | | 0 | Option | | | | |
| DSUB 9 | (|) | | 0 | | 0 | 0 | 1 | | | | |
| Banana | (|) | | 0 | | 0 | 1 | Option | | | | |
| (Counter) LEMO 7pin | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | | | |

SIRIUSI-HS MODULES

Aerospace TELEMETRY



DEWESoft[®] is the next generation of Telemetry Ground Station software for real time telemetry data processing and Mission Control Room Displays with full post mission analysis capabilities. The Telemetry interface is built around the established DEWESoft[®] user friendly and reliable software to process/display/record critical mission data.

DEWESoft[®] has based its Telemetry data interface around the IRIG 106 Chapter 10 Ethernet protocol. Along with the real time Ethernet interface DEWESoft[®] has the ability to read any vendors recorded IRIG 106 Chapter 10 data file. With different hardware solutions any application has a solution to get their data real time into the DEWESoft[®] platform. Utilising the Dewe-NET Ethernet option this solution can be scaled from a single portable system to the Launch Control Center at NASA's Kennedy Space Center.

MAIN FEATURES PCM

- ► Easy to use interface to setup the hardware and software process the data
- ► Able to bring in Telemetry data from wide variety of sources
- ▶ IRIG Chapter 10 Processing (Ethernet & .CH10 File) and Record capability
- Synchronized PCM, Analogue, ARINC 429, GPS, and 1553 data inside of DEWESoft[®]
- ► Full range of hardware solutions from a USB brick to an entire Ground Station Server.
- ► Integrated drivers for VAR Single Board Receivers and Single Board PCM Processors with Simulator.
- PCM Encoder functionality using the DEWESoft[®] data acquisition hardware

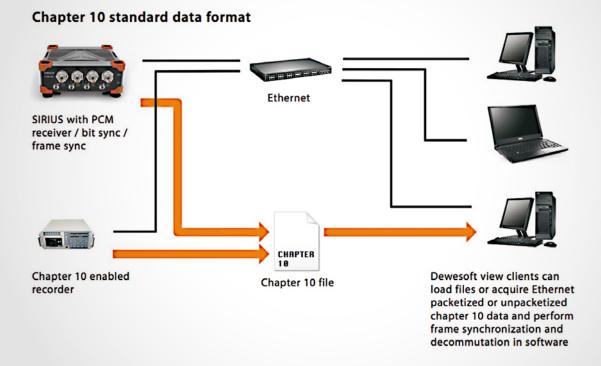
GROUND STATION

The DEWESoft® Ground Station solution is focused on accurate and efficient data processing. Starting with the Ethernet IRIG 106 Chapter 10 interface users can be supplied data from a variety of channels like PCM, Analogue, Mil-1553 and Video. This interface gives the users the flexibility to look at a wide variety of data sources on the screen at the same time. With TMATs built into the Chapter 10 structure the software can automatically tell what each data stream is and prepare it for further processing.

DEWESoft[®] performs real time software based frame synchronization and decommutation on any PCM stream. Capable of extracting multiple embedded PCM streams for decommutation in the software simultaneously. Individual parameters can be defined with easy to interpret setup screens. Once the parameter is defined as a channel all the tools and mathematics of DEWESoft[®] can be used.

Each sample from a Decom parameter is given an individual time stamp to keep all data within DEWESoft® time correlated. This gives any parameter the ability to have independent math functions performed on the data real time for the user. The DEWESoft® solution gives the user the ability to store their data in a magnitude of ways to meet any mission requirement. One way is to store a DEWESoft® data file (D7D) which can be analysed by anyone free of charge using DEWESoft® analysis section of the software. DEWESoft® is also able to store the raw frame data in an IRIG 106 Chapter 10 data format. Chapter 10 files are stored in such a form that they can later be replayed by any Chapter 10 recorder. Utilising Ethernet connections, data can be transferred between any number of hardware systems. Each client is given the ability to setup, display and record their own data subset in real time. The Ethernet connection allows for data real time data transmission to any number of view client computers. Within a single package, users can process multiple telemetry streams while displaying & recording the decommutated data in visually stunning displays.





VARIETY OF HARDWARE

The DEWESoft® has a wide variety of hardware it can interface with in the Telemetry Market. Using the Chapter 10 interface any Telemetry data recorder can be used to feed data real time over Ethernet or a prerecorded file to DEWESoft®. This gives the user the ability to only have to learn a singular software package for data Analysis. The DEWESoft® Frame Sync box allows users to bring in up to 40 Mbps Clock & Data signals into a platform independent solution. The Frame Sync box can receive to independent data streams into a single system. The units can then be daisy channel together to allow for higher channel counts.



The USB interface and size of the Frame Sync box allow this product to go out be tossed in a backpack with a standard Windows laptop for a flight line checkout. When combining this product with a portable computer or the DEWESoft® SBOX this solution can provide telemetry data processing in the aircraft and provide the pilot a visual display of the Telemetry data real time. This giving the ultimate flexibility to the engineer to solve their mission requirements.

What makes DEWESoft[®] unique in Market is the ability to combine standard DEWESoft[®] Data Acquisition solutions with Telemetry data, Aircraft Bus data, Video. This giving the

end user the flexibility to only have to invest their time into learning a single easy to use software interface for a variety of solutions.

CHAPTER 10 INTERFACE

With the scalability of DEWESoft® the user can take the entire ground station capability into one computer. DEWESoft® utilised the IRIG-06 Chapter 10 standard file and real time Ethernet format to bring in variety of data types simultaniously.

Interface with Chapter 10 file & Ethernet packets real time consisting of

- PCM Data (unpacked, packed and throughput)
- Mil-1553 and ARINC-429 BUS Data
 Video (Ch10 Channel and Embedded in PCM stream)
- ► Ethernet & UART Data Channels
- ► Analogue Channels
- TMATS (setup channel)
- Timing (absolute time)

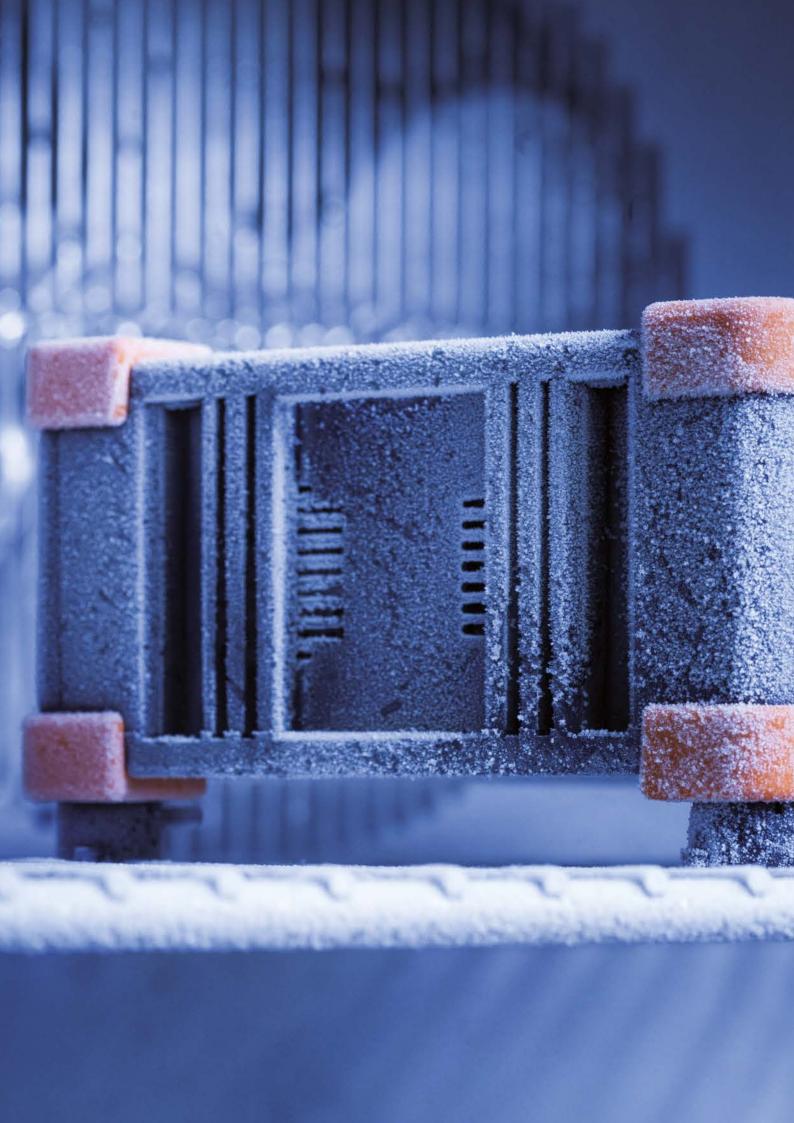
| | Acquisition A | nalysis Setup files Oh. | setup Measure | | | |
|---|--|---|---|--|--|--|
| Rore | Save Sav | e as File details Storing | Analog PCM Chapter 18 | 00 Math | | |
| eproduce | et | | | | | |
| file List: DeweSoft | Test Recording, | 10xec.ch10 | Stat position: 10/18/2014 3:49:08 PM (0 Stop position: 10/18/2014 3:49:27 PM (1 Continuous Loop Mode Replay ra | RECORD(E) # 10/18/2 STOP # 10/18/2014 3 | 2014 3 49 08 PM 49:27 PM | |
| Directory: D | DEWESoft File | to for all versions\Setups\T | Fast playback | | | |
| | | | | | | |
| Add ch | annel Reno | we channels Import channels | Auto-Scan Packet: 0 / 173 | 09 | | |
| | annel Reno Status | ve channels Import channels Name | AutoScan Packetz 0/173 Data Type | 19 Info | Setup | |
| | | Contraction of Section Section 199 | | | Setup Set di. | |
| Index | Status | Name | Data Type | Info | | |
| Index 0 | Status Unused | Name Setup Record | Data Type Computer Generated Data, Format 1 | Info Wideband Systems, Inc. DRS8500X model | Set di. | |
| Index 0 0 | Status Unused Unused | Name Setup Record Recording Events | Data Type Computer Generated Data, Format 1 Computer Generated Data, Format 2 | Info Wideband Systems, Inc. DRS8500X model No Data | Set ch. | |
| Index 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | Status Unused Unused Used | Name Setup Record Recording Events TDME01 | Data Type Computer Generated Data, Format 1 Computer Generated Data, Format 2 Time Data, Format 1 | Info Wideband Systems, Inc. DRS#S00X model fto Calo 10/18/2014 3:49:10 PH | Set ch. Set ch. Set ch. | |
| Index 0 0 1 2 | Status Unused Unused Used Unused | Name Setup Record Recording Events TINED 1 40 MSPS IRSG 8 | Data Type Computer Generated Data, Format 1 Computer Generated Data, Format 2 Time Data, Format 1 Analog Data Packets, Format 1 | Info Wideband Systems, Inc. DRS8500X model No Data 10/18/2014 3:49:10 PH No of AI Channels: 1 | Set dr. Set dr. Set dr. Set dr. | |
| Index 0 0 1 2 3 | Status Unused Unused Used Unused Unused | Name Setup Record Recording Events TDHE01 40 MSRS BIDG B Low Freq Test ch 2 | Data Type Computer Generated Data, Format 1 Computer Generated Data, Format 2 Time Data, Format 1 Analog Data Padets, Format 1 Analog Data Padets, Format 1 | Info Wideband Systems, Inc. DR58500X model Ioo Calo 30/18/2014 3:44:30 PH No of Al Channels: 1 No of Al Channels: 1 | Set d. Set d. Set d. Set d. Set d. Set d. | |
| Index 0 0 1 2 3 4 | Status Unused Used Used Unused Unused Unused | Name Setup Record Recording Events TINE01 40 MSIFS IRGS 8 Low Freq Test ch 2 Low Freq Test ch 3 | Data Type Computer Generated Data, Format 1 Computer Generated Data, Format 2 Time Data, Format 1 Analog Data Packets, Format 1 Analog Data Packets, Format 1 Analog Data Packets, Format 1 | Info Wideband Systems, Inc. DRS8500X model 100 Calo 10/16/2014 3:49:30 PH No of AI Channels: 1 No of AI Channels: 1 | Set dr. Set dr. Set dr. Set dr. Set dr. Set dr. | |

PCM ENCODER

DEWESoft[®] has the ability to acquire and synchronize a magnitude of different types of signals like analogue, GPS, IRIG time, 1553, video, ARINC 429 and many others. Once the data has been acquired by DEWESoft[®] it can be encoded into a PCM data stream real time. Thus creating the perfect solution for a flexible and scalable PCM Encoder system. This solution helps the user in a variety of ways from easily creating a PCM stream over trying out new sensor configurations to simulating a vehicle on the launch pad without tying up expensive flight hardware. This capability can also be used to correlate and record the stray analog signals from receiver AGC strengths to the communication links in the ground station.

| | (maine) | aler. | | Soft - Set | 10000 | | | | | | | | | No A/D ha | ruware | | |
|--------------|---------------------------------------|---------------|--------------|------------|----------|-------------------------------|-----------|--|-----------|------------|--------|---------|--------------------------|------------|----------------------------|-----|--|
| | coulsition | Analysis | Setup | files On | setup 1 | leasure | | | | | | | Se | bup Errors | 😜 Help | 3 | |
| Store | Save | Save as | File details | s Storing | Analog | Tarsus | 0 0 | | | | | | | | | | |
| Tarsus Card | 0 | | Dit sy | | Frame s | ync 👬 | Decor | • •Q | Frame pre | view Rints | | • (E | Peek/Poke) Iame Dump | | Computer tir 14:20:28.0 | | |
| Enable F | 'CM Qulpu | 0 Output | Type E | ncoder | | • | oply | | | | | | | | | | |
| Bit Sync Se | Atings | | | | | | | | | | | | | | | | |
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| Bits/Word | 16 | | | Start SFID | 0 | | | shedded Tim | | | | Remove | | | | | |
| Sync Bits | 32 | MSB bit order | | | | DWGhannel (Rotenborneter: W11 | | | | | | | | | | | |
| Sync Pattern | FEGE | 2840 | | | | | | DW/Channel (Motion Sensor; W13/B15/32) | | | | Paste | | | | | |
| | Sync | Sync | Word 1 | Word 2 | Word 3 | Word 4 | Word 5 | Word 6 | Word 7 | Word 8 | Word 9 | Word 10 | Word 11 | Word 12 | Word 13 | Wor | |
| Frame 0 | FE68 | 2940 | 0000 | QH | 5555 | FV | ET | ET | ET | ET | 5555 | OH | CH | \$\$\$\$ | CH | 1 0 | |
| Frame 1 | FE68 | 2040 | 0001 | OH. | 5555 | EV. | ET | LT. | ET | ET | 5555 | OH | CH | \$\$\$\$ | CH | 9 | |
| Frame 2 | FE68 | 2840 | 0002 | OH . | \$\$\$\$ | EV | ET | ET | ET | ET | 5555 | QI | CH | \$5555 | CH_ | 1 6 | |
| Frame 3 | FE6B | 2840 | 0003 | CH | 5555 | FV | ET | ET | ET | ET | 5555 | CH | CH | 5555 | CH | 1 | |
| Frame 4 | FE68 | 2840 | 0004 | CH | 5555 | FV | ET | ET | ET | ET | 5555 | CH | CH | 5555 | CH | 0 | |
| Frame S | FE6B | 2840 | 0005 | CH | 5555 | FV | ET | ET | ET | ET | 5555 | он | CH | 5555 | CH | 1 | |
| Frame 6 | FE68 | 2840 | 0006 | CH | 5555 | FV | ET | ET | ET | ET | 5555 | CH | CH | 5555 | CH | | |
| Frame 7 | FE68 | 2840 | 0007 | сн | 5555 | FV | -EI | E | ET | El | 5555 | CH | CH | 5555 | CH | | |
| | FE68 | 2840 | 0008 | CH | 5555 | FV | ET | ET | ET | ET | 5555 | CH | CH | 5555 | CH | | |
| Frame 8 | FE6B | 2840 | 0009 | CH_ | 5555 | FV | ET. | ET | ET | ET | 5555 | CH | CH | 5555 | CH_ | 1-9 | |
| Frame 8 | | | | | | | | | | | | | | | | | |





We make sure to deliver well-tested solutions to our customers

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